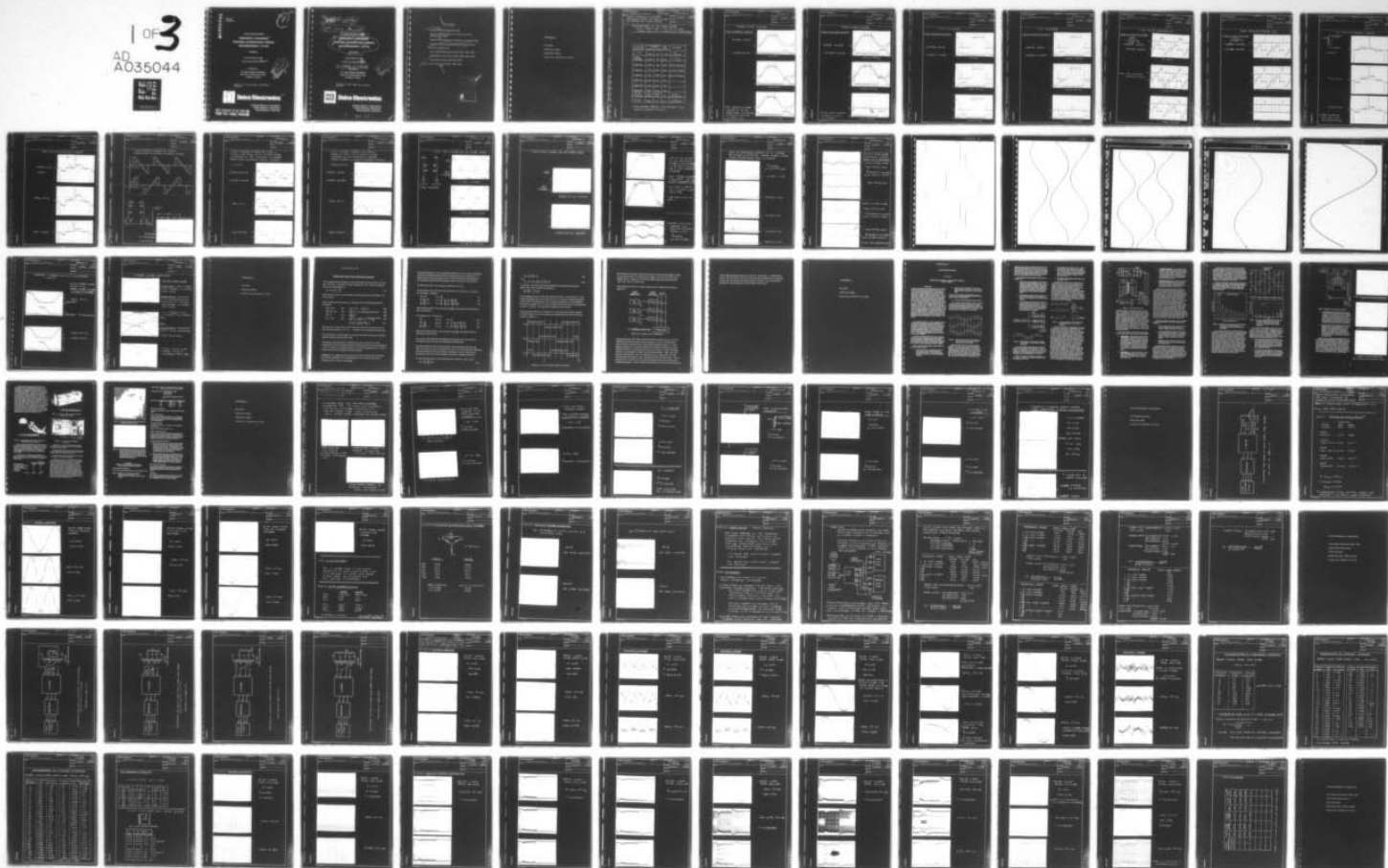


AD-A035 044

GENERAL MOTORS CORP GOLETA CALIF DELCO ELECTRONICS DIV F/6 9/5
FREQUENCY CONVERTER PORTABLE, ALTERNATING CURRENT MULTIFREQUENC--ETC(U)
MAY 74 T CORRY, BARRETT DAAK02-72-C-0210
R74-40-VOL-2 NL

UNCLASSIFIED

1 of 3
AD
A035044



ADA 035044

R74.40 ✓
MAY 1974

B.S.
①

FINAL TECHNICAL REPORT
FREQUENCY CONVERTER ✓
PORTABLE, ALTERNATING CURRENT
MULTIFREQUENCY, 10 KW

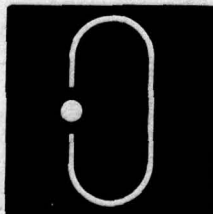
VOLUME II

Contract CDRL Item A002
Contract No. DAAK 02-72-0210 ✓

Submitted to
U.S. ARMY MOBILITY EQUIPMENT
Research and Development Center
Fort Belvoir, Virginia

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14 R74-40-Vol-2
11 MAY 74
12 242p.

10 T. Corry / Barrett

9 FINAL TECHNICAL REPORT.

6 **FREQUENCY CONVERTER
PORTABLE, ALTERNATING CURRENT
MULTIFREQUENCY, 10 KW.**

VOLUME II.

Contract CDRL Item A002

Contract No. DAAK 02-72-0210

15 DAAK 02-72-C-0210
Submitted to

U.S. ARMY MOBILITY EQUIPMENT
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Appendix A Waveforms, Item 0004

Appendix B Generalized Three-Phase Waveform
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Appendix C Development of Inverter Concept, Item 0001

Appendix D Thyristor and Diode Currents, Item 0004

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Test Results (Single Phase) Items 0001, 0003, 0004

Test Results (Three Phase) Items 0001, 0003, 0004

Test Results (Design Data) Item 0005

Parts Lists, Items 0001, 0003, 0004

ACQUISITION FOR	
NTIS	White Section <input checked="checked" type="checkbox"/>
A-C	Buff Section <input type="checkbox"/>
UNANNOUNCED	<input type="checkbox"/>
DISCONTINUED	<input type="checkbox"/>
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APPENDIX A

Item 0004

CDRL Item A0002

Modification P0006

Contract No. DAAK02-72-C-0210

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ITEM 0002

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TITLE

10KW FREQUENCY CONVERTER
ITEMS 0001, 0003 AND 0004 CONTRACT
NO. DAAK02-72-C-0010 REPORT

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MEASUREMENTS OF THYRISTOR VOLTAGES
400 HZ, THREE PHASE, 11KW, PF=0.8 LOAD
(THREE WIRE INPUT, NO TRANSISTORS, 125 MFD. 6T-N)

THYRISTOR DESIGNATION	MAX. VOLTAGE (VOLTS)		$\frac{dv}{dt}$ V/ μ SEC.	REMARKS
	FORWARD	REVERSE		
T ⁺ , T ⁻	320	40	150	WITH SUPPRESSORS
POWER CENTER	350	90	200	AT TOP OF WAVE
STEP #0	225	130	280	70V IN $\frac{1}{4}$ μ SEC.
STEP #1	150	200	200	100V IN $\frac{1}{2}$ μ SEC.
STEP #2	160	180	240	60V IN $\frac{1}{4}$ μ SEC.
STEP #3	140	210	100	
STEP #4	120	240	150	
R ₅ & L ₅	350	260	200	
PHASE SELECTOR	300 380 COM.	380 COM. 300	100	WITH SUPPRESSORS
T _C ⁺ , T _C ⁻	325	—	200	WITH SUPPRESSORS

(INPUT VOLTAGE = 295 VDC; OUTPUT VOLTAGE = 117 V RMS;
OUTPUT CURRENT = 31 A RMS)

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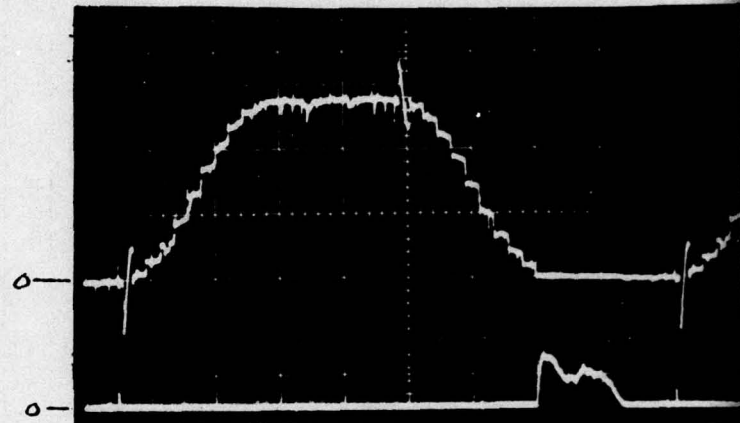
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POWER CENTER THYRISTORS

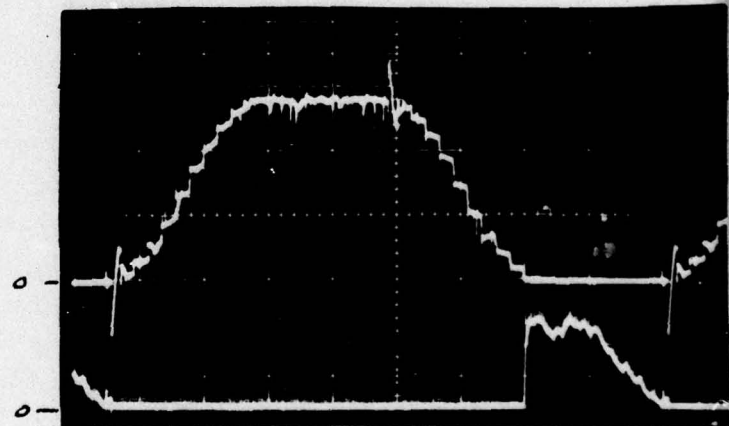
ANODE VOLTAGES & CURRENTS

VOLTAGE 100V/DIV

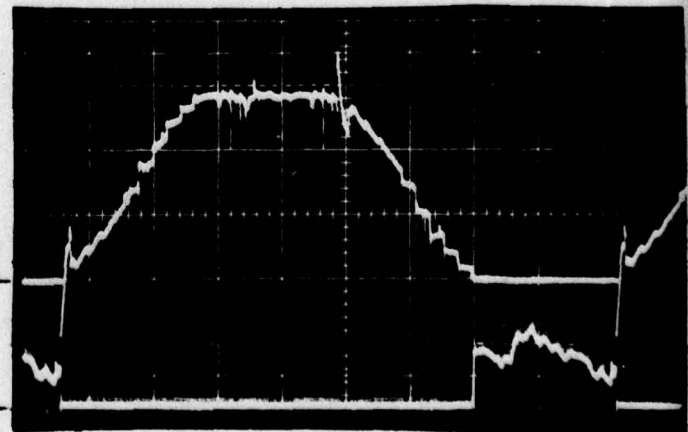
CURRENT 50A/DIV.



NO LOAD



11KW, PF=1.0



11KW, PF=0.8

(NOTE: FREQUENCY CONVERTER
OPERATING AT 400 HZ,
THREE PHASE, NO TRANSISTORS,
125 MFD 65-V FOR PHOTOS
ON PAGES 2-15)

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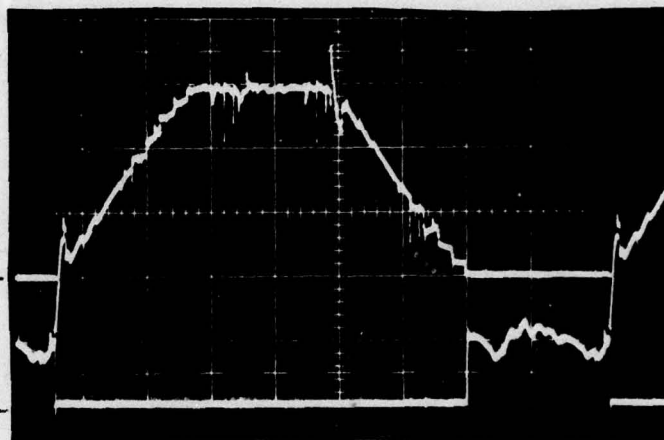
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POWER CENTER THYRISTORS

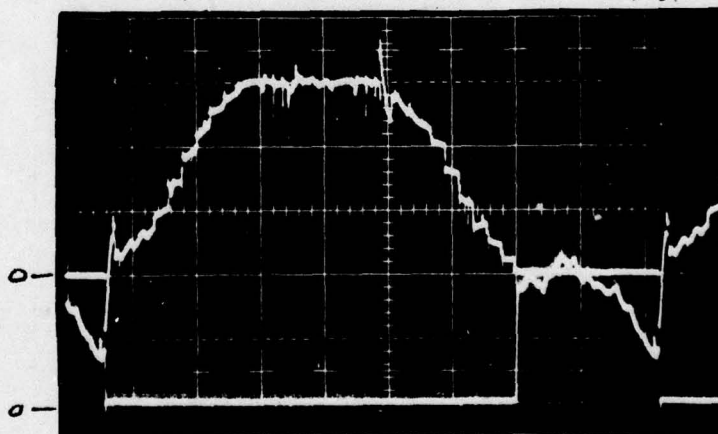
ANODE VOLTAGES & CURRENTS

VOLTAGE 100V/DIV.

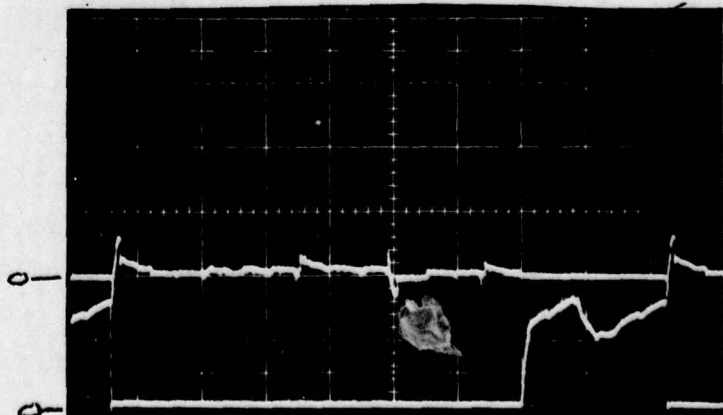
CURRENT 50A/DIV.



13.6 KW, PF=0.8



22 KW, PF=1.0



SHORT CIRCUIT

(SHORT CIRCUIT CURRENT
LIMITED TO 60A RMS.
V_{OC}=17.5VDC)

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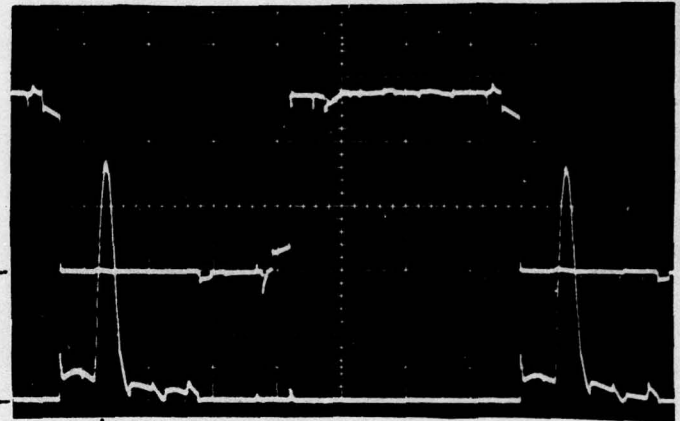
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T⁺, T⁻ THYRISTORS

ANODE VOLTAGES & CURRENTS

VOLTAGE 100V/DIV.

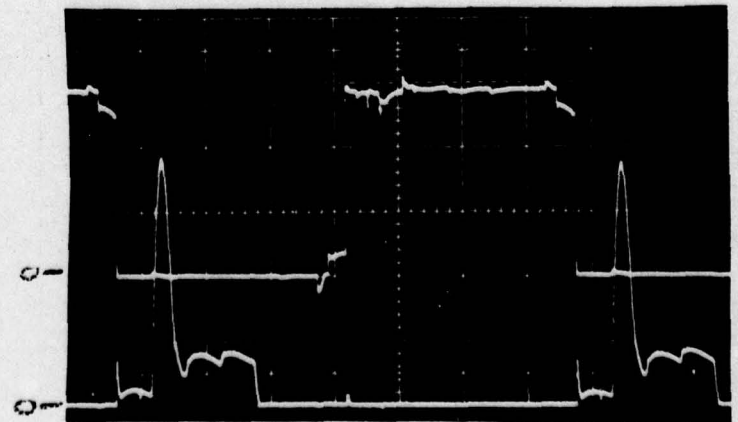
CURRENT 50A/DIV.



NO LOAD



11KW, PF=1.0



11KW, PF=0.8

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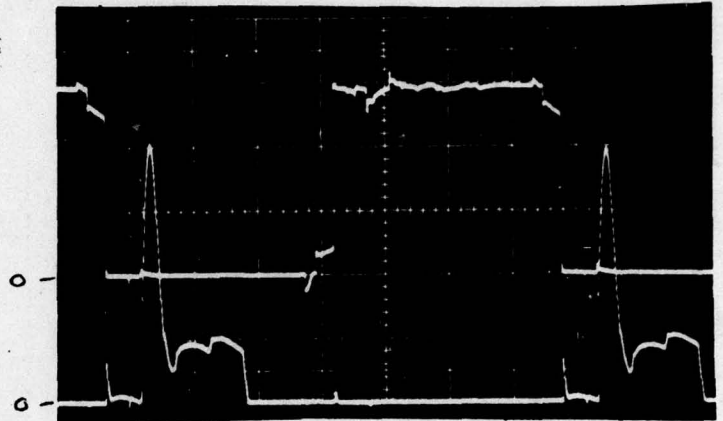
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T⁺, T⁻ THYRISTORS

ANODE VOLTAGES & CURRENTS

VOLTAGE 100V/DIV.

CURRENT 50A/DIV.



13.6 KW PF=0.8



22 KW, PF=1.0



SHORT CIRCUIT

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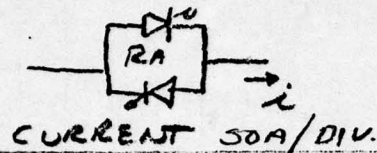
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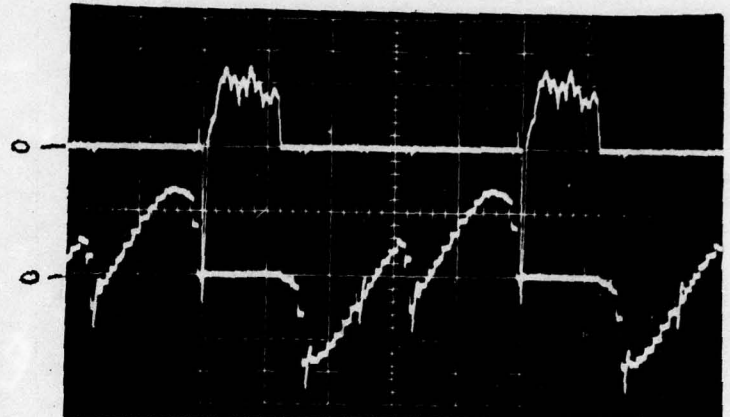
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PHASE SELECTOR THYRISTORS (12A)

ANODE CURRENTS & VOLTAGES

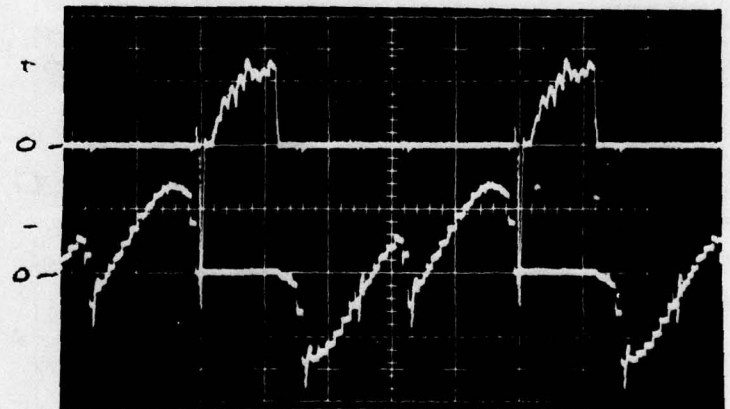


VOLTAGE 200V/DIV.

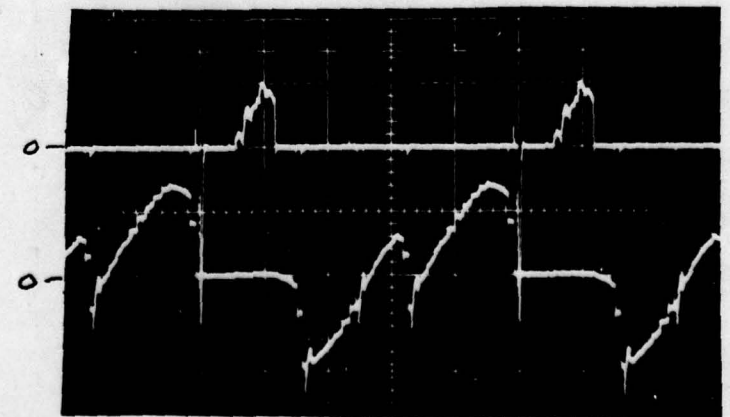


NO LOAD

(NOTE: NEG. COMMUTATION
CURRENT 125A. PEAK)



11 KW, PF = 1.0



11 KW, PF = 0.8

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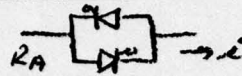
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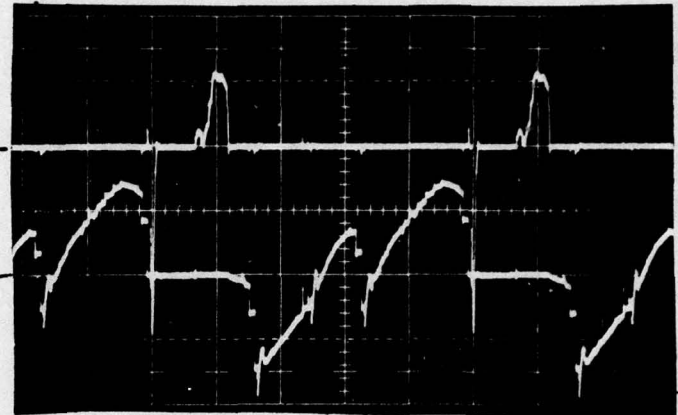
PHASE SELECTOR THYRISTORS (RA)

ANODE CURRENTS & VOLTAGES

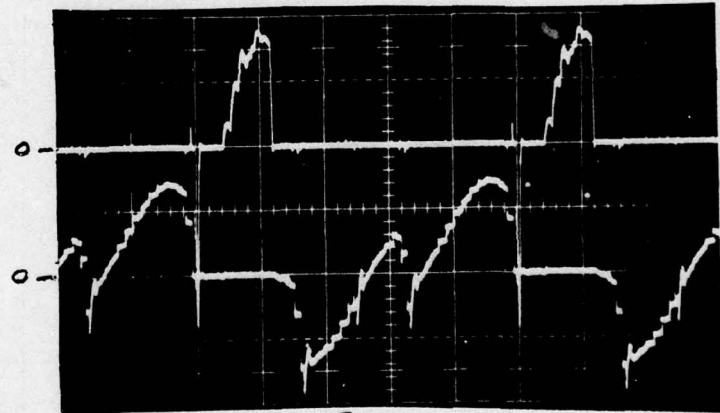


CURRENT 50A/DIV.

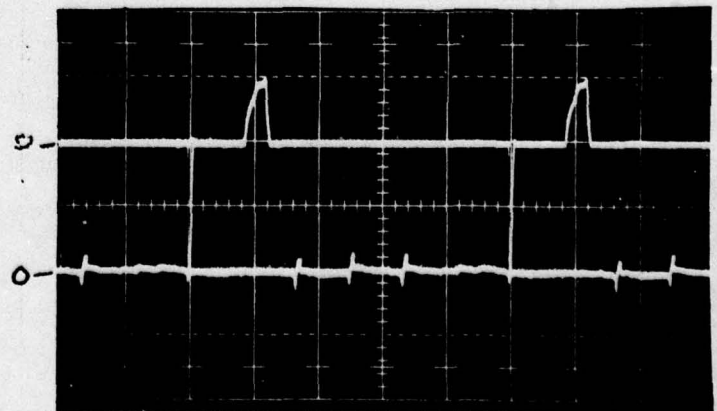
VOLTAGE 200V/DIV.



13.6 KW PF=0.8



22 KW, PF=1.0



SHORT CIRCUIT

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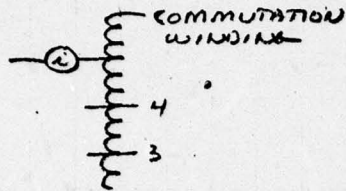
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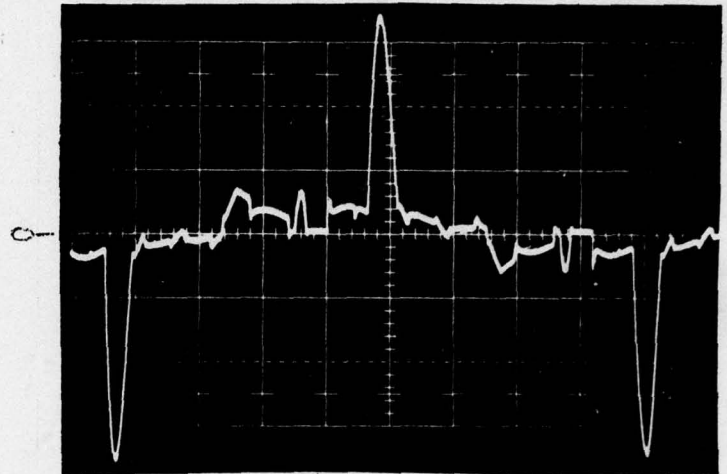
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STEP AUTO-TRANSFORMER CURRENT



NO LOAD

50A/DIV.



11KW, PF=1.0



11KW, PF=0.8



(NOTE: COMMUTATION PULSE GOES THRU TOP WINDING ONLY)

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STEP AUTO-TRANSFORMER CURRENT

13.6KW, PF=0.8

50A/DIV.



22KW, PF=1.0



SHORT CIRCUIT



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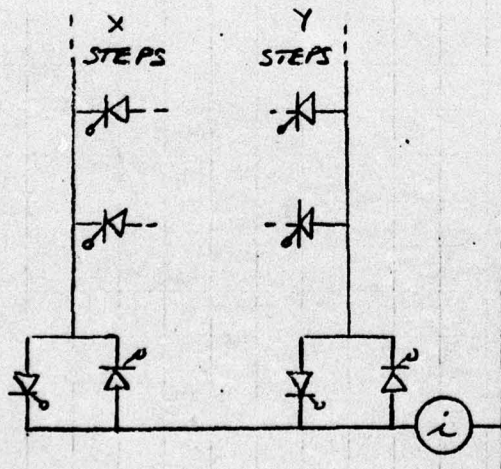
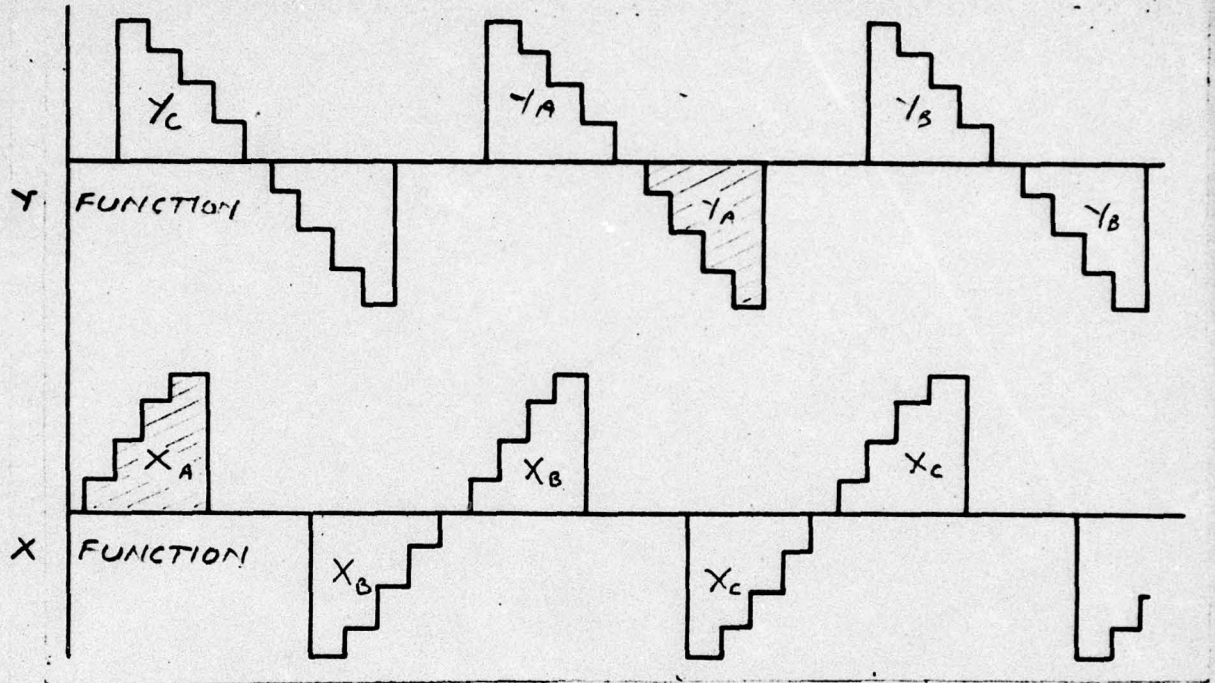
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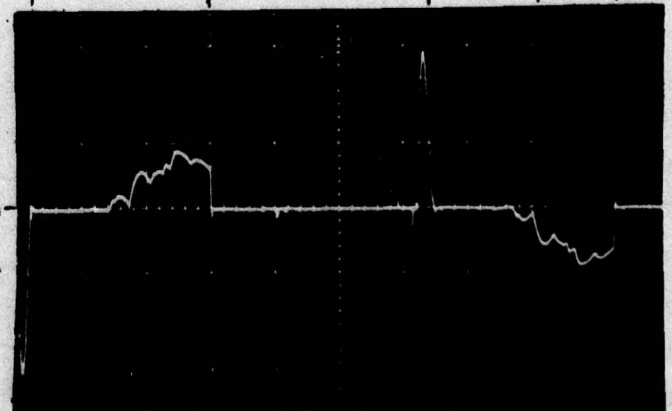
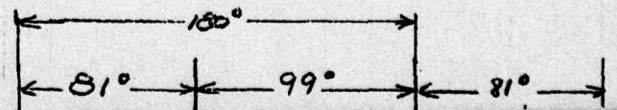
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X AND Y FUNCTION CURRENTS FOR PHASE A.
(POWER CENTER COMMUTATION CURRENTS INCLUDED)



PHASE A
LINE



50A/DIV

200μSEC/DIV

11KW, PF = 0.8

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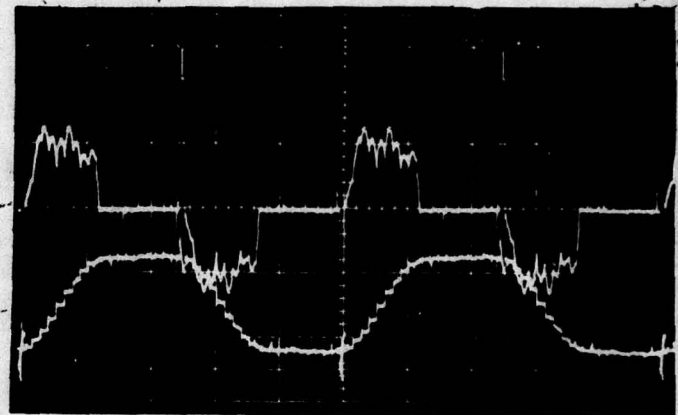
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X AND Y FUNCTION CURRENTS FOR PHASE A
SHOWN WITH BASIC LINE-TO-NEUTRAL VOLTAGE
WAVEFORM OF THE FREQUENCY CONVERTER.
(POWER CENTER COMMUTATION CURRENTS INCLUDED)

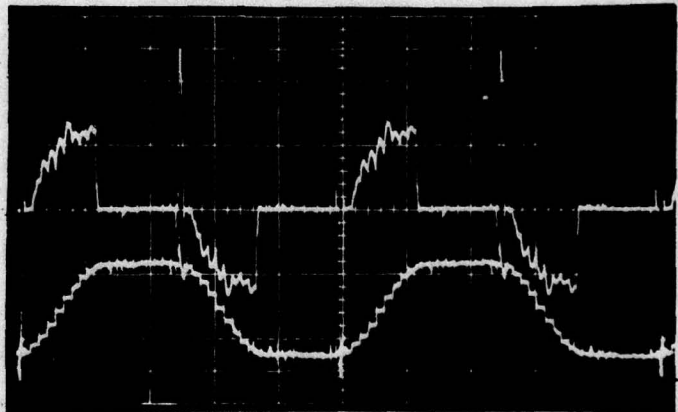
NO LOAD

CURRENT 50A/DIV.

VOLTAGE 200V/DIV.



11KW, PF=1.0



11KW, PF=0.8



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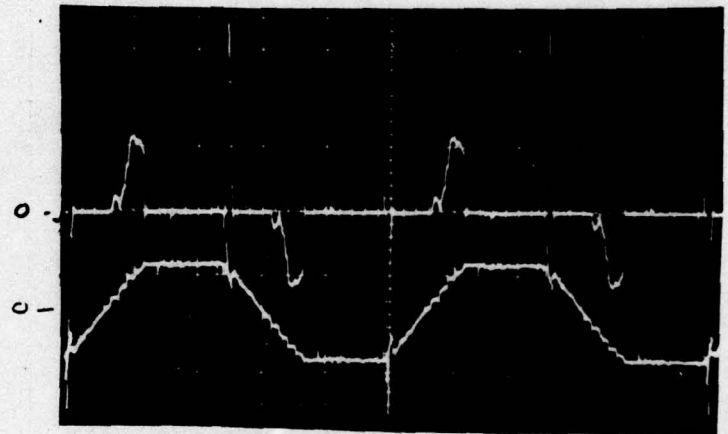
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X AND Y FUNCTION CURRENTS FOR PHASE A
SHOWN WITH BASIC LINE-TO-NEUTRAL VOLTAGE
WAVEFORM OF THE FREQUENCY CONVERTER.
(POWER CENTER COMMUTATION CURRENTS INCLUDED)

13.6 KW, PF = 0.8

CURRENT 50A/DIV.

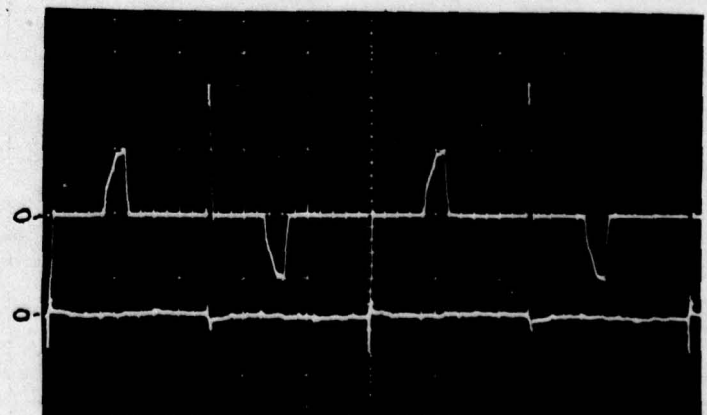
VOLTAGE 200V/DIV.



22 KW, PF = 1.0



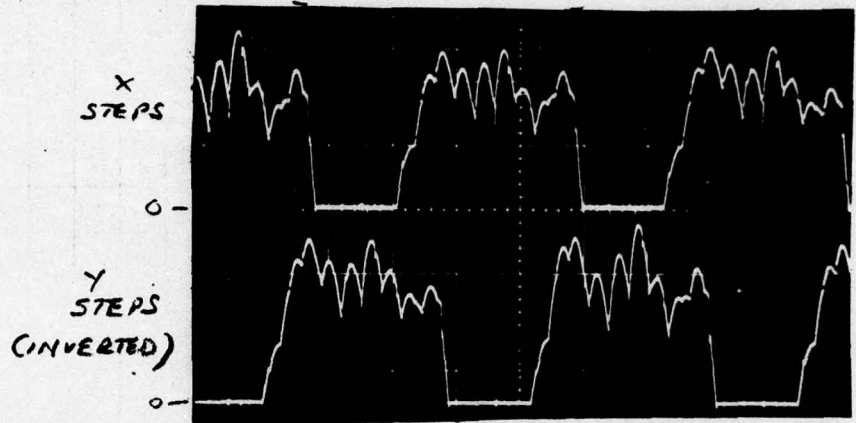
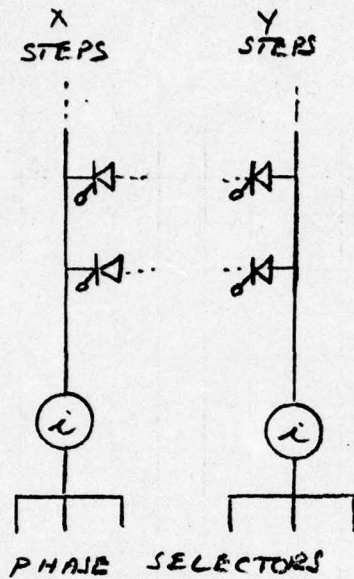
SHORT CIRCUIT



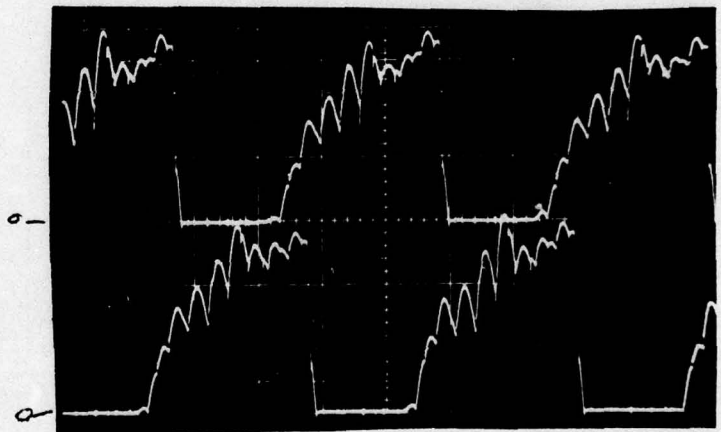
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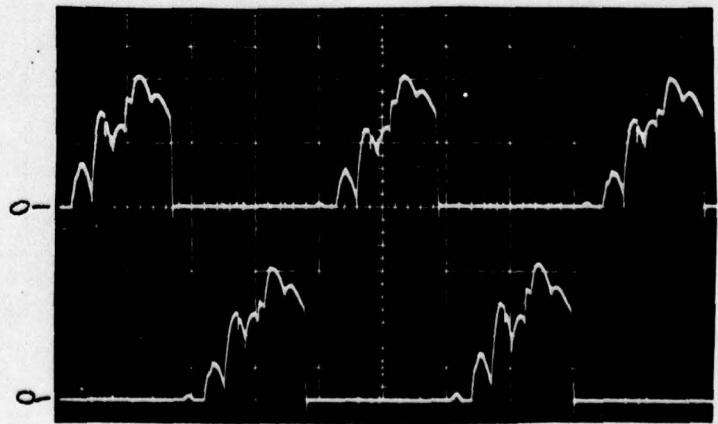
X AND Y STEP CURRENTS FOR ALL THREE PHASES



NO LOAD 25 A/DIV.



11KW, PF=1.0 25 A/DIV.



11KW, PF=0.8 25 A/DIV.

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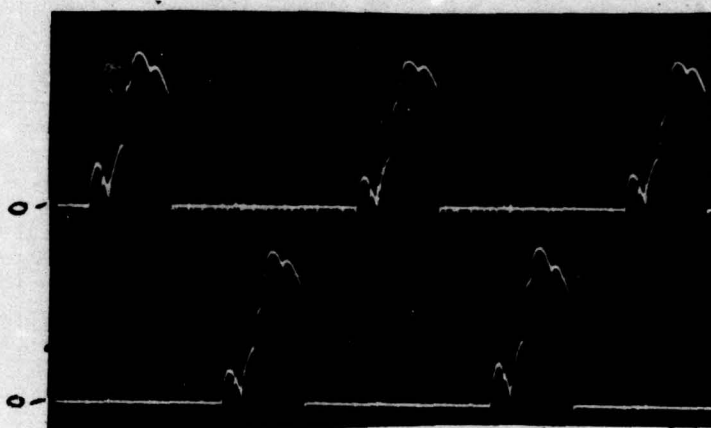
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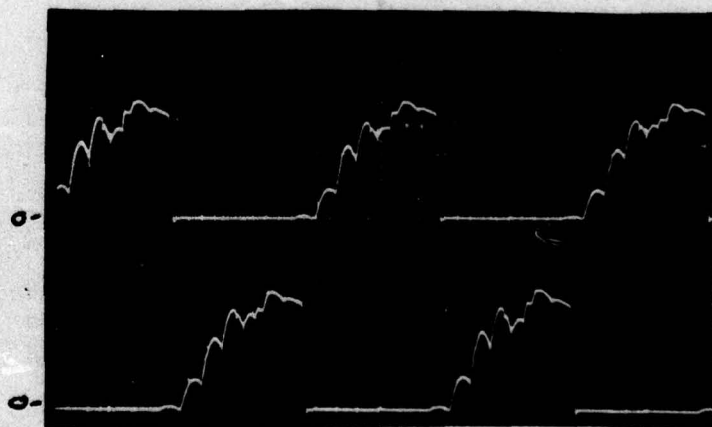
X AND Y STEP CURRENTS FOR ALL THREE PHASES

X
STEPS



Y
STEPS
(INVERTED)

13.6 KW, PF = 0.8 25 A/DIV.



22 KW, PF = 1.0 50 A/DIV.

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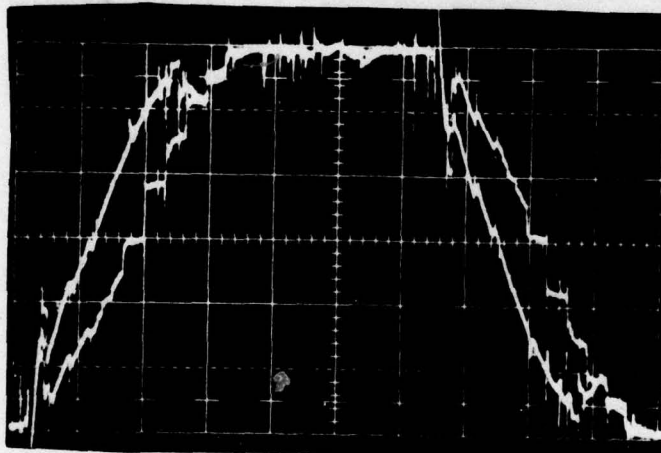
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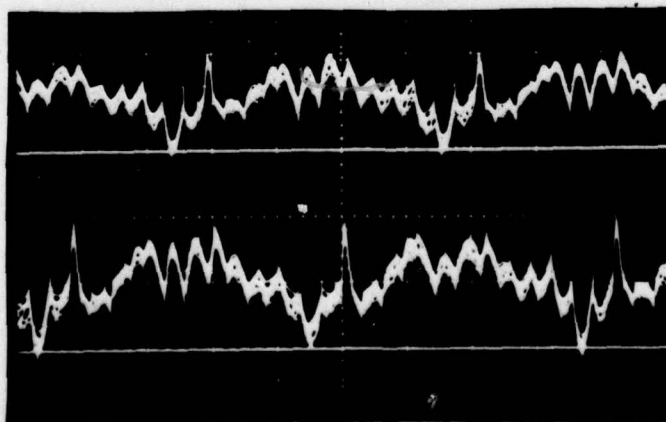
STUDY OF THE EFFECT
OF LOW LOAD POWER
FACTOR ON THE DISTORTION
ON THE BASIC L-T-N VOLT
AGE OF THE FREQUENCY
CONVERTER.

LEFT - NORMAL WAVEFORM
11 KW, 0.8 PF THD OF
OUTPUT WAVEFORM = 2.4%



LOAD = 11 KW + 5 KVAR
THD OF OUTPUT WAVE-
FORM = 8%

NOTE PHASE SHIFT TO
LEFT.



+ VOLTAGE INPUT LINE
CURRENTS FOR
11 KW, PF=0.8 LOAD
(60 MFD. L-T-L)

↓ 50A/DIV.

↔ 200 μSEC/DIV

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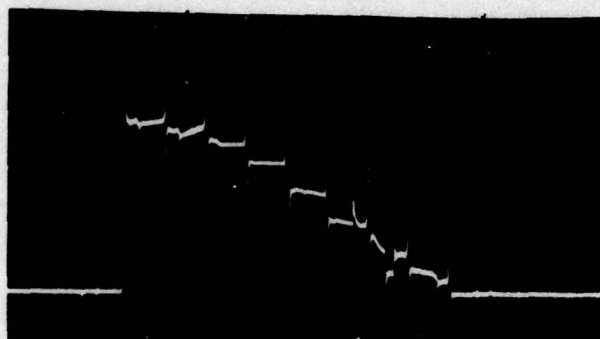
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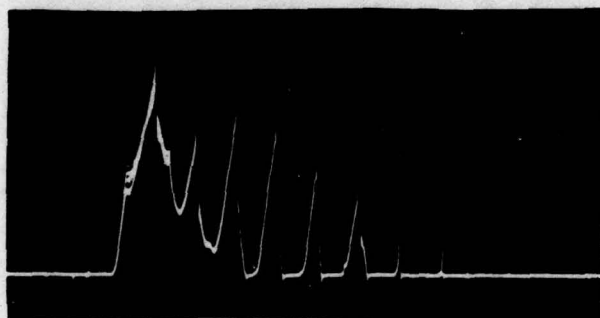
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STUDY OF TRANSISTOR CURRENT AS A FUNCTION
OF OUTPUT CAPACITANCE. 400HZ, THREE PHASE -
11KW, PF=0.8 LOAD HELD CONSTANT.

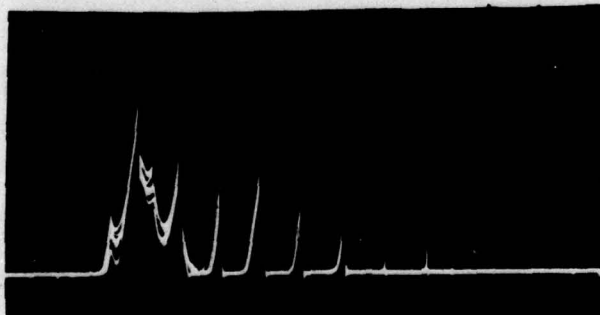


↑ 25 A / DIV.
← 100 μSEC / DIV.

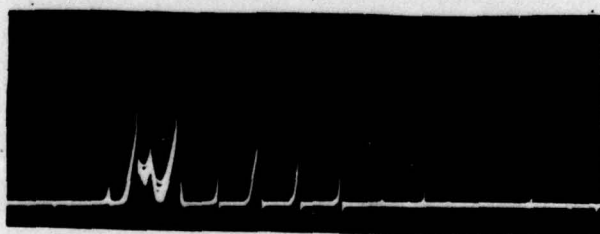
0 MFD. L-T-L



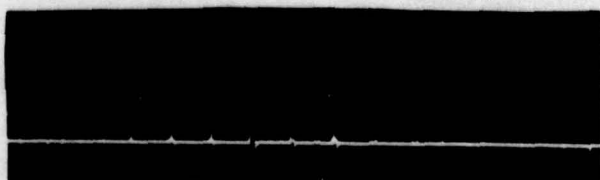
20 MFD. L-T-L



30 MFD. L-T-L



40 MFD. L-T-L



60 MFD. L-T-L

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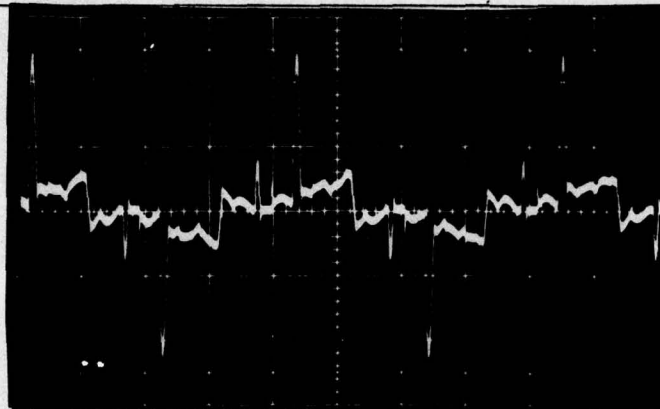
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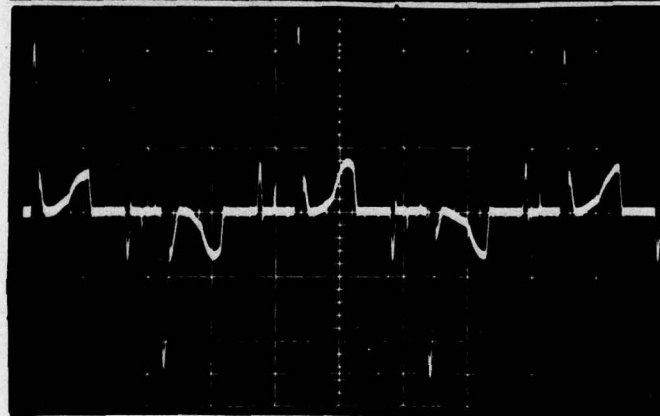


STUDY OF POWER CENTER
COMMUTATION CURRENTS
THRU T+, T- THYRISTORS

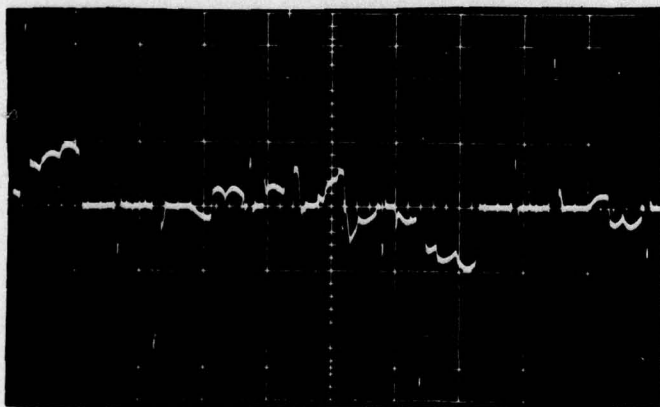
400 HZ, THREE PHASE

11 KW, PF=0.8 LOAD

↓ 100A/DIV. ↔ 200μSEC/DIV.
(BOOST VOLTAGE = ±25VDC)



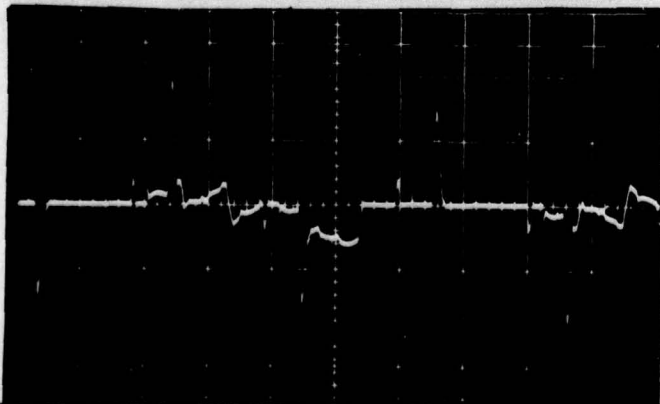
11 KW, PF=0.8 LOAD



400 HZ, SINGLE PHASE

11 KW, PF=0.8 LOAD

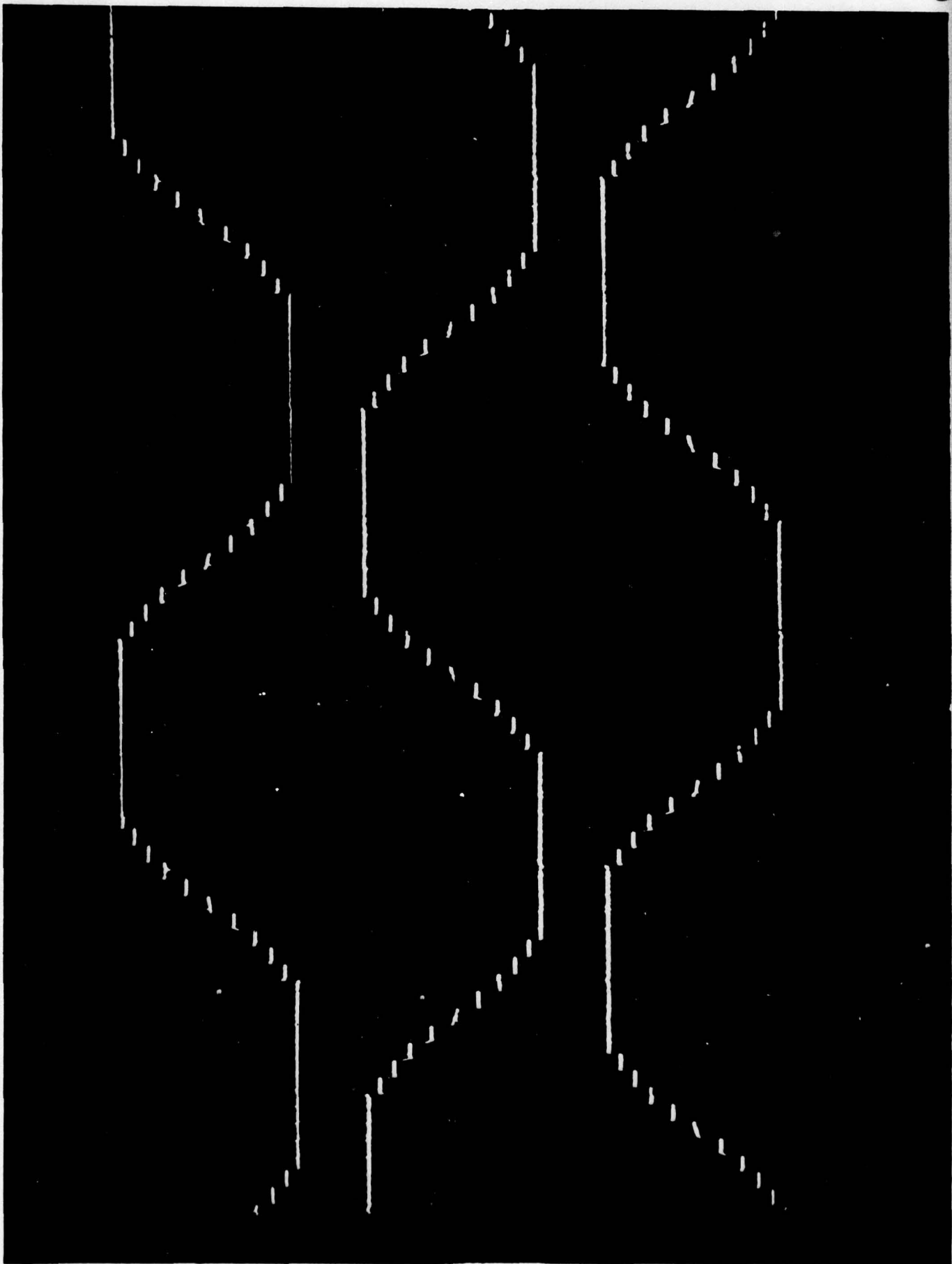
↓ 100A/DIV. ↔ 200μSEC/DIV.
(BOOST VOLTAGE = ±28VDC)



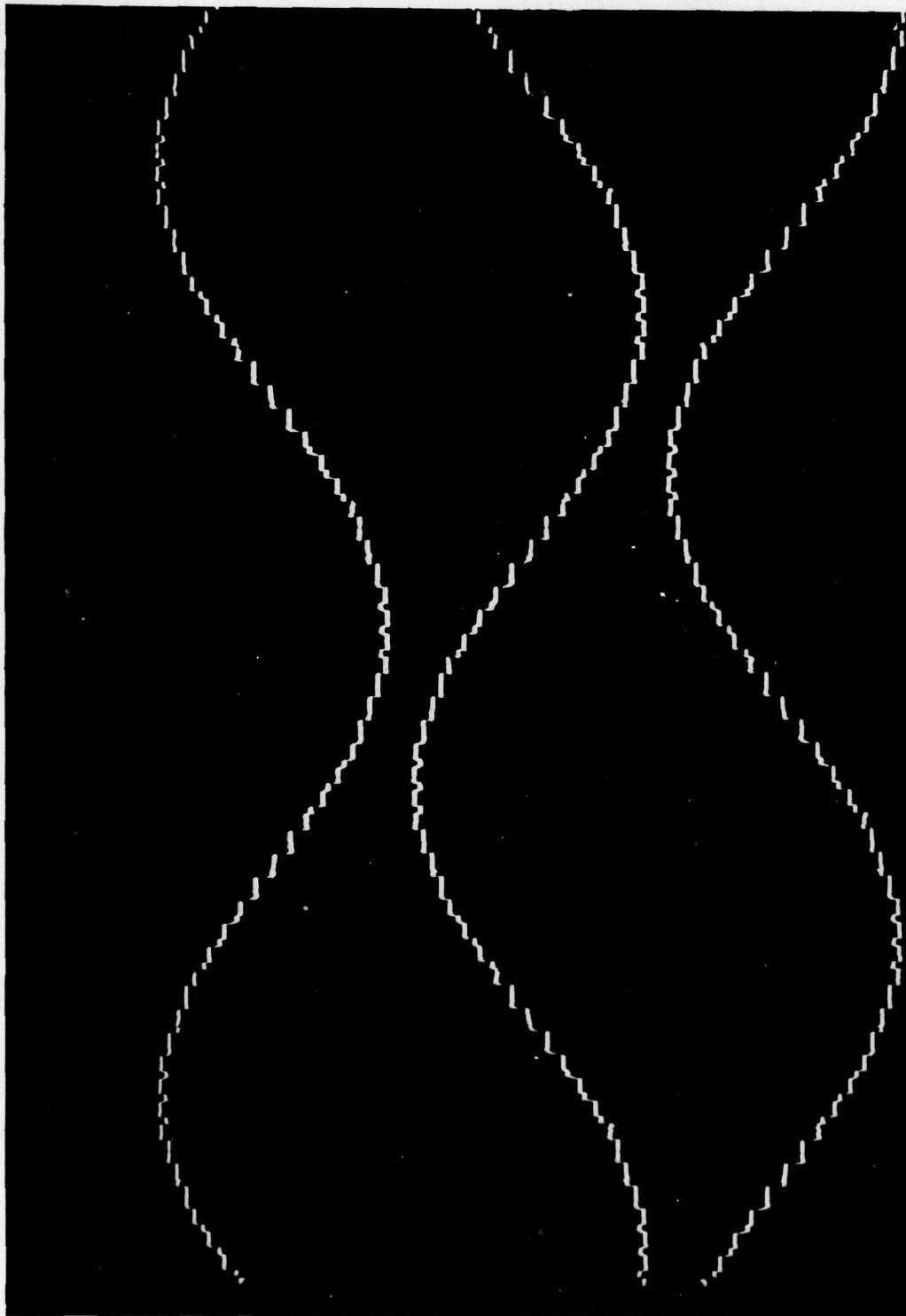
11 KW, PF=0.6 LOAD

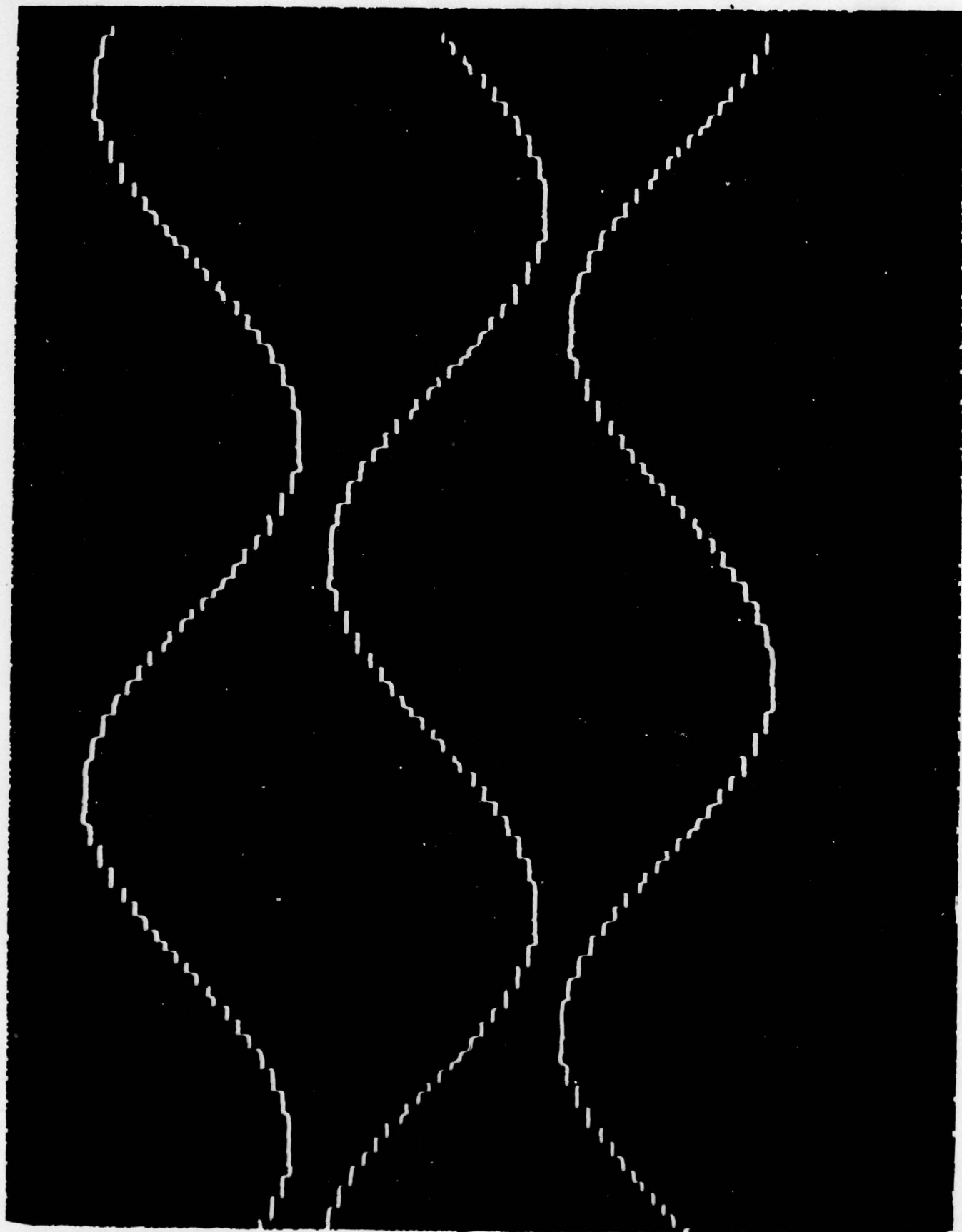
↓ 200A/DIV. ↔ 200μSEC/DIV.
(BOOST VOLTAGE = ±35VDC)

(NOTE: PEAK CURRENTS → 400A.)



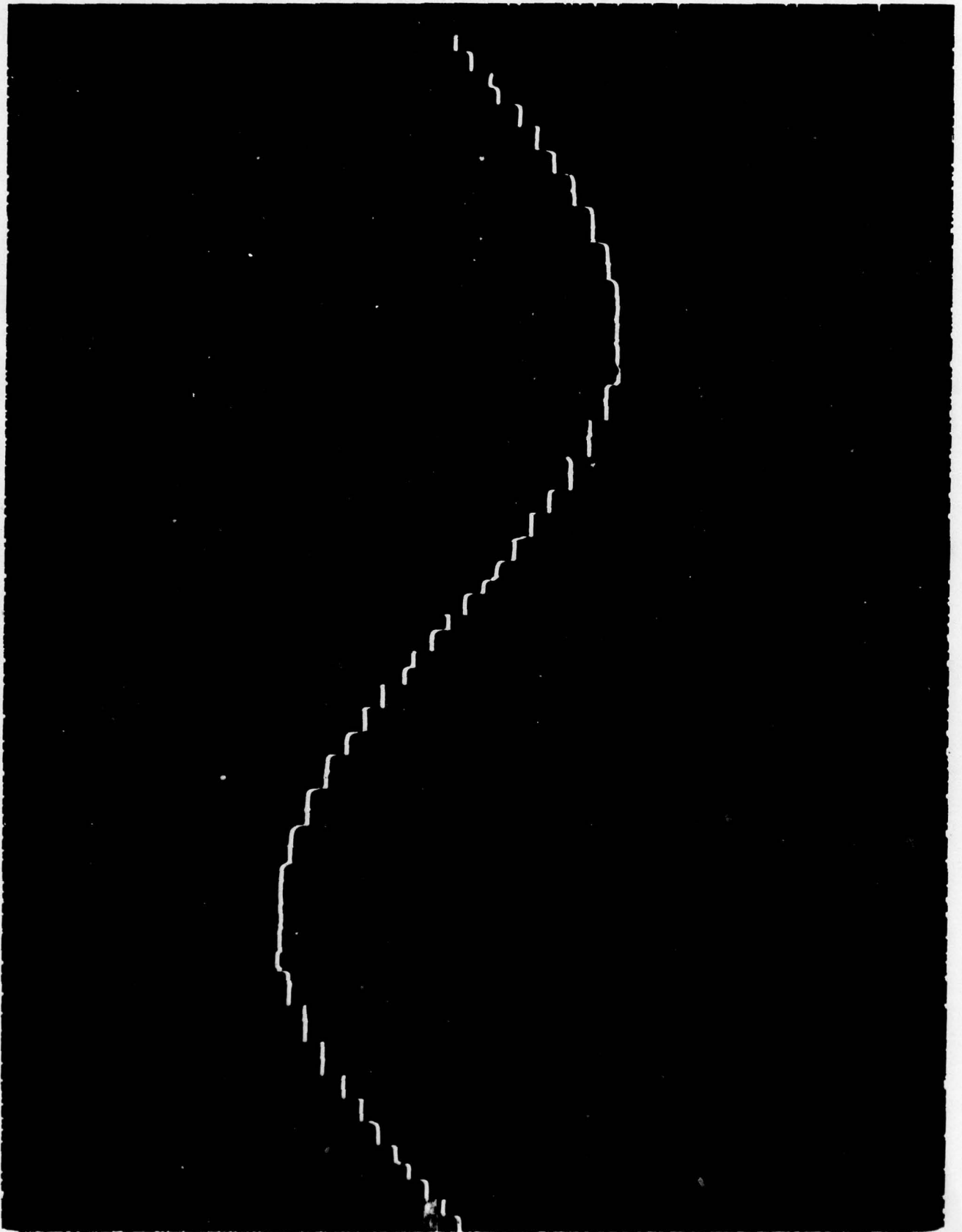
APPENDIX A





LINE-TO-LINE VOLTAGES

LINE-TO-LINE VOLTAGE





FILTERED L-T-N OUTPUT VOLTAGE THD = 0.95%

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CORRY

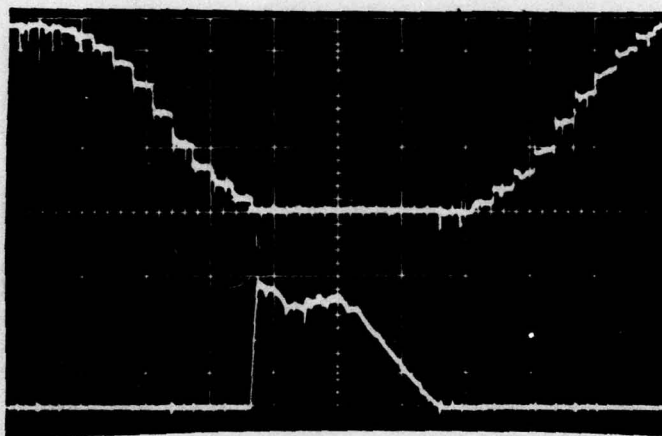
2/1/79

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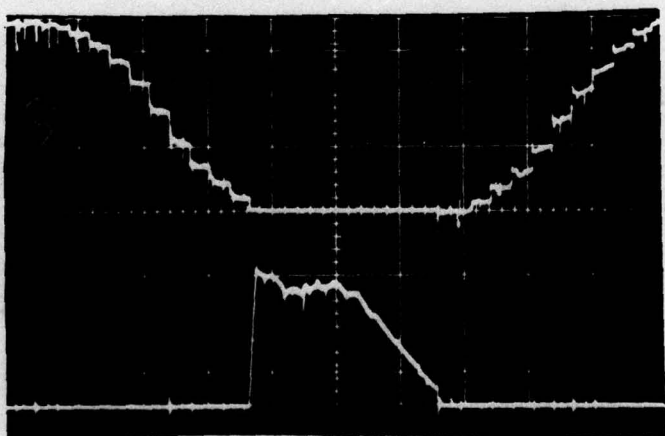
OPERATING INVERTER WITH NO P.C. COMMUTATION
CIRCUIT

400 HZ, THREE PHASE
60 MFD. L-T-L
POWER CENTER ANODE
VOLTAGE & CURRENT



+ 13KW, PF=1.0
- 100V/DIV

+ 50A/DIV
- 200μSEC/DIV



16KW, PF=1.0
(UPPER LIMIT)

DISTRIBUTION:

TITLE

PREPARED

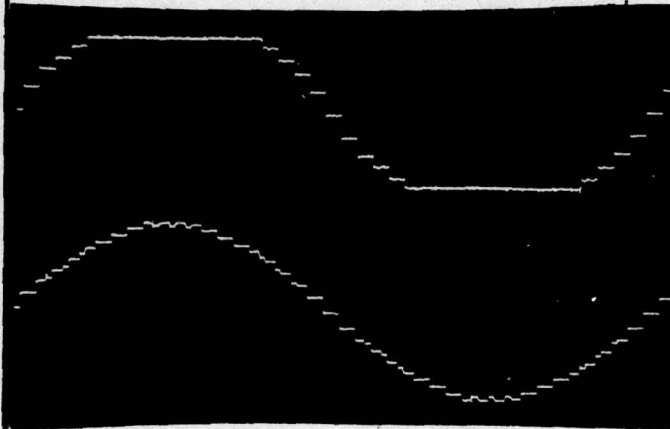
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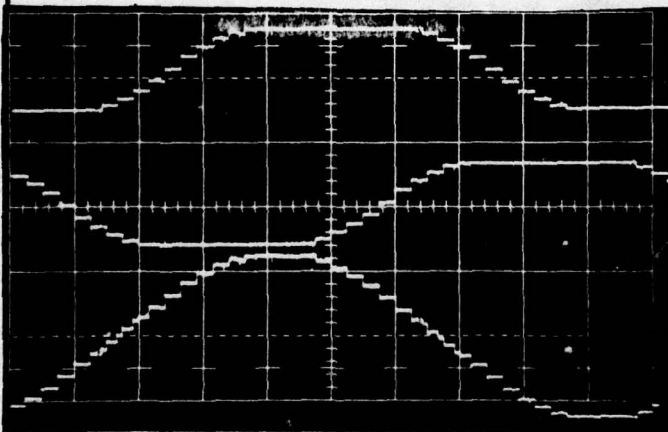
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INVERTER VOLTAGE WAVEFORMS

60 HZ, THREE PHASE

UPPER TRACE - BASIC INVERTER
L-T-N VOLTAGE INTO TRIPLIN
ATTENUATOR.

LOWER TRACE - RESULTANT
L-T-N VOLTAGE WAVEFORM
AT OUTPUT OF TRIPLIN
ATTENUATOR. UNFILTERED
THD = 4.2%

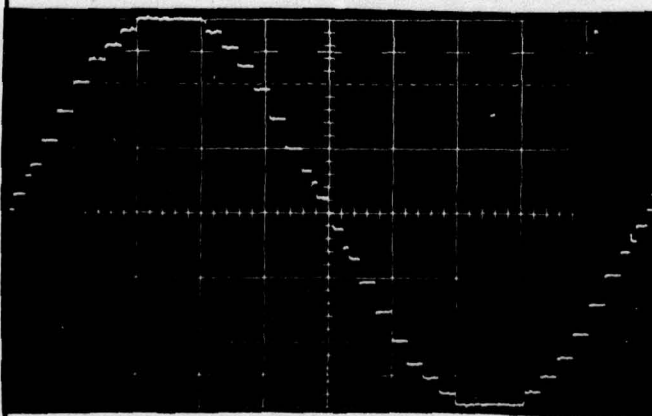


UPPER TRACES - BASIC
INVERTER L-T-N VOLTAGES
 V_{AN}

 V_{BN}

LOWER TRACE - RESULTANT
LINE-TO-LINE VOLTAGE V_{AB}

$$V_{AB} = V_{AN} + V_{NB}$$



BASIC LINE-TO-LINE
VOLTAGE PRIOR TO
FILTERING. THD = 4.2%

DISTRIBUTION:

APPENDIX B

Item 0001

CDRL Item A0002

Contract No. DAAK02-72-C-0210

APPENDIX B

GENERALIZED THREE-PHASE WAVEFORM GENERATOR

In three-phase electrical systems, the basic expression relating a line-to-line voltage, call it $g(t)$, to the line-to-neutral voltage, call it $f(t)$, (assume a balanced system for this discussion) is

$$g(t) = f(t) - f\left(t + \frac{T}{3}\right) \quad (1)$$

where the three line-to-neutral voltages are displaced 120 electrical degrees, one from the other.

In three-phase electrical systems, we generally have the following properties of $f(t)$ and $g(t)$

$$f(T+t) = f(t) \quad (2a) \quad g(T+t) = g(t) \quad (\text{periodic}) \quad (2b)$$

$$f\left(\frac{T}{2} + t\right) = -f(t) \quad (3a) \quad g\left(\frac{T}{2} + t\right) = -g(t) \quad (\text{half-period symmetry}) \quad (3b)$$

$$f(0) = 0 \quad (4a) \quad g\left(\frac{T}{12}\right) = 0 \quad (4b)$$

$$f(-t) = -f(t) \quad (5a) \quad g\left(\frac{T}{12} - t\right) = -g\left(\frac{T}{12} + t\right) \quad (\text{symmetric relative to } \frac{T}{12}) \quad (5b)$$

$$g(t) + g\left(t + \frac{T}{3}\right) + g\left(t + \frac{2T}{3}\right) = 0 \quad (6)$$

The 'neutral,' N , against which $f(t)$ is measured, need not be constant; it can contain any or all of the $3n$ th, $n=0, 1, 2, \dots$, harmonics of the fundamental frequency $\frac{1}{T}$.

It is important to note that (though it is not generally appreciated) property (5a) does not have to hold for property (5b) to hold.

The purpose of the following is to establish that: Given a waveform $g(t)$ with properties 2b-5b and 6, and given the task of creating $g(t)$ from some $f(t)$ via Equation 1, then, in addition to the usual properties of $f(t)$ cited in Equations 2a-5a, it can be shown that we have the following remarkable property.

Property 1: We can assign arbitrary values to any set of points of $f(t)$ with measure $\frac{T}{6}$ in the interval $\left(0, \frac{T}{2}\right)$, and the remaining points of $f(t)$ in this interval can be properly chosen to construct $g(t)$ exactly.

This unusual property of $f(t)$ has powerful implications, since it allows considerable latitude in mechanizing the construction of desired line-to-line waveforms in a 3-phase electrical system by means of line-to-neutral waveforms whose shapes are not necessarily constrained to be the same as that of the line-to-line waveforms.

To clarify this notion, let us consider a special form for $f(t)$.

Let the functions $a(t)$, $b(t)$, and $c(t)$ be arbitrary over the interval $0 \leq t < \frac{T}{6}$ and be zero elsewhere, and define

$$f(t) = a(t) \quad 0 \leq t < \frac{T}{6} \quad (7)$$

$$f\left(t + \frac{T}{6}\right) = b(t) \quad 0 \leq t < \frac{T}{6}, \frac{T}{6} \leq \left(t + \frac{T}{6}\right) < \frac{2T}{6} \quad (8)$$

$$f\left(t + \frac{2T}{6}\right) = c(t) \quad 0 \leq t < \frac{T}{6}, \frac{2T}{6} \leq \left(t + \frac{2T}{6}\right) < \frac{3T}{6} \quad (9)$$

These equations define $f(t)$ on the interval $\left(0, \frac{T}{2}\right)$, and properties (2a) and (3a) define it for all other t .

From Equation (1), it follows that

$$g(t) = a(t) - c(t) \quad 0 \leq t < \frac{T}{6} \quad (10)$$

$$g\left(t + \frac{T}{6}\right) = b(t) + a(t) \quad 0 \leq t < \frac{T}{6}, \frac{T}{6} \leq \left(t + \frac{T}{6}\right) < \frac{2T}{6} \quad (11)$$

$$g\left(t + \frac{2T}{6}\right) = c(t) + b(t) \quad 0 \leq t < \frac{T}{6}, \frac{2T}{6} \leq \left(t + \frac{2T}{6}\right) < \frac{3T}{6} \quad (12)$$

These three equations define $g(t)$ on the interval $\left(0, \frac{T}{2}\right)$, and properties (2b) and (3b) define it for all other t .

Now we ask, what constraints are imposed on the functions $a(t)$, $b(t)$, and $c(t)$ so that Equations (10)–(12) meet the requirements of Equation (6)?

By having constructed $f(t)$ in this special way, the resulting Equations (10)–(12) make it clear that any one of the functions $a(t)$, $b(t)$, or $c(t)$ can be specified arbitrarily, and the remaining two derived to construct $g(t)$ exactly. In fact, without such a specification, there are an infinite number of solutions to Equations (10)–(12).

To check this observation, let us assume that $b(t)$ is arbitrary. Then we have

$$a(t) = g\left(t + \frac{T}{6}\right) - b(t) \quad (13)$$

$$c(t) = g\left(t + \frac{T}{3}\right) - b(t) \quad (14)$$

and

$$a(t) - c(t) = g\left(t + \frac{T}{6}\right) - g\left(t + \frac{T}{3}\right) = g(t) \quad (15)$$

as it should. (Note that the last step depended upon the property expressed by Equation (6), where we make the substitution

$$g\left(t + \frac{2T}{3}\right) = -g\left(t + \frac{T}{6}\right).)$$

A more general statement of this observation is as follows: For each point t in the interval $\left(0, \frac{T}{6}\right)$ any one of the functions $a(t)$, $b(t)$, or $c(t)$ can be specified arbitrarily, and the other two assigned their value according to Equation (6). In this statement, the choice as to which of the functions is assigned an arbitrary value is itself arbitrary for each t in $\left(0, \frac{T}{6}\right)$. The generalized Property 1 follows directly.

Using the special definitions of Equations 7–9, and properties 2a and 3a, the line-to-neutral voltages for the three phases (each displaced from the other by 120°) are as shown in Figure C-1.

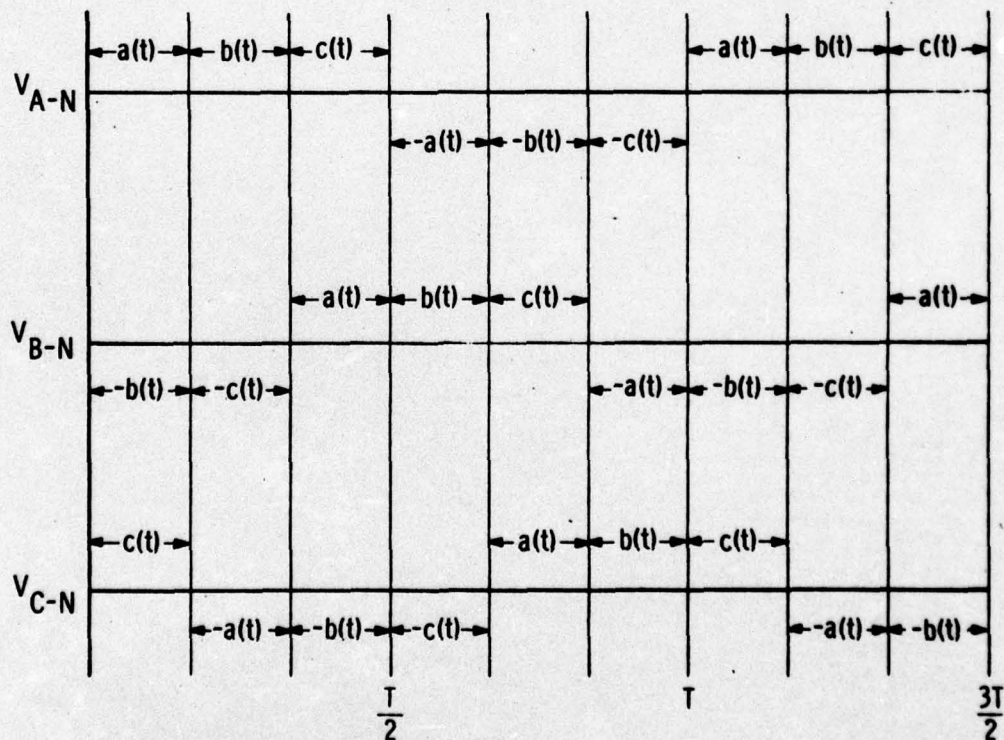


Figure C-1 Line to Neutral Voltage Construction

We note that at any instant of time, $a(t)$ and $c(t)$ are simultaneously negated (a minus sign in front of each) or not; when they are negated, $b(t)$ is not; when they are not negated, $b(t)$ is. Further, we note that the negation alternates between $b(t)$ and $[a(t), c(t)]$ every $\frac{T}{6}$ units of time.

These observations allow us to make a general circuit configuration as shown in Figure C-2.

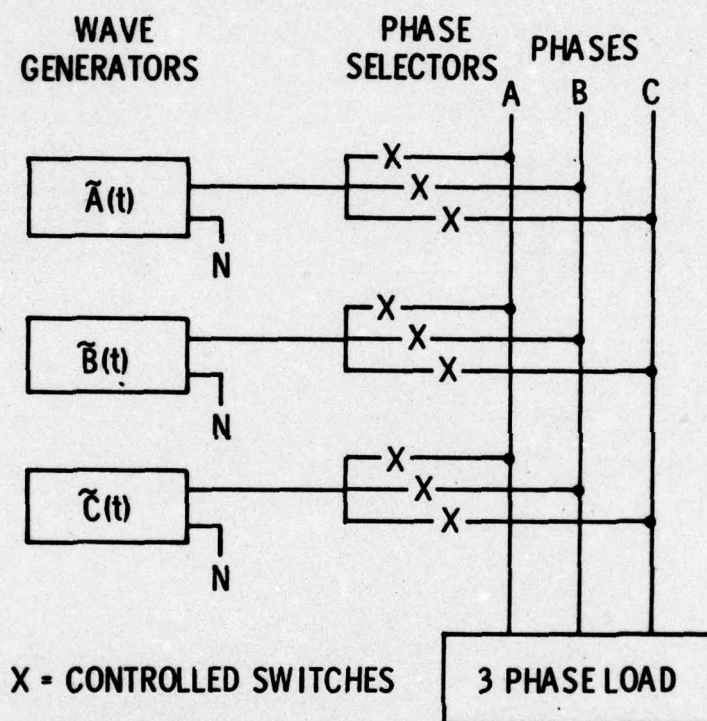


Figure C-2 General Circuit Configuration

The wave generators $\tilde{A}(t)$, $\tilde{B}(t)$, and $\tilde{C}(t)$ produce the functions $a(t)$, $b(t)$, and $c(t)$, respectively, and repeat these functions every $\frac{T}{6}$ units of time with alternating polarity (relative to the neutral N), synchronized according to Figure A-1. Each generator feeds its line-to-neutral voltage into each phase according to the timing indicated in Figure A-1 (each generator feeds only one phase at a time). The phase selection is accomplished by means of (the indicated) switches. (Note: $\tilde{A}(t)$ could generate $c(t)$ followed by $-a(t)$, and repeat this every $\frac{T}{3}$ units of time, and $\tilde{C}(t)$ could generate $c(t)$ followed by $-a(t)$, repeating this every $\frac{T}{3}$ units of time. This is the way we do it in practice, but for ease of discussion the former method is used throughout this paper.) Thus, any $g(t)$ with properties 2b-5b and 6 can be constructed

via the system specified by Figures A-1 and A-2. The period T is fixed directly by $g(t)$. The functions $a(t)$, $b(t)$, and $c(t)$ are selected according to $g(t)$ via Equations (10) and (12), and within the latitude provided by Property 1, they are selected to minimize (or some optimization of) the hardware requirements.

APPENDIX C

Item 0001

CDRL Item A0002

Contract No. DAAK02-72-C-0210

APPENDIX C

A NEW INVERTER CONCEPT

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Goleta, California

ABSTRACT

A rational method for using switching circuits to produce precision three-phase sine wave power from dc or ac power sources has been developed. A three-phase sine wave format is considered to be composed of voltage segments consisting of stepped waves and square waves generated by separate circuits and combined on a three-phase line to produce voltage waveforms with a total harmonic content of 4% prior to filtering. The stepped portions of the wave, called X and Y functions, are generated by a tapped autotransformer and appropriate switches. Only about 20% of the power is generated in the form of steps. A simple circuit that generates a square wave voltage called the "center" function, handles more than 80% of the inverter power. The inverter has the following characteristics: high input power factor (typically 0.9 to 0.95); low output impedance; can energize nonlinear loads without significant change in total harmonic content; and easy to parallel because of low energy storage in the output filter. The inverter has an efficiency of 88-93% and weighs about 120 lb (breadboard). Power rating is 10 kW with 200% overload capacity and output frequency is 60 or 400 Hz.

My invention, Patent No. 3,725,767 describes a new concept in the organization of power switching circuits to produce low harmonic content three-phase power. The first part of this paper reviews the conceptual thinking that led to the development of the inverter and describes the patented circuits. The second part summarizes the development effort on a 10 kW breadboard inverter built under contract DAAK 02-72-C-0210 for the U.S. Army Mobility Equipment Research and Development Center (MERDC).

Rather than starting with known inverter concepts such as square wave summing, pulse width modulators, or cycloconverters, and designing them to produce three-phase sine wave power, I started by reviewing the art, determining some basic characteristics preferred in an inverter, and commencing a waveform analysis.

Since it was desired to develop a light-weight unit, the initial criteria were to:

1. Have as much power as possible go from the power source to the load without passing through transformers. This criterion helps minimize iron and copper weight and enhances efficiency.

2. Utilize the power switches to create close approximations to sine waves. This criterion helps to minimize energy stored in the output filter.

For purposes of computer optimization and circuit analysis, this criterion established the frame of reference for waveform construction:

3. Construct the waveform from line-to-neutral.

These criteria and the computer waveform study led to the three-phase waveform design shown in Figure 1. Although these approximations of sine waves appear to be crude, the total harmonic content (THD) is only 6.4% and the THD of the resultant line-to-line voltage is 3.2% because the triplen harmonics are not present.

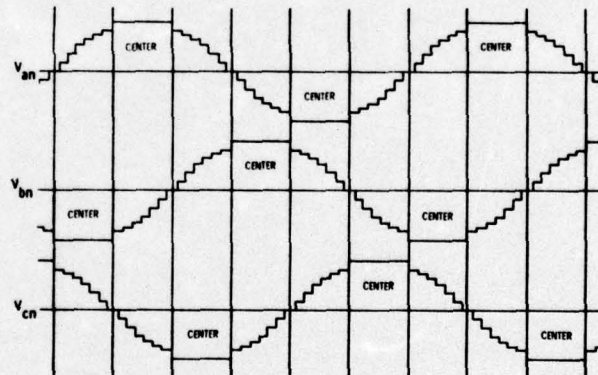


Figure 1. Three-phase Sine Wave Format Designed By The Author In Developing The New Approach to Inverter Design.

This three-phase format has several important properties. V_{an} , V_{bn} , and V_{cn} are line-to-neutral voltages. Each half-cycle consists of a 60° section of voltage steps rising toward the peak, a 60° section of constant amplitude voltage, and a 60° section of voltage steps descending to zero voltage. Each successive half-cycle is a reversed reproduction of the previous one. For any number (n) steps, the amplitude of each step, the angle of occurrence for each step, and the

amplitude of the center are selected to produce a minimum harmonic content line-t-line voltage. For any 60° interval the polarities of the center portions and the stepped portions of the waves are opposite. The polarities of the two stepped portions are the same, and the polarities of the center and steps rotate at a frequency three times the frequency of the line voltages.

The usefulness of these properties to the circuit designer are:

- The flat top center portions of the wave can be formed by a simple switching circuit. If the voltage is the proper magnitude, the switch can be connected directly to the three-phase line without the use of transformers. More than 60% of the wave energy is contained in the center portion and this energy can be handled at 99% efficiency with very little investment in weight.
- Transformers needed in step-forming circuits handle only 40% of the power and operate at three times the frequency of the inverter output voltages.
- A block diagram that organizes the inverter on the basis of the waveform design can be constructed as illustrated in Figure 2. For a 400 Hz three-phase inverter, the output voltages are composed of three 1200 Hz functions combined sequentially on the three-phase line to produce low harmonic voltages.

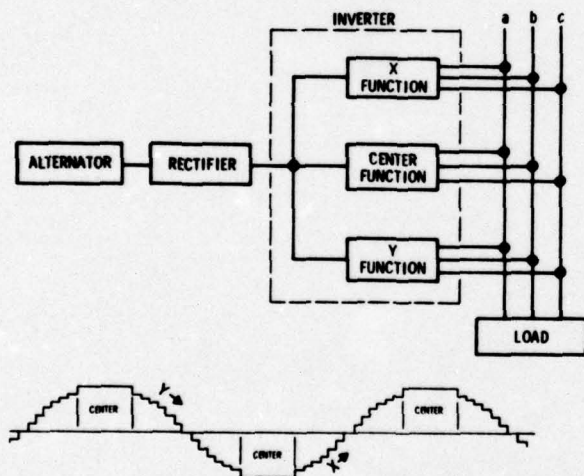


Figure 2. Block Diagram Of Alternator, Rectifier, And Inverter X, Y and "Center" Function Generators.

The circuit designer can then devise circuits that perform the functions of the inverter block; namely, create X, Y and "center" wave functions. This is a new freedom the designer does not have with other inverter approaches. The block functions can be selected and optimized relatively independently of each other.

There are several circuits that can generate X, Y and "center" functions; two additional guidelines help in defining these circuits:

4. At any instant of time there must be a path for current flow in either direction at a voltage level that preserves the sine wave approximation. In other words, never interrupt the load current. This guideline assures operation of the inverter with leading, lagging, or unity power factor loads.
5. Use double-bus switching techniques for changing voltage levels.

The three functions that must be produced by the blocks that compose the inverter are illustrated in Figure 3. Basic circuits for producing the X, Y and "center" functions are also defined. The X and Y functions are voltage steps of the same polarity with one set ascending while the other set descends. The steps can be produced by using a tapped autotransformer energized by a square wave that is three times the inverter output frequency. Two sets of switches are connected to the transformer taps; one set produces the X function, and the other the Y function. The "center" wave can be generated by a square wave switching circuit that operates in synchronism with the X, Y functions but that is 180° out of phase.

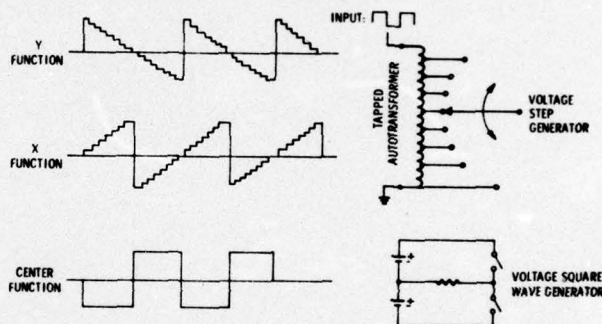


Figure 3. Waveform Definitions And Circuits That Can Generate the X, Y And "Center" Functions.

All that is needed now is to design these two simple circuits within the constraints of guidelines 4 and 5 and to connect the circuits to the inverter output lines. Figure 4 shows how the function generator circuits can be configured and connected to produce the new inverter concept. The circuit consists of a dc voltage source, "center", X and Y function circuits, and phase selectors. The "center" function generator is a three-phase thyristor bridge circuit. Most of the inverter power passes directly from the power source through the center switches and into the load; this is a very low impedance, high efficiency path. The major losses are the conduction losses of the thyristors. The remaining power is handled by the step autotransformer circuit. Step voltage power passes from the power source through a thyristor square wave switching circuit that energizes the autotransformer through the appropriate X and Y function voltage levels, and to the proper output line by means of the phase selectors. The impedance of this circuit consists of several semiconductors in series with the transformer leakage inductance. The total inverter circuit shown consists primarily of thyristors which require commutation to turn off. The currents of the step thyristors pass through transistors A or B. Commutation is accomplished by turning the

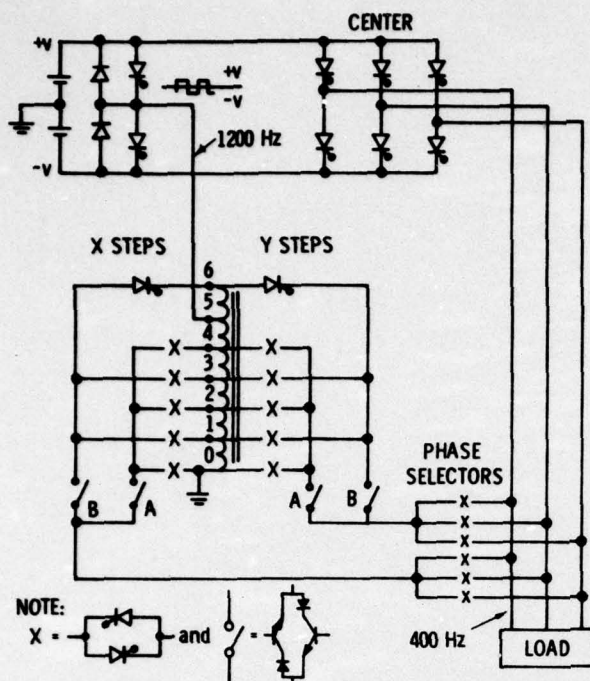


Figure 4. Basic Inverter Circuit

conducting transistor off and starving the series thyristor. Starvation commutation has proven to be efficient and very reliable, and all step changes are made using this process. The center function thyristors are commutated by the sixth level voltage on the autotransformer. Reverse commutation current is switched through the commutation thyristor, transistor B, the phasor, and finally the conducting "center" function thyristor. Capacitor commutation circuits are not used in this particular circuit configuration, but they can be used to turn off step or power center thyristors if that method is preferred. Transistors can be used throughout the inverter rather than thyristors. Triacs or thyristor-diode bridges can be substituted for the bilateral connected thyristors.

The circuit concept of Figure 4 has made possible inverter hardware with these important characteristics:

- **Light weight** - Output voltage waveforms with total harmonic content less than five percent at the output of the power switches can be constructed with low weight investment in filters and transformer iron and copper. In the following paragraphs it will be shown that more than 80 percent of the power can be made to flow through the "center" function generator of the inverter. Consequently, the autotransformer carries less than 20 percent of the inverter power.
- **High Efficiency** - More than 80 percent of the power passes through the basic inverter at close to 99 percent efficiency. The overall efficiency of the MERDC inverter peaks at about 92 percent.

- **Low Output Impedance** - This characteristic, combined with the low total harmonic content waveform, makes possible small output filters with low energy storage. The result is an inverter that is easy to parallel and that can energize nonlinear loads. In addition, inverter regulation is low. It has good transient response characteristics.
- **High Input Power Factor** - Since this inverter is the dc-link type, it requires rectifiers at the input for operation on ac power lines. Three-phase full wave rectifiers have power factors that range from 0.90 to 0.95.

This new inverter concept allows the designer to experiment with waveshape designs with only minor power circuit changes. Various waveshapes have different impacts on the inverter circuit performance and output filter design. An abstract description of the concepts that resulted in the basic inverter organization was developed shortly after my observations that X, Y and "center" functions can be used to create three-phase sine waves were made. Briefly, in a three-phase system, the line-to-line voltage defined $g(t)$, can be constructed exactly by a line-to-neutral voltage, defined $f(t)$, that has the same period as $g(t)$ and an interesting property: one-third of a half-cycle of $f(t)$ is specified arbitrarily, and the remaining two-thirds of the half-cycle are derived according to $g(t)$. The mathematical proof of this fact verifies that the center 60-degree portion of each half-cycle of the line-to-neutral wave can be set arbitrarily to a constant value, and then the left and right portions selected according to $g(t)$. The waveform design studies revealed that this procedure can produce a pure line-to-line sine wave and also result in a good approximation of a line-to-neutral sine wave.

With these insights, the designer can then establish additional guidelines that will help in building useful inverters:

6. Select waveforms that allow safe commutation times for thyristors in the step-former, "center" function and phase sector circuits.
7. Use energy handling components in preference to energy storage components. For example, when tradeoff permits, increase transformer weight or number of switches if it will lead to reductions in filter capacitor and inductor weight.
8. Design the voltage waveforms with harmonics distributed so as to minimize energy storage in the output filter.

In designing waveforms for this inverter, one has considerable control over the distribution and magnitudes of the harmonics. The designer can minimize line-to-line or line-to-neutral voltage total harmonic distortion within various constraints such as the number of voltage levels, the width of the "center" function, the widths of the voltage steps, or multiple constraints such as number of steps and minimizing selected harmonics. Each optimization exercise influences the inverter switching circuits and output filter.

An analysis of waveforms was made in which the computer was asked to construct line-to-neutral voltages that produced line-to-line voltages with minimum harmonic content as a function of the number of voltage taps on the inverter autotransformer. The following sets of conditions were used: (a) center width equal to 60° with unconstrained step widths, (b) unconstrained center and step widths, (c) unconstrained center and equal step widths, and (d) equal step widths with center width constrained to be a multiple of a step width.

Figure 5 shows total harmonic content of the line-to-line voltages as a function of autotransformer steps for the conditions defined in (b). The chart shows that the inverter can produce unfiltered output voltages with total harmonic content of 2.5 percent by using seven transformer steps.

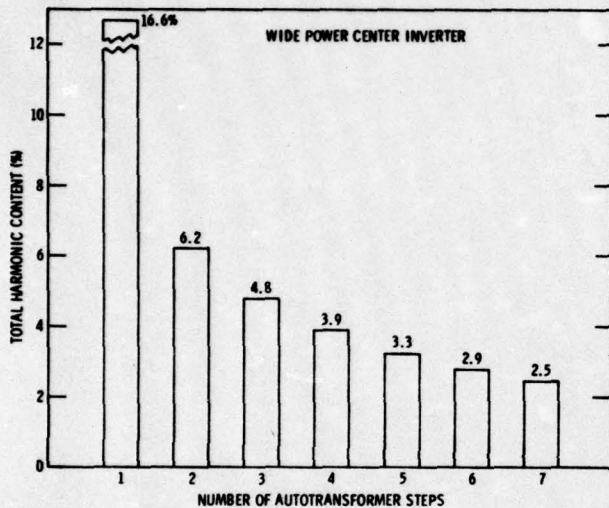


Figure 5. Total Harmonic Content Versus The Number Of Taps On The Step Transformer. No Constraints Were Placed On Center and Step Widths.

The waveform selected for the MERDC inverter was defined on the basis of constraints in (d) and is illustrated in Figure 6. This waveform has these desirable properties. The flat top portion of the wave is 99° wide and allows the "center" function circuit to deliver more than 80 percent of the power. The total harmonic content of the line-to-line wave is 4.2 percent; the MERDC requirement defines a maximum THD of five percent. Equal step widths with the center 11 times the width of a step allows relatively simple logic circuitry for triggering power switches. All harmonics greater than one percent are clustered around the 41st harmonic (Figure 7). This property helps in the output filter design. The undesirable property of this wave is that it contains 16.02 percent third harmonic. However, this harmonic and all multiples of the third can be removed easily by a triplen attenuator that also functions to filter noise.

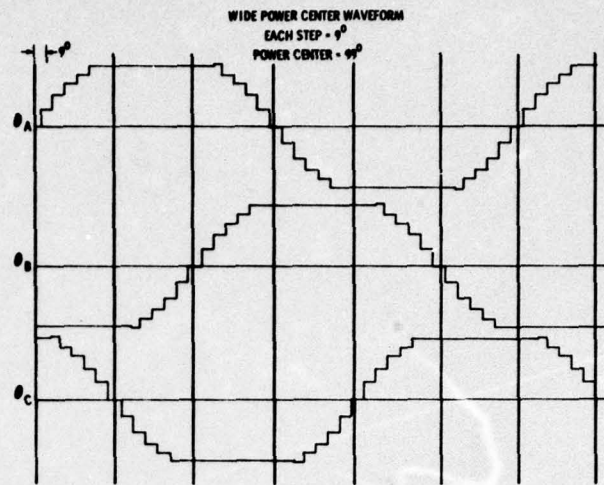


Figure 6. Waveform Selected For The MERDC Inverter

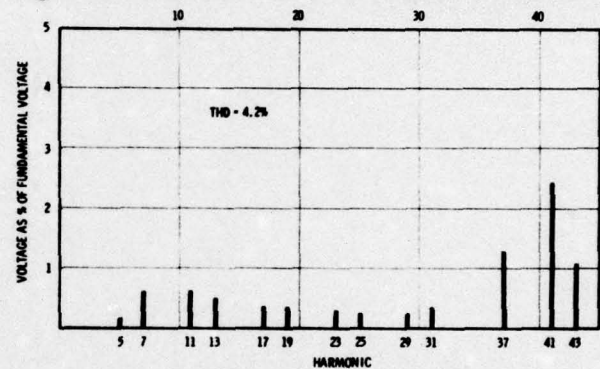


Figure 7. Harmonic Content Distribution Of The Line-To-Neutral Voltage Has 16.02% Third Harmonic, But This And Other Triplen Voltages Are Eliminated In The Output Attenuator.

The objective of the MERDC project was to develop a 60 Hz - 400 Hz 10 kW inverter to operate from an Army turbo-alternator system. A simplified schematic diagram of the inverter designed for MERDC is given in Figure 8; elements of the circuit not pertinent to this discussion are not shown. Differences between the MERDC circuit (Figure 8) and the basic inverter (Figure 4) starting from the top and working down are:

- A commutation circuit for the thyristors that drive the step autotransformer has been added. The maximum current that this circuit must commute is about one ampere, the magnetizing current of the transformer. Load current does not flow through the transformer during this commutation interval.
- A capacitor has been added in series with the top level of the autotransformer. This addition allows the "center" function circuit commutation current to bypass the step commutation transistors, and increases the current capability of the inverter.

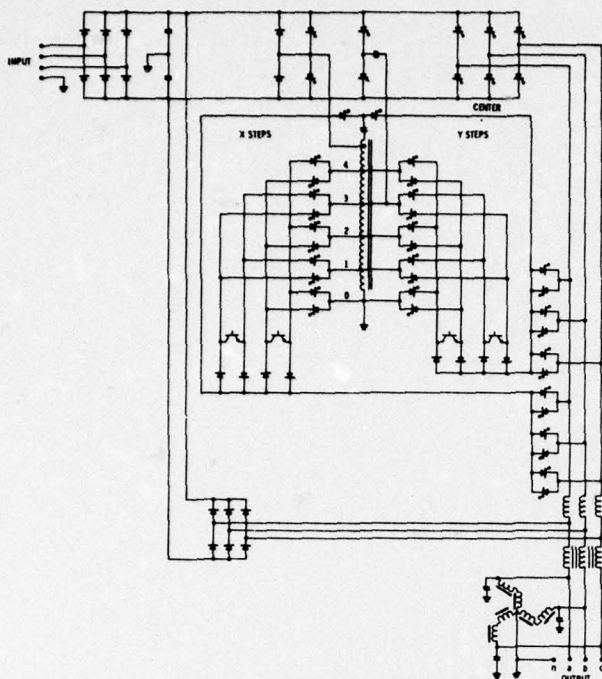


Figure 8. MERDC Inverter Schematic Diagram

- A diode bridge has been added (on lower left of the schematic) to enable the inverter to operate at any power factor from unity to zero, leading or lagging. For power factors greater than 0.76, reactive energy circulates from one phase to another through the autotransformer. For power factors below 0.76, the reactive current also returns through the diode bridge which is in parallel with the "center" function circuit thyristors.
- Near the output of the circuit are shown a triplen attenuator and a zig-zag transformer. The attenuator offers a high impedance to the third harmonic. The zig-zag autotransformer is designed to carry the line-to-neutral load unbalance, and maintains phase voltage balance for unbalanced loads. Line-to-line loads do not require the actions of the attenuator or the zig-zag transformer.

Figure 9 shows oscilloscope photographs of the unfiltered power voltages generated by the MERDC inverter. The three-phase composite voltages as generated by the X, Y and "center" function circuits are shown in Figure 9a. This waveform is virtually identical to that designed by the computer optimization program. The center is 99° wide and each step is 9° wide. Resultant line-to-neutral and line-to-line output voltages are shown in Figures 9b and 9c. The total harmonic content of these waveforms is 4.2 percent. Individual harmonic magnitudes are very close to the magnitude listed in the computed design.

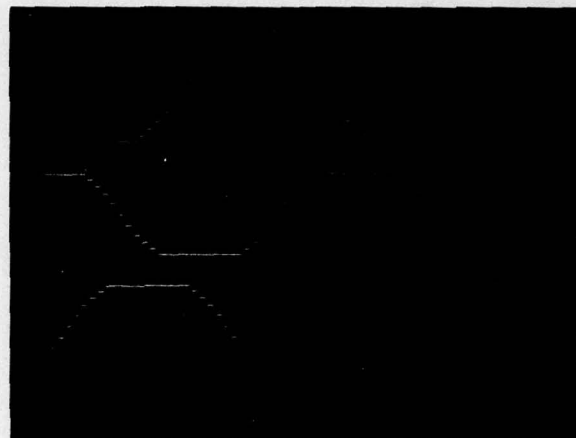


Figure 9a. Three-phase Composite Voltages Generated By The X, Y, And "Center" Function Circuits.

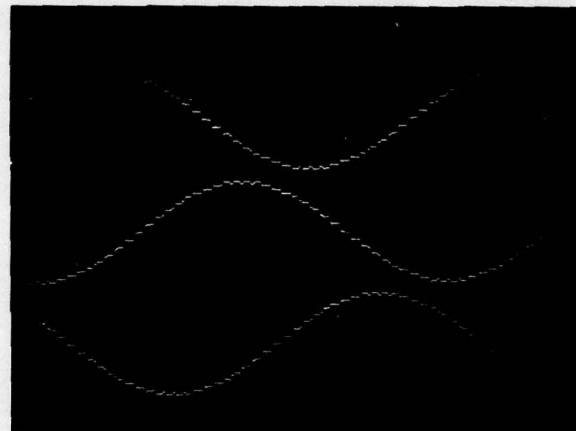


Figure 9b. Line-To-Neutral Output Voltages

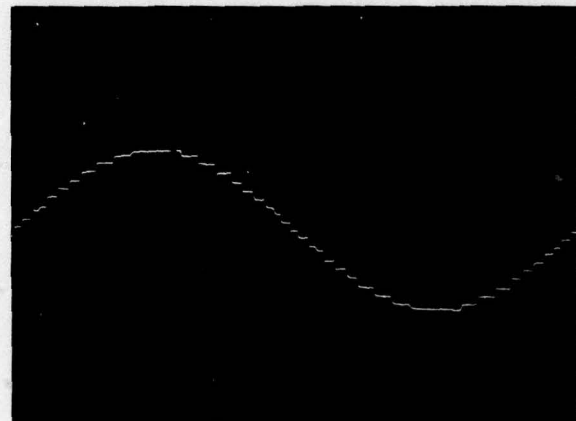


Figure 9c. Line-To-Line Output Voltage

Figure 9. MERDC Inverter Unfiltered Power Voltages

Because of the ultimate requirements for light weight and low cost for production inverters, it was decided not to use conventional stud-mounted or disc-type thyristor assemblies. Figure 10 illustrates a preferred thyristor assembly compared to two equivalent stud-mounted thyristors. The improved assembly uses two passivated 110 Arms thyristor chips attached to beryllium oxide insulators soldered to a copper base. The assembly is coated with epoxy resin, with power and gate leads brought out the top. The advantages of this approach are lighter weight and lower inverter assembly costs. The package can be mounted directly to an uninsulated heat sink. Mica insulating washers are eliminated and the need to have access to both sides of the heat sink is eliminated. These advantages are achieved with no increase in thermal impedance from the thyristor junction to heat sink. A semiconductor read-only memory is used to control the firing sequence of all inverter power switches. This device replaces TTL logic and significantly reduces logic circuitry and cost.

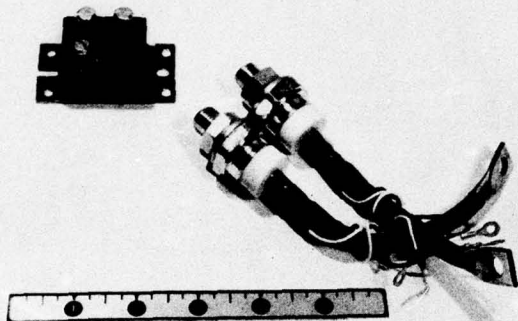


Figure 10. Comparison Of Stud-Mounted Thyristors With Insulated Base Plate Type

Figure 11 shows the assembly of the center thyristors on the heat sink structure. Eighty percent of the inverter power flows through this simple power switch circuit at 99 percent efficiency. Installation of the thyristors requires only a screwdriver for bolting the copper flanges to the heat sink and for connecting the power leads.

A top view of the 10 kW inverter breadboard is shown in Figure 12. The circuit breaker and alternator field control circuits are not included in the weight tabulation below.

	Weight (lb)	Percent of Total Weight
Power Assembly	22	18
Transformer and Inductor iron and copper	46.7	38.5
Aluminum heat sink and structure	50	41
Electronics	3	2.5
TOTAL	121.7	100.0

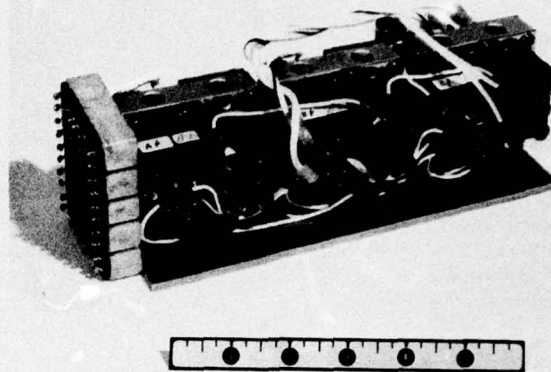


Figure 11. "Center" Function Circuit Thyristors Assembled On Heat Sink.

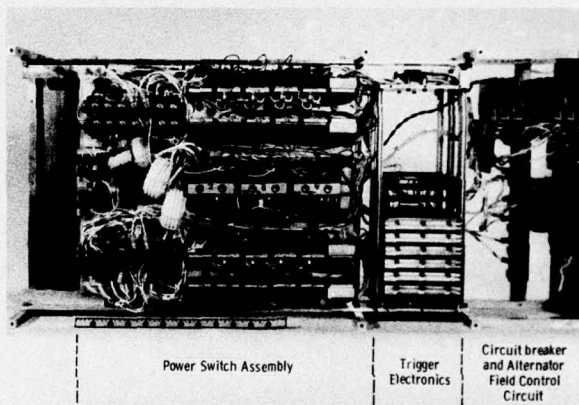


Figure 12. 10 kW Inverter Breadboard (Top View)

Figure 13 is a rear view of the inverter showing the output filter and zig-zag transformer mounted on the bottom of the heat sink.

The turbo-alternator inverter transient response to a step change from no load to full load with the inverter frequency at 60 Hz is shown in Figure 14.

Results of the tests thus far conducted on the MER-DC inverter are given in the Appendix.

In summary, a new way of looking at the problem of generating three-phase sine waves with semiconductor power switches has been described. Several circuits have been defined that can generate X, Y and "center" functions, the most promising of which was discussed in this paper. The resultant inverter has these useful properties: high input power factor, continuous input dc current, low harmonic content waveform into output filter, can energize nonlinear loads, and can energize unbalanced loads with differing power factors from unity to zero, leading or lagging. Because energy storage in the output filter is low the inverter is easy to parallel and there is no deterioration in waveform quality with step changes in load.



Figure 13. Inverter Heat Sink, Zig-Zag Transformer, And Output Filter (End View).

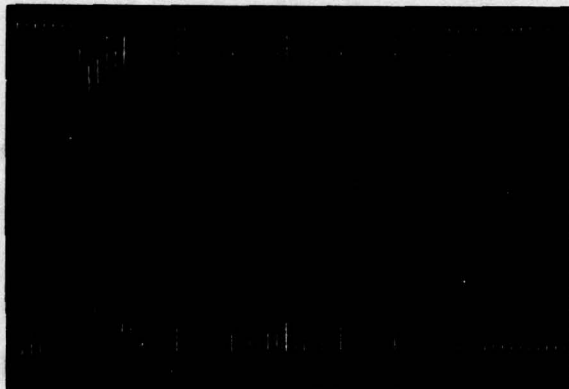


Figure 14. Transient Response Of The Turbo-Alternator Inverter System For A Step Change In Load From No Load To Full Load, With The Inverter Operating At 60 Hz. The Response Time Is Determined By The Time Constant Of The Alternator Field And The Droop Primarily By The Alternator Impedance.

APPENDIX MERDC 10 KW BREADBOARD INVERTER - HIGH SPEED ALTERNATOR SYSTEM

PERFORMANCE SUMMARY

Input: ± 142 Vdc (rectified output of turbo-alternator unit)

Output: 120/208 Vrms, three-phase, 400 Hz or
120/208 Vrms, three-phase, 60 Hz
adjustable between 95 and 105 percent of rated
voltage

Power Rating: 10 kW, 0.8 power factor (p.f.) lagging,
200% rated current for five seconds

Voltage Waveform: Total harmonic content
4.2% at 60 Hz
3.5% at 400 Hz

DC voltage component less than 10
mV.

Efficiency:	Frequency (Hz)	Load (p.f.)	Efficiency (%)
	60	10 kW, 1.0	92.7
	60	10 kW, 0.8	87.8
	400	10 kW, 1.0	91.9
	400	10 kW, 0.8	88.9

Phase Voltage Balance:

Unbalance is less than 0.5% for all balanced three-phase
loads.

Phase Angle Balance:

The 120° angular difference between any two adjacent
voltage vectors varies by less than 2° for all balanced
load conditions and less than 5° for 25% single-phase,
line-to-line loading.

Voltage Regulation:

Closed loop - less than 1-1/2% for all load conditions
up to full load.

Open loop - (inverter) 4.5% at 10 kW

Effect of Unbalanced Load:

With the turbo-alternator inverter system operating at
no load, rated voltage and frequency, application of a
single-phase, line-to-line, unity p.f. load equal to 25%
of rated current caused worst case line-to-line voltage
differences of 6.9% at 60 Hz and 6.1% at 400 Hz.

Transient Voltage Performance:

- With the turbo-alternator inverter system initially
operating at no load, rated voltage and rated fre-
quency, the rms terminal voltage dropped to 70%
of rated voltage when a 0.4 p.f. lagging load having
an impedance of 0.5/unit was applied to the output
terminals of the set. The system recovered to
rated voltage in less than 200 msec.
- With the system operating at rated frequency and
rated voltage, a step change in load from no load to
rated load caused the output voltage to drop to 77%
of rated voltage. The system recovered to rated
voltage in less than 150 msec. When the load is
suddenly changed from rated load to no load, the
initial voltage transient is $< 120\%$ rated voltage.

Short Circuit Performance:

The inverter withstands short circuits for at least five
seconds without damage. Output current is limited to
200% rated current by means of the alternator field
control.

Frequency:

The inverter will produce power at either 60 Hz or 400
Hz. Frequency of the inverter is crystal-controlled
and is independent of load or voltage changes.

APPENDIX D

Item 0004

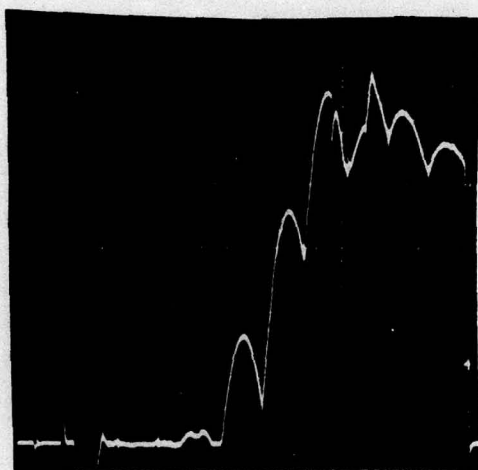
CDRL Item A0002

Modification P0006

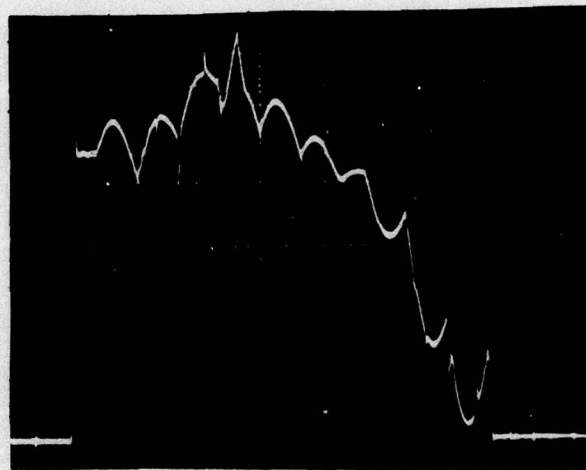
Contract No. DAAK02-72-C-0210

DELCO ELECTRONICS GENERAL MOTORS CORPORATION	REPORT NO. ITEM NO. 0002	PAGE APPENDIX D	JOB NO.	PAGE 1
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		APPROVED		

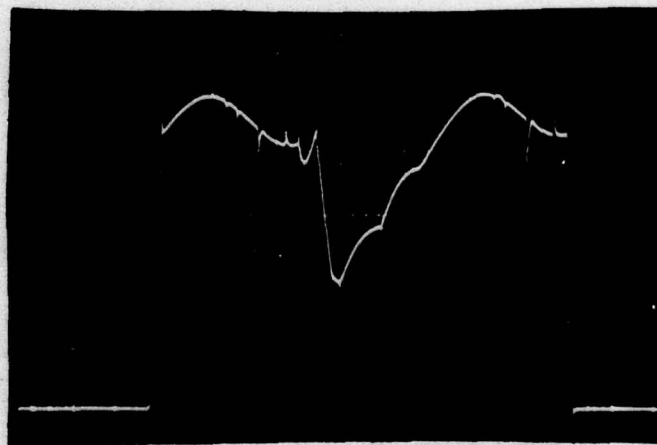
THYRISTOR, DIODE AND STEP TRANSFORMER
CURRENTS FOR 1PU AND 2PU OPERATION.
(FREQUENCY CONVERTER OPERATING AT
400 HZ, THREE PHASE, FREE COMMUTATION
STEPS, POWER FACTOR CORRECTED WITH 50 MFD L-T-L)



TOTAL RIGHT SIDE
STEP CURRENTS
• PHASE SELECTOR CURRENT
↑ 10A/DIV. ↔ 100μSEC/DIV.
1 P.U.



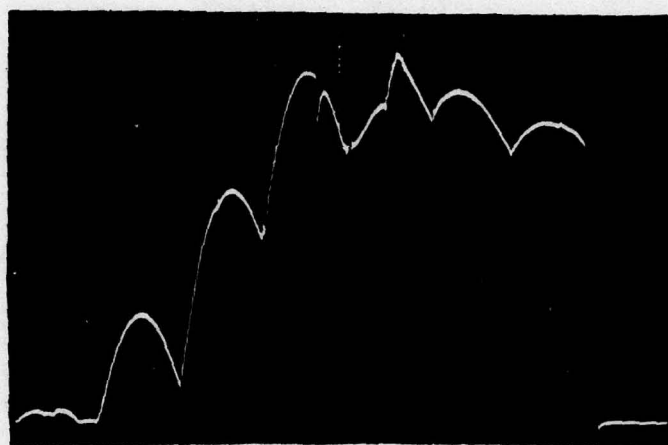
POWER CENTER CURRENT P_n
↑ 10A/DIV. 100μSEC/DIV.
1 P.U. LOAD 11KW, PF=0.8



POWER CENTER CURRENT P_n
↑ 20A/DIV. 100μSEC/DIV.
2 P.U. LOAD 22KW, PF=0.8

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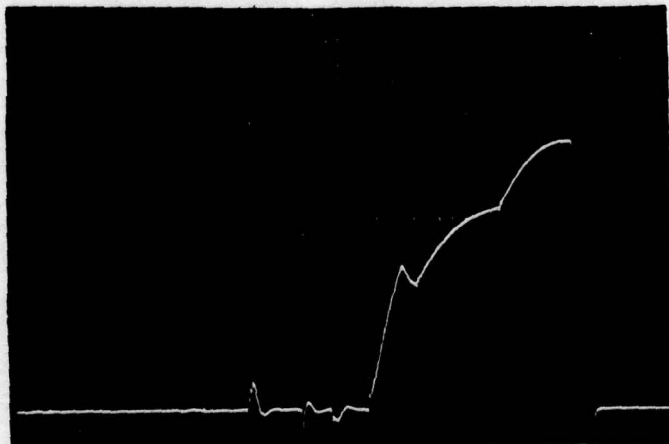


1 0 1 2 3 4
STEP NUMBER

RIGHT SIDE STEP
CURRENTS & RT.
PHASE SELECTOR
CURRENT

1 P.U. LOAD

↓ 10A/DIV.
↔ 50 μSEC/DIV.



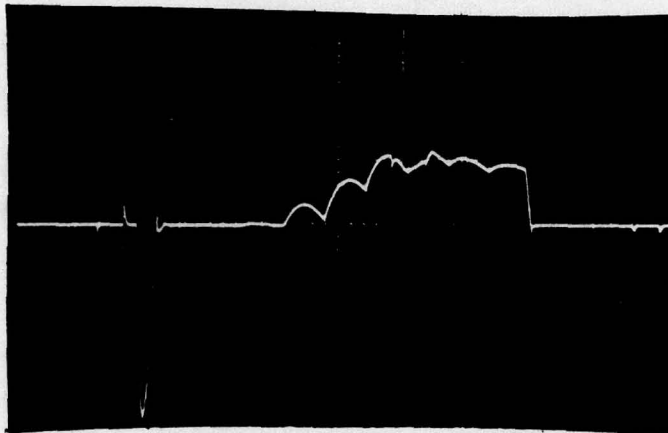
1 0 1 2 3 4

2 P.U. LOAD

↓ 20A/DIV.
↔ 50 μSEC/DIV.

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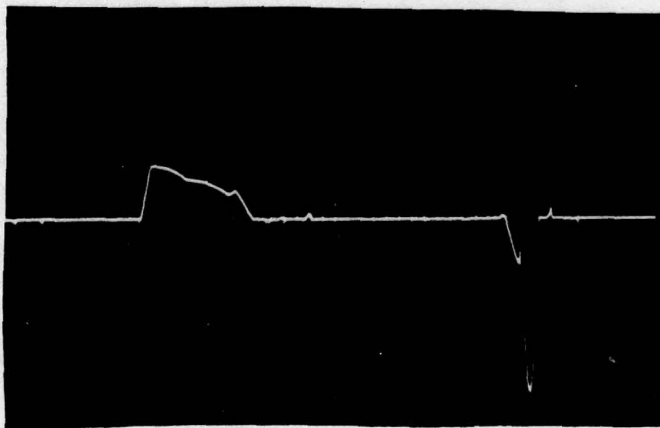


+ RIGHT SIDE PHASE
SELECTOR CURRENT

+ - RS & PHASE SELECTOR
COMMUTATION CURRENT

1 P.U. LOAD

↓ 50 A/DIV. ↔ 100 μSEC/DIV.



2 P.U. LOAD

↓ 100 A/DIV. ↔ 100 μSEC/DIV.

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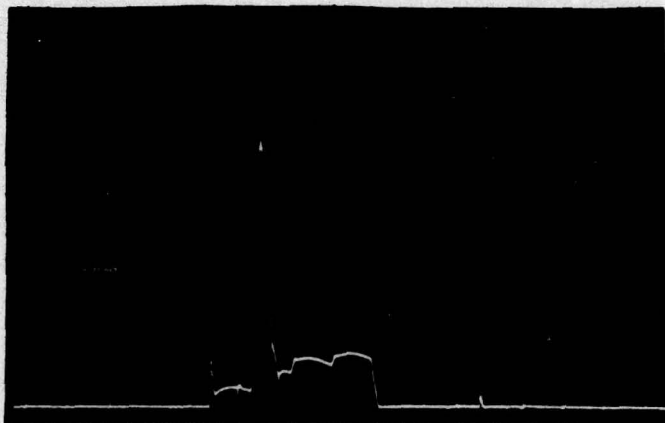
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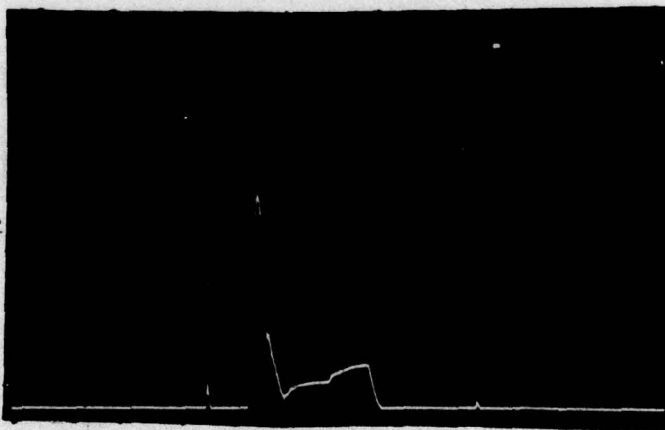
T - CURRENT



1 P.U. LOAD

↓ 50A / DIV.

↔ 100 μSEC / DIV.

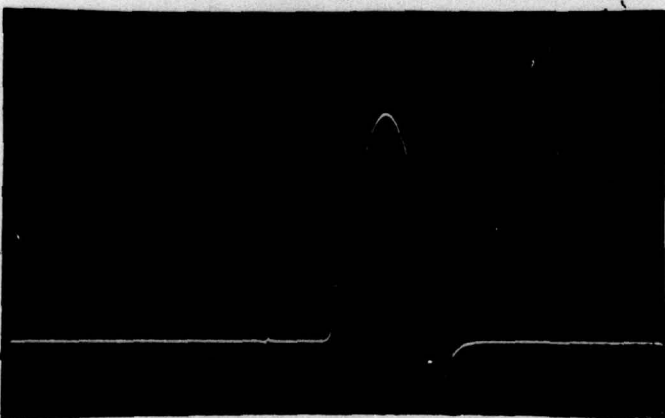


2 P.U. LOAD

↓ 100A / DIV.

↔ 100 μSEC / DIV.

T_C - CURRENT



↓ 20A / DIV.

↔ 10 μSEC / DIV.

SAME MAGNITUDE
FOR 1 P.U. OR 2 P.U. LOADS

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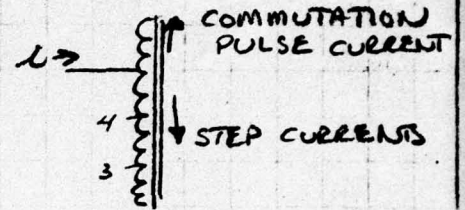
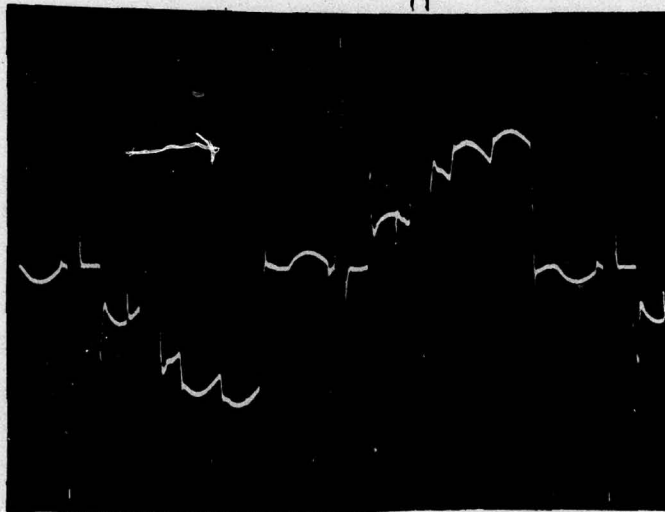
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200 AMPS. PEAK
POLAR CENTRAL
COMMUTATION
CURRENT

STEP TRANSFORMER
CURRENT

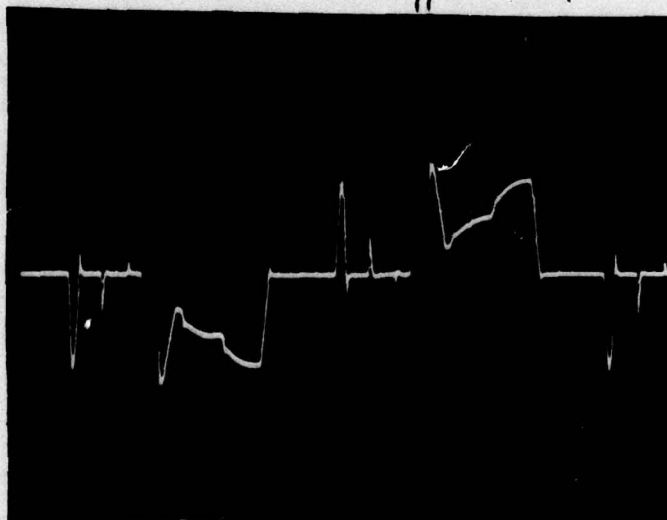


1 P. U. LOAD

20 A / DIV.

100 μSEC / DIV.

320 AMPS. PEAK
COMMUTATION
CURRENT



2 P. U. LOAD

50 A / DIV.

100 μSEC / DIV.

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6

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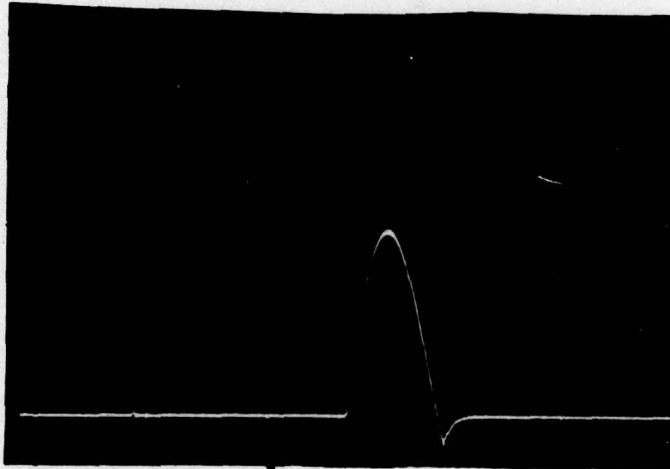
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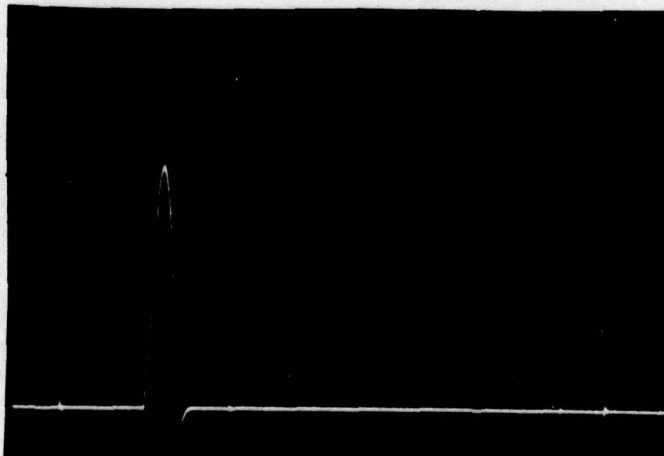


POWER CENTER 81-PASS
DIODE CURRENT

1 P.U. LOAD

↓ 50A/DIV.

↔ 20μSEC/DIV.



2 P.U. LOAD

↓ 50A/DIV.

↔ 50μSEC/DIV.

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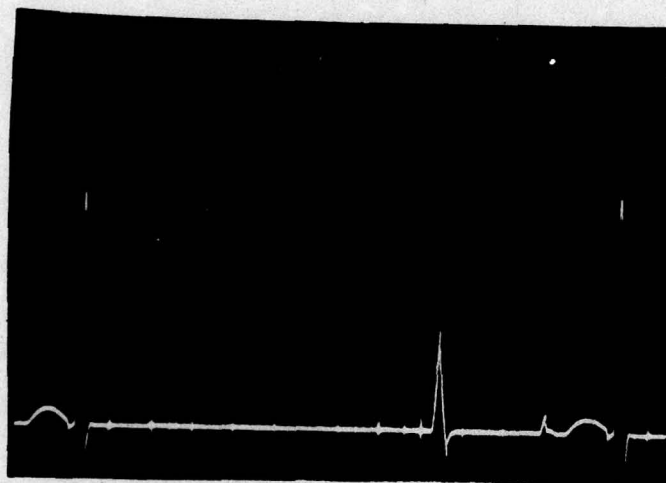
APPROVED

T- BY-PASS DIODE
CURRENT

1 P.U. LOAD

↑ 20A / DIV

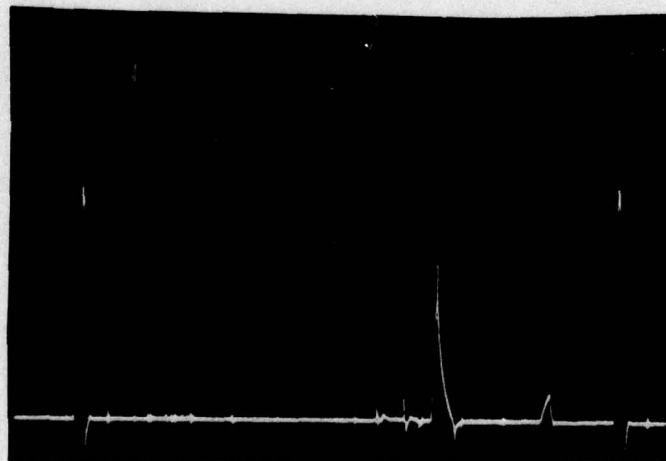
→ 100 μSEC / DIV



2 P.U. LOAD

↑ 20A / DIV

→ 100 μSEC / DIV



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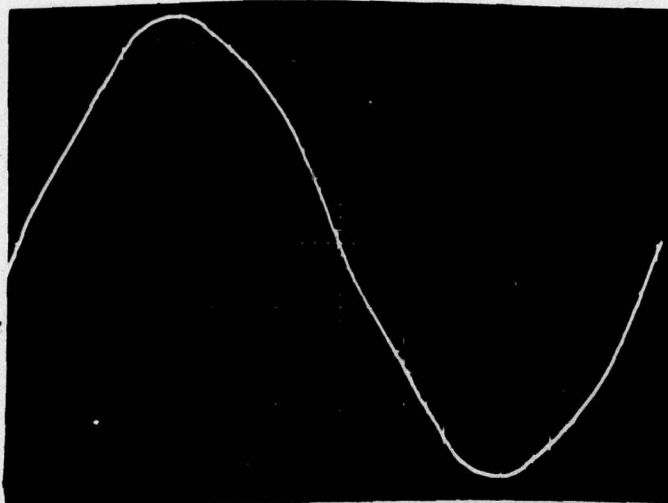
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FREQUENCY CONVERTER OUTPUT VOLTAGE
FOR PRECEDING CURRENT MEASUREMENTS



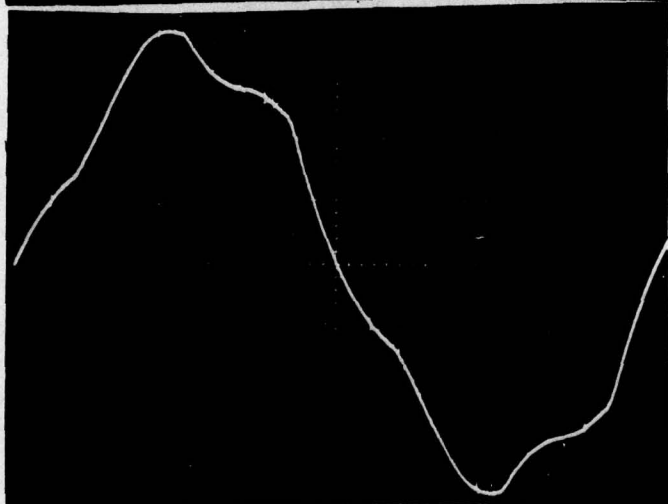
L-T-N VOLTAGE

1 P.U. LOAD

THD = 2.76%

$V_{DC} = 295V_{DC}$

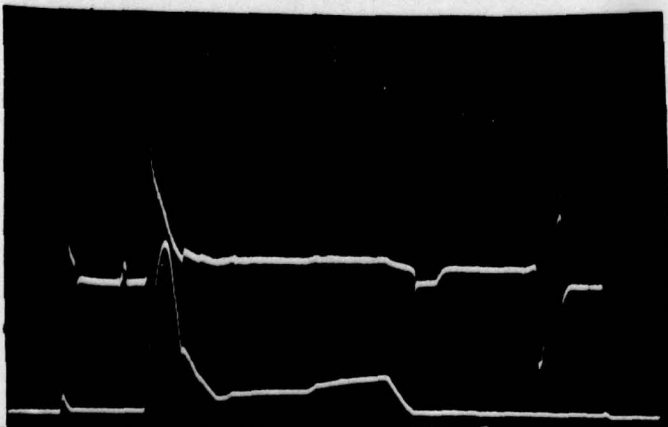
(THREE WIRE INPUT)



2 P.U. LOAD

THD = 8.8%

$V_{DC} = 307V_{DC}$



T - VOLTAGE DROP &
CURRENT MAGNITUDE

VOLTAGE \uparrow 5V/DIV.

\leftarrow 50 μ SEC/DIV.

CURRENT 100A/DIV

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10 KW FREQUENCY CONVERTER

Test Results Item 0001

CDRL Item A002

Contract No. DAAK02-72-C-0210

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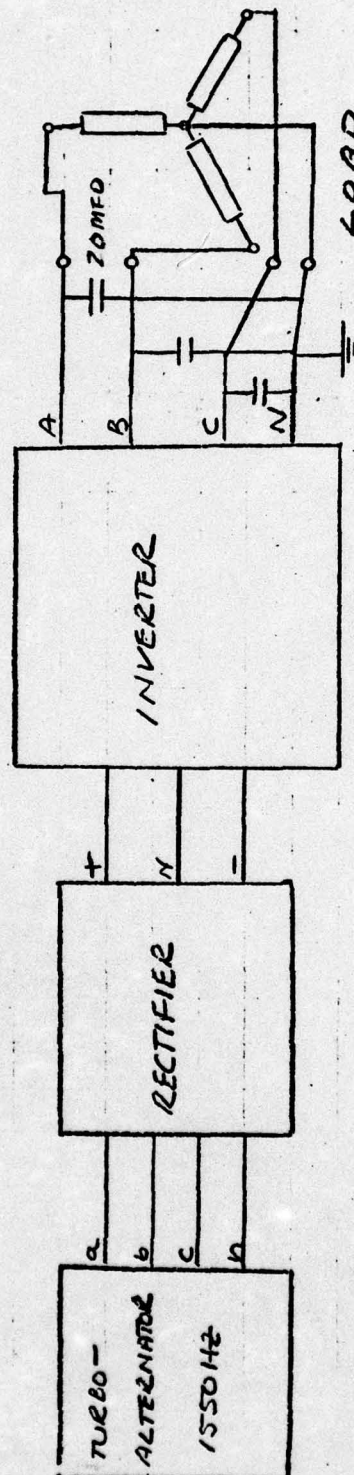
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CONNECTIONS FOR 400HZ OR 60HZ THREE PHASE POWER

FOR DATA ON PAGES 1-14

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TITLE 10KW FREQUENCY CONVERTER ITEM 0001 CONTRACT NO. DAAK 02-72-C-0210 TEST DATA		PREPARED BARRETT CHECKED APPROVED																									
TESTS IN ACCORDANCE WITH ATTACHMENT NO.1 AND MIL-STD-705B																											
<div style="margin-left: 40px;"> 3.24.1.1 <u>Voltage Operating Range</u>[#] </div> <table style="margin-left: 100px; margin-top: 20px;"> <thead> <tr> <th></th> <th colspan="2" style="text-align: center;">VOLTS RMS</th> </tr> <tr> <th></th> <th style="text-align: center;"><u>MIN.</u></th> <th style="text-align: center;"><u>MAX.</u></th> </tr> </thead> <tbody> <tr> <td>400Hz NO LOAD</td> <td style="text-align: center;">110.1</td> <td style="text-align: center;">133.3</td> </tr> <tr> <td>60Hz NO LOAD</td> <td style="text-align: center;">111.7</td> <td style="text-align: center;">135.0</td> </tr> <tr> <td>400Hz 10KW PF=1.0</td> <td style="text-align: center;"><114.0</td> <td style="text-align: center;">122.7 *</td> </tr> <tr> <td>60Hz 10KW PF=1.0</td> <td style="text-align: center;"><114.0</td> <td style="text-align: center;">123.3 *</td> </tr> <tr> <td>400Hz 10KW 0.8PF</td> <td style="text-align: center;"><114.0</td> <td style="text-align: center;">119.7 * *</td> </tr> <tr> <td>60Hz 10KW 0.8PF</td> <td style="text-align: center;"><114.0</td> <td style="text-align: center;">120.4 * *</td> </tr> </tbody> </table> <div style="margin-left: 100px; margin-top: 30px;"> <p>* $I_{real} = 25.9 A.$</p> <p>* * $I_{real} = 25.9 A.$</p> <p>$I_{react.} = 19.4 A.$</p> </div> <div style="margin-left: 40px; margin-top: 30px;"> <p>[#] ALTERNATOR FIELD CONTROL CIRCUIT NOT INCLUDED IN CONTRACT WORK STATEMENT</p> </div>					VOLTS RMS			<u>MIN.</u>	<u>MAX.</u>	400Hz NO LOAD	110.1	133.3	60Hz NO LOAD	111.7	135.0	400Hz 10KW PF=1.0	<114.0	122.7 *	60Hz 10KW PF=1.0	<114.0	123.3 *	400Hz 10KW 0.8PF	<114.0	119.7 * *	60Hz 10KW 0.8PF	<114.0	120.4 * *
	VOLTS RMS																										
	<u>MIN.</u>	<u>MAX.</u>																									
400Hz NO LOAD	110.1	133.3																									
60Hz NO LOAD	111.7	135.0																									
400Hz 10KW PF=1.0	<114.0	122.7 *																									
60Hz 10KW PF=1.0	<114.0	123.3 *																									
400Hz 10KW 0.8PF	<114.0	119.7 * *																									
60Hz 10KW 0.8PF	<114.0	120.4 * *																									

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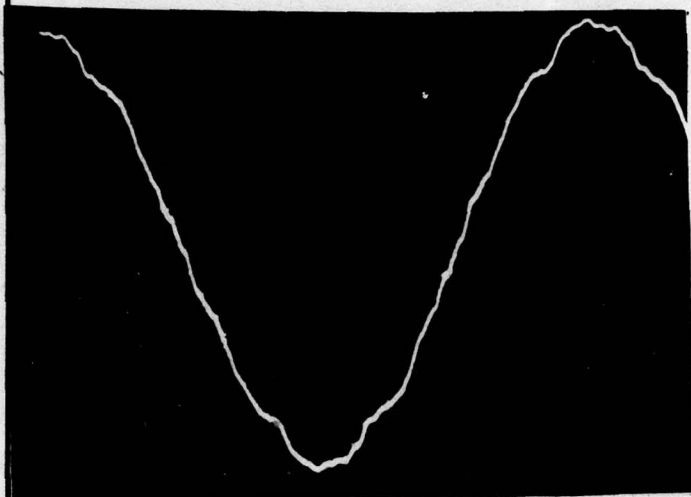
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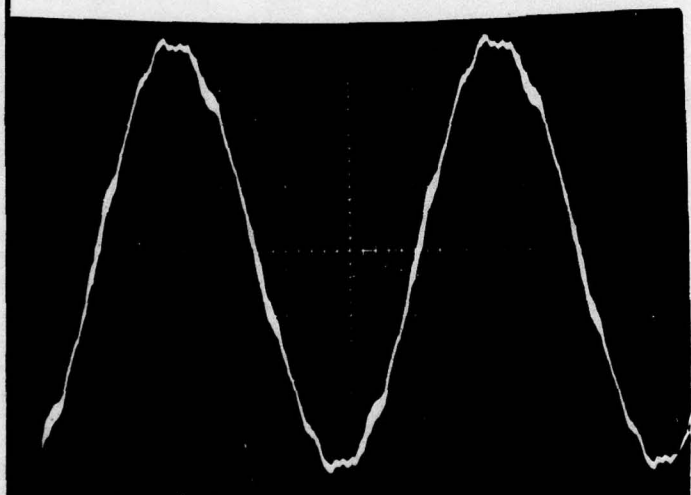
3.24.1.3 VOLTAGE WAVEFORM



400 HZ THREE PHASE
LINE-TO-NEUTRAL
VOLTAGES

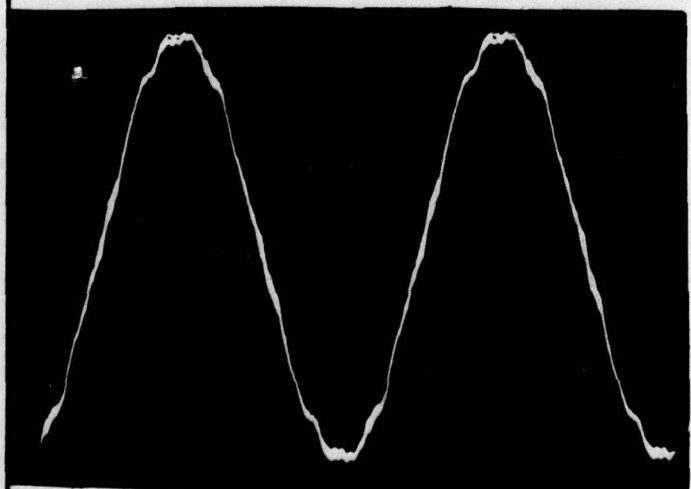
NO LOAD

THD=3.4%



11KW, PF=1.0

THD=3.1%

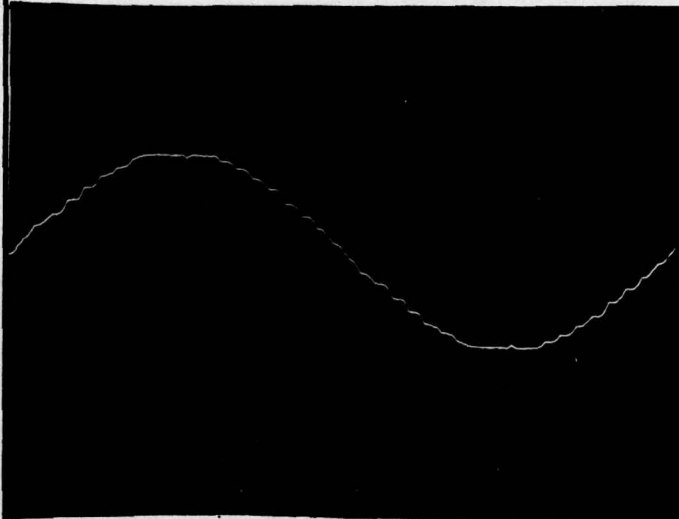


11KW, PF=0.8

THD=3.1%

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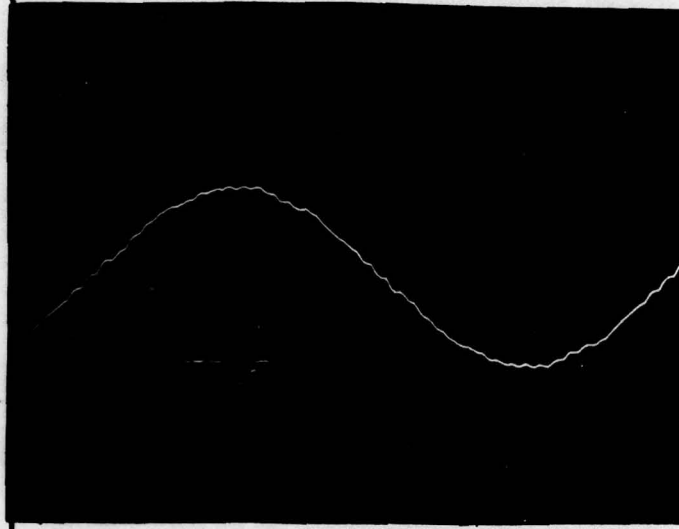
DELCO ELECTRONICS GENERAL MOTORS CORPORATION	REPORT NO.	PAGE	JOB NO.	PAGE
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400 HZ THREE PHASE
LINE-TO-LINE
VOLTAGES

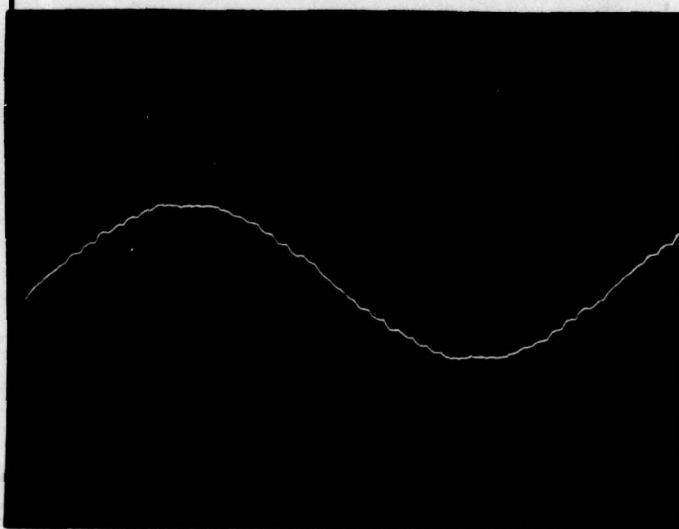
NO LOAD

THD = 3.3%



11 KW, PF = 1.0

THD = 3.1%



11 KW, PF = 0.8

THD = 3.1%

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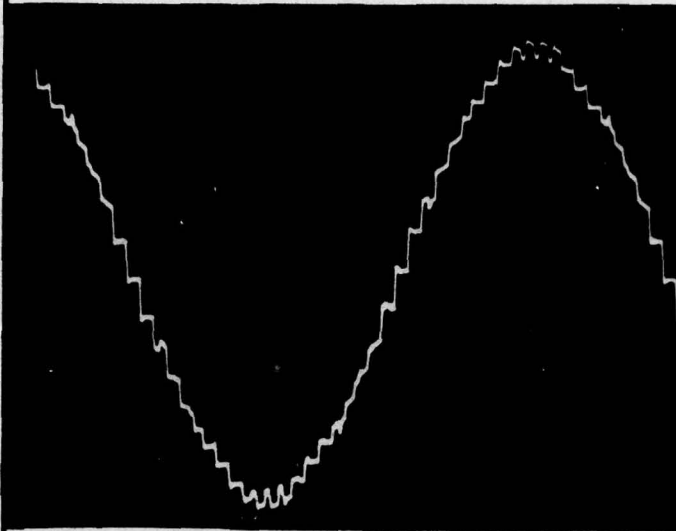
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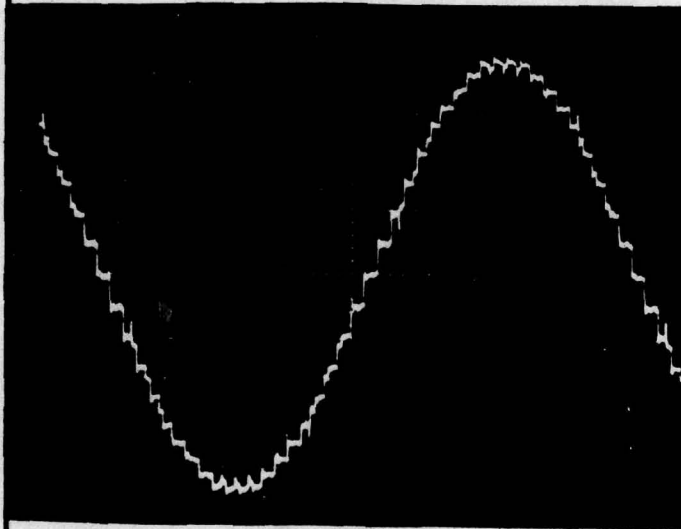
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60 HZ THREE PHASE
LINE-TO-NEUTRAL
VOLTAGES

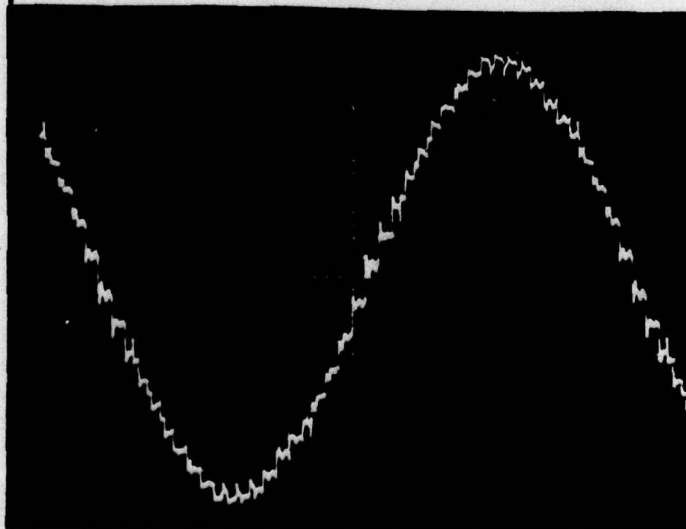
NO LOAD

THD = 3.83%



11 KW, PF = 1.0

THD = 4.0%



11 KW, PF = 0.8

THD = 4.6%

DISTRIBUTION:

TITLE

PREPARED

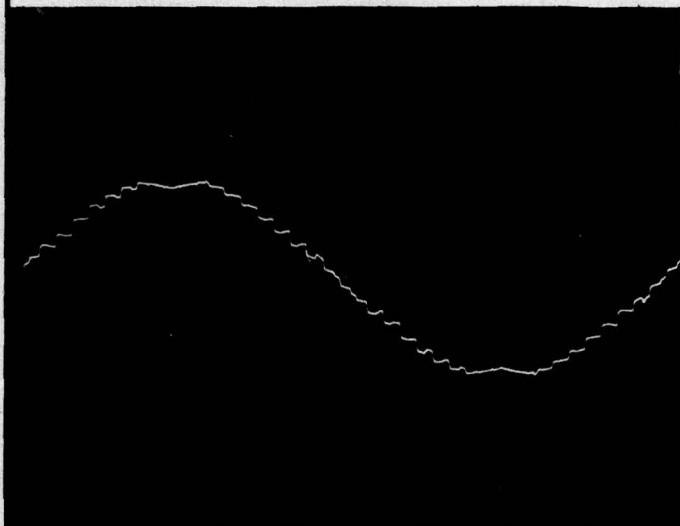
DATE

BARRETT

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APPROVED



60HZ THREE PHASE
LINE-TO-LINE
VOLTAGE

NO LOAD

THD= 3.81%

4.6.1 DC CONTENT TEST

THE DC VOLTAGE LEVEL AT THE OUTPUT
TERMINALS AT RATED LOAD, 0.8 PF, 1.0 PF
AND NO LOAD AT 60HZ AND 400HZ
IS LESS THAN 50 MILLIVOLTS FOR
ALL VOLTAGE CONNECTIONS.

3.24.1.4 PHASE VOLTAGE BALANCE

	<u>60HZ</u>	<u>400HZ</u>
V _{a-n}	119.6 Vrms	120.0 Vrms
V _{b-n}	119.3 "	120.1 "
V _{c-n}	119.1 "	120.2 "
V _{a-b}	206.4 "	207.4 "
V _{b-c}	206.1 "	208.4 "
V _{c-a}	206.2 "	207.6 "

CONDITIONS: NO LOAD

ALL VOLTAGES WITHIN 1%
OF RATED VOLTAGE

DISTRIBUTION:

TITLE

PREPARED

BAZETT

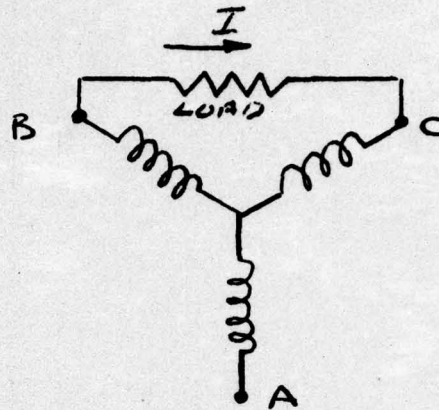
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CHECKED

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3.24.1.5 EFFECT OF UNBALANCED LOAD (3 PHASE)



$$I = 8.5 \text{ A rms}$$

60 Hz

V_{BC}	207.8
V_{BA}	221.0
V_{AC}	222.1
V_{CN}	122.9
V_{BN}	122.3
V_{AN}	130.2

60 Hz UNBALANCE

L-L 6.9%

L-N 6.6%

400 Hz

208.0
217.4
220.7
123.1
121.2
128.2

400 Hz UNBALANCE

6.1%

5.8%

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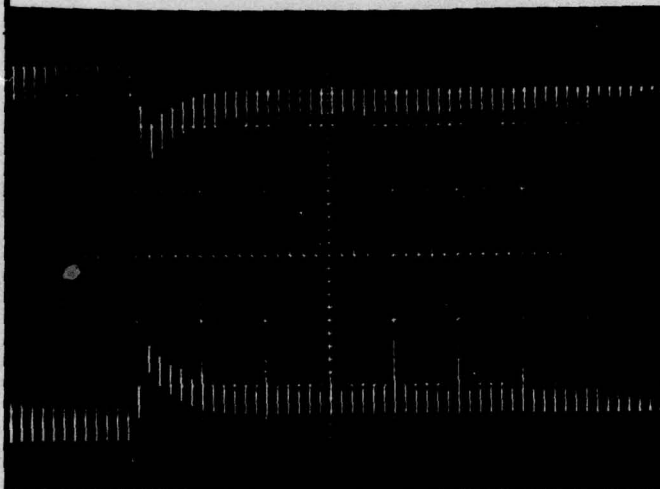
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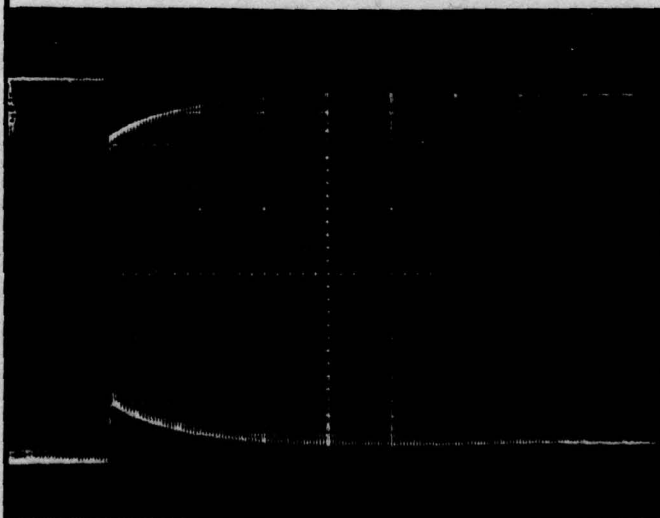
3.24.1.12 TRANSIENT VOLTAGE PERFORMANCE

a) APPLICATION OF 0.4 PF, 0.5 PER UNIT
IMPEDANCE LOAD



60 HZ

HOR. SCALE 100MS/DIV.



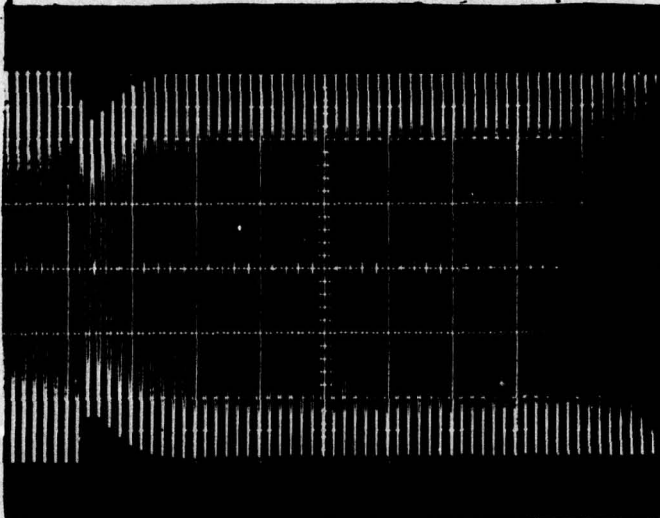
400 HZ

HOR. SCALE 50MS/DIV.

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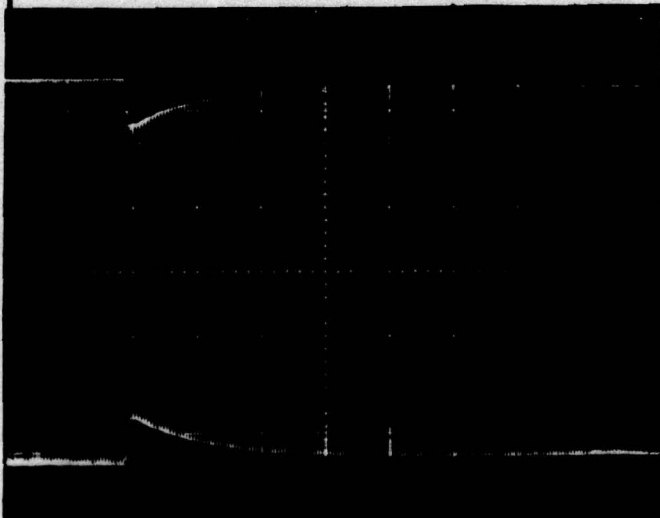
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b) APPLICATION OF 11KW, 0.8PF. LOAD



60 HZ

HOR. SCALE 100 mV / DIV.



400 HZ

HOR. SCALE 50 mV / DIV.

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3.24.1.13 SHORT CIRCUIT TS12.1C MODIFIED

THE OUTPUT BREAKER ON THE FREQUENCY CONVERTER WAS OPENED AND CLOSED - NO LOAD TO SHORT CIRCUIT. THE SHORT CIRCUIT CURRENT WAS OBSERVED ON A SCOPE AND THE MAGNITUDE WAS READ FROM A CURRENT TRANSFORMER ON A HP 3400 TRUE RMS VOLTMETER.

AT 60 HZ THE SHORT CIRCUIT CURRENT WAS 65 A. RMS.

AT 400 HZ THE SHORT CIRCUIT CURRENT WAS 72 A. RMS.

3.24.3 EFFICIENCY

SUMMATION OF LOSSES ON ME12DC
10KW FREQUENCY CONVERTER

1) INPUT POWER WAS MEASURED AFTER THE INPUT FILTER CAPACITORS. AVERAGE RESPONDING INSTRUMENTS WERE USED.

a) INPUT VOLTAGE FROM + LINE TO - LINE WERE MEASURED WITH A HP 3440A DVM. IT WAS CHECKED AGAINST A HP 3450A DVM AND A WESTON 622 THERMOCOUPLE VOLT METER.

b) INPUT CURRENT WAS MEASURED WITH A HP 3440A AND A TEM COAXIAL CURRENT VIEWING RESISTOR (CVR). THE READINGS WERE CHECKED WITH A WESTON 931 AND A 100A. SHUNT.

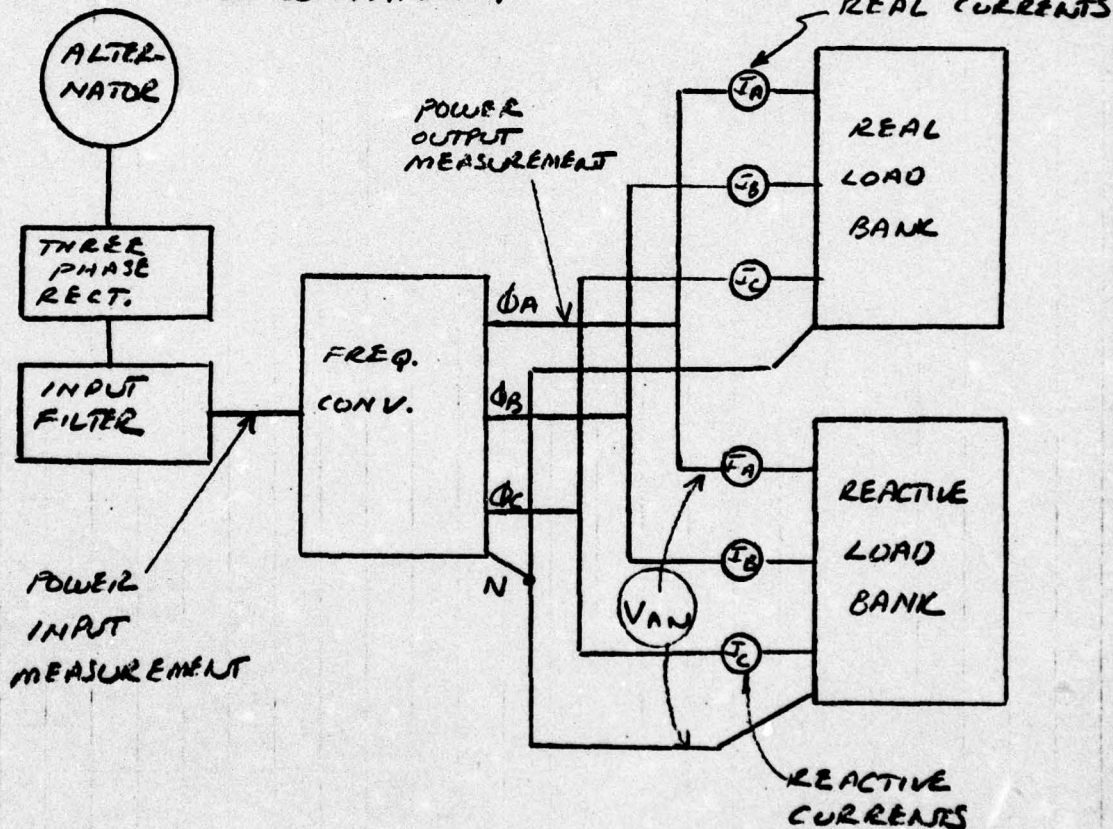
2) OUTPUT POWER WAS MEASURED AT THE FREQUENCY CONVERTER OUTPUT TERMINALS. TRUE RMS INSTRUMENTS

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WERE USED.

a) LINE TO NEUTRAL OUTPUT VOLTAGES ON ALL THREE PHASES WERE MEASURED WITH A HP 3450A THAT WAS CHECKED AGAINST A WESTON 622.

b) OUTPUT CURRENT ON ALL THREE PHASES WAS MEASURED WITH A HP 3450A AND PEARSON 110 CURRENT TRANSFORMERS. OUTPUT POWER ON PHASE A WAS CHECKED WITH A WESTON 432 WATTMETER.



3) EFFICIENCY (η) IS CALCULATED FROM DATA TAKEN WITH THE AFOREMENTIONED DIGITAL EQUIPMENT AND SHUNTS. FOR COMPARATIVE PURPOSES DATA TAKEN WITH CONVENTIONAL MOVING COIL METERS IS PRESENTED.

4) CALCULATED EFFICIENCY AT 0.8 PF IS PROBABLY SLIGHTLY ON THE LOW SIDE (LESS THAN 1%) BECAUSE

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IT WAS ASSUMED THAT THERE ARE NO POWER LOSSES IN THE REACTIVE LOAD BANK. THE REAL LOAD BANK IS ESSENTIALLY PURELY RESISTIVE.

S) TABULATION OF FIXED LOSSES -

a) TRIGGER CIRCUITS	30 VOLTS X 33 AMPS	= 99 WATTS.
b) INPUT INDUCTOR		= 15 "
c) INPUT CAPACITORS		= 20 "
d) INPUT RECTIFIERS		= 100 "
		<u>234 WATTS.</u>

FREQUENCY 60 HZ	LOAD 10KW 1.0 PF			
	TRIAL ①	TRIAL ②	AVG.	
1. DC INPUT VOLTAGE	298.0	296.5	297.3	VOLTS DC
2. DC INPUT CURRENT	36.1	35.9	36.0	AMPS DC
3. ϕ_A OUTPUT VOLTAGE	120.38	119.49	119.94	V RMS
4. ϕ_B " "	121.14	120.30	120.72	" "
5. ϕ_C " "	120.90	120.36	120.63	" "
6. ϕ_A OUTPUT CURRENT	28.43	28.25	28.34	A. RMS
7. ϕ_B " "	27.98	27.81	27.89	" "
8. ϕ_C " "	28.03	27.87	27.95	" "

POWER INPUT (297.3 VOLTS)(36.0 AMPS) = 10,703 WATTS.
FIXED LOSSES 234 "

POWER OUTPUT (120.72)(27.89) = 3367 WATTS
(119.94)(28.34) = 3399 "
(120.63)(27.95) = 3372 "
10,138 WATTS

$$\eta = \frac{(10138)(100)}{(10703) + (234)} = \underline{\underline{92.7\%}}$$

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FREQUENCY 400 HZLOAD 10KW 1.0 PF

	TRIAL ①	TRIAL ②	AVG.
1. DC INPUT VOLTAGE	299.1	297.8	298.5
2. DC INPUT CURRENT	36.5	36.5	36.5
3. ϕ_A OUTPUT VOLTAGE	119.88	118.87	119.38
4. ϕ_B " "	122.00	121.23	121.61
5. ϕ_C " "	122.22	121.59	121.90
6. ϕ_A OUTPUT CURRENT	28.33	28.15	28.24
7. ϕ_B " "	28.23	28.06	28.15
8. ϕ_C " "	28.29	28.13	28.21

POWER INPUT $(298.5)(36.5) = 10895$ WATTS.
 FIXED LOSSES 234 "

POWER OUTPUT $(119.38)(28.24) = 3371$ WATTS
 $(121.61)(28.15) = 3423$ "
 $(121.90)(28.21) = 3439$ "
 10233 WATTS

$$\eta = \frac{(10233)(100)}{(10895) + (234)} = \underline{\underline{91.9\%}}$$

FREQUENCY 60 HZLOAD 10KW 0.8 PF

	TRIAL ①	TRIAL ②	AVG.
1. DC INPUT VOLTAGE	302.3	298.4	300.4
2. DC INPUT CURRENT	38.7	38.2	38.5
3. ϕ_A OUTPUT VOLTAGE	122.07	120.48	121.27
4. ϕ_B " "	122.77	121.45	121.11
5. ϕ_C " "	122.52	121.32	121.92
6. ϕ_A REAL OUTPUT CURRENT	28.82	28.68	28.75
7. ϕ_B " "	28.36	28.24	28.30
8. ϕ_C " "	28.31	28.22	28.26
9. ϕ_A REACTIVE OUTPUT CURRENT	20.8		
10. ϕ_B " "	20.8		
11. ϕ_C " "	20.8		

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POWER INPUT $(300.4)(38.5) = 11,565$ WATTS
FIXED LOSSES 234 "

POWER OUTPUT $(121.27)(28.75) = 3487$ WATTS.
 $(121.11)(28.30) = 3427$ "
 $(121.92)(28.26) = 3445$ "
10359 WATTS.

KVAR (APPROX) $(121.27)(20.8) = 2522$ VAR
 $(121.11)(20.8) = 2519$ "
 $(121.92)(20.8) = 2536$ "
7,565 VAR

$$\eta = \frac{(10359)(100)}{(11565) + (234)} = \underline{\underline{87.8\%}}$$

FREQUENCY 400 HZ

LOAD 10KW 0.8 PF

AVG.

1. DC INPUT VOLTAGE	299.0
2. DC INPUT CURRENT	36.8
3. Φ_A OUTPUT VOLTAGE	118.08
4. Φ_B " "	120.92
5. Φ_C " "	119.80
6. Φ_A REAL OUTPUT CURRENT	27.90
7. Φ_B " "	27.95
8. Φ_C " "	27.72
9. Φ_A REACTIVE OUTPUT CURRENT	20.6
10. Φ_B " "	20.6
11. Φ_C " "	20.6

POWER INPUT $(299.0)(36.8) = 11,003$ WATTS
FIXED LOSSES 234 WATTS.

POWER OUTPUT $(118.08)(27.90) = 3294$ WATTS
 $(120.92)(27.95) = 3380$ "
 $(119.8)(27.72) = 3321$ "
9,995 WATTS

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KVAR (APPROX) $(118.08)(20.6) = 2432$ VAR
 $(120.92)(20.6) = 2491$ "
 $(119.8)(20.6) = \underline{2464}$ "
7391 VAR

$$\eta = \frac{(9995)(100)}{(11003) + 234} = \underline{\underline{88.9\%}}$$

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10 KW FREQUENCY CONVERTER

Test Results Items 0001, 0003, 0004

Single Phase Performance

CDRL Item A002

Modification Nos. P0003 & P0006

Contract No. DAAK02-72-C-0210

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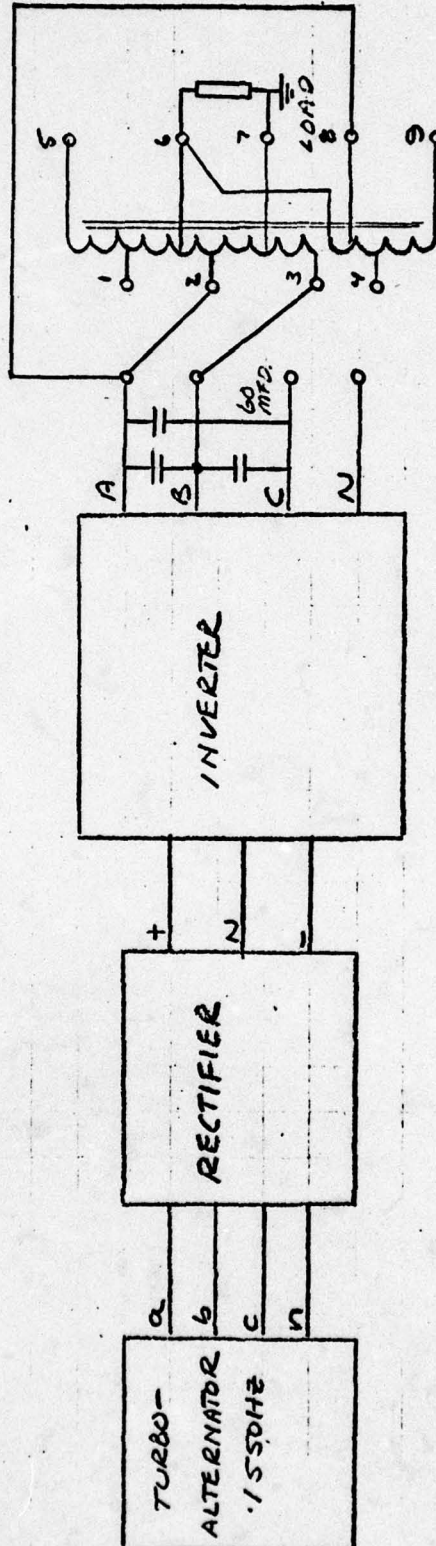
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CORRY

11/29/74



SINGLE
PHASE TRANSFORMER

CONNECTIONS FOR 400HZ, SINGLE PHASE, TWO WIRE POWER

(STEP TRANSISTORS NOT CONNECTED)

FOR DATA ON PAGES 15-37

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SINGLE
PHASE TRANSFORMER

CONNECTIONS FOR 400HZ, SINGLE PHASE, THREE WIRE POWER
 (STEP TRANSISTORS NOT CONNECTED)

FOR DATA ON PAGES 15-37

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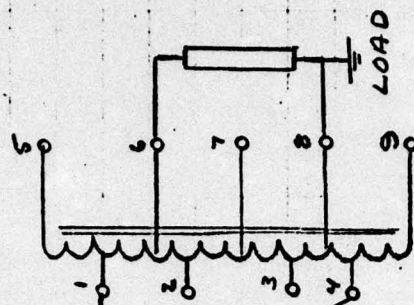
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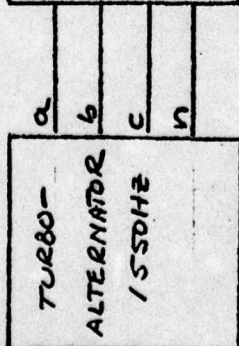
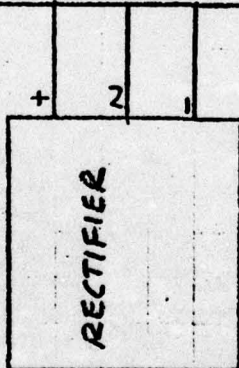
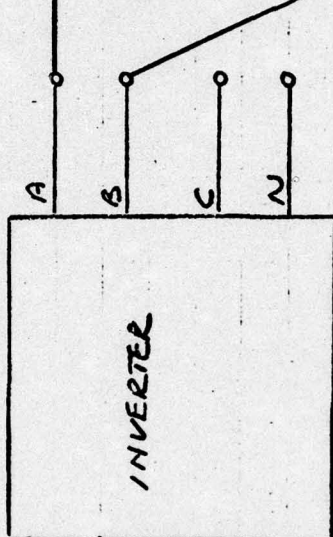
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SINGLE
PHASE TRANSFORMER



CONNECTIONS FOR 60 HZ, SINGLE PHASE, TWO WIRE POWER

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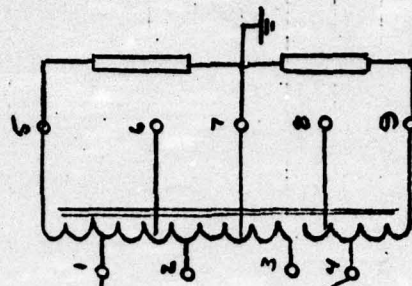
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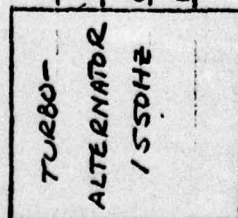
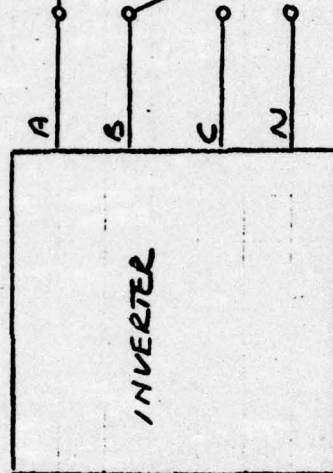
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SINGLE
PHASE TRANSFORMER



CONNECTIONS FOR 60HZ, SINGLE PHASE, THREE WIRE POWER

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PHASE

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TITLE TESTS IN ACCORDANCE WITH ATTACHMENT
NO. 3 OF CONTRACT NO. DAAK02-72-C-0210
MODIFICATION NOS. P0003 & P0006 AND
MIL-STD-7058. ITEMS 0001, 0003, 0004.

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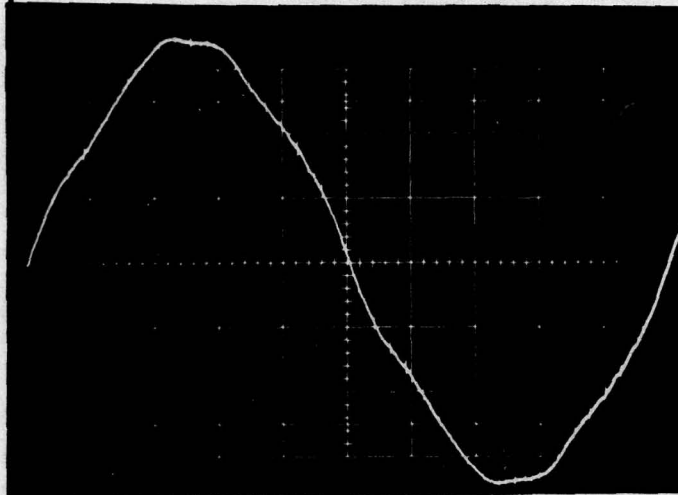
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3.24.1.3 VOLTAGE WAVEFORM

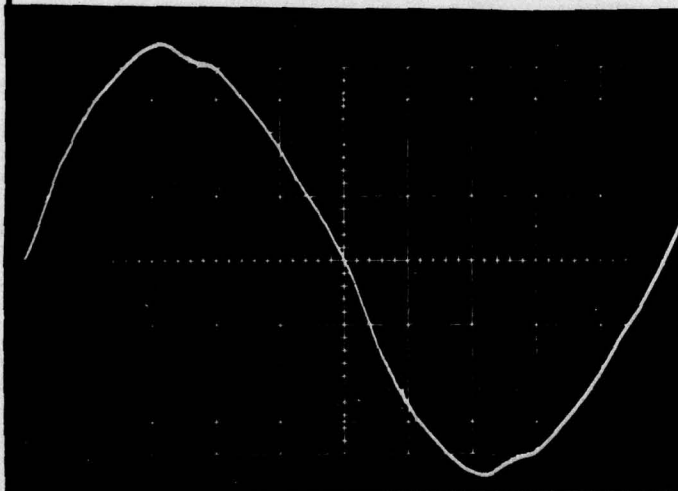


400 HZ SINGLE
PHASE, TWO WIRE

NO LOAD

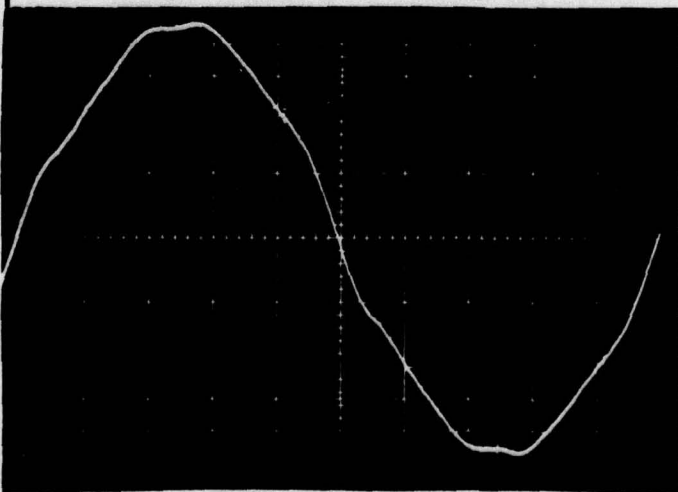
THD = 3.6%

50V / DIV.



10 KW, PF = 0.8

THD = 4.95%

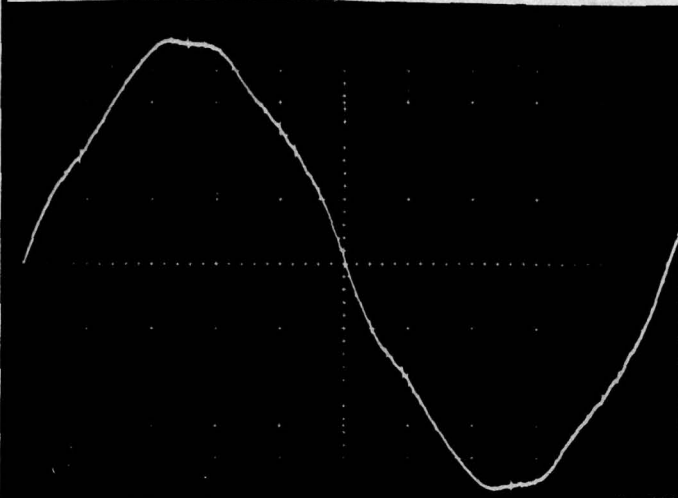


10 KW, PF = 1.0

THD = 4.65%

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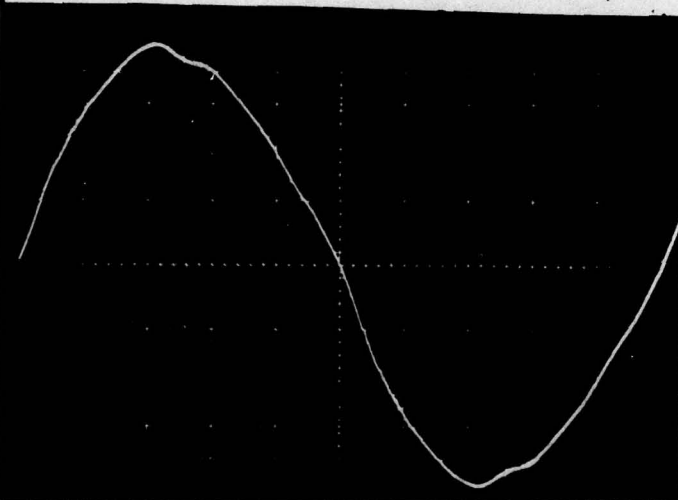


400 HZ SINGLE
PHASE, THREE WIRE

NID LOAD

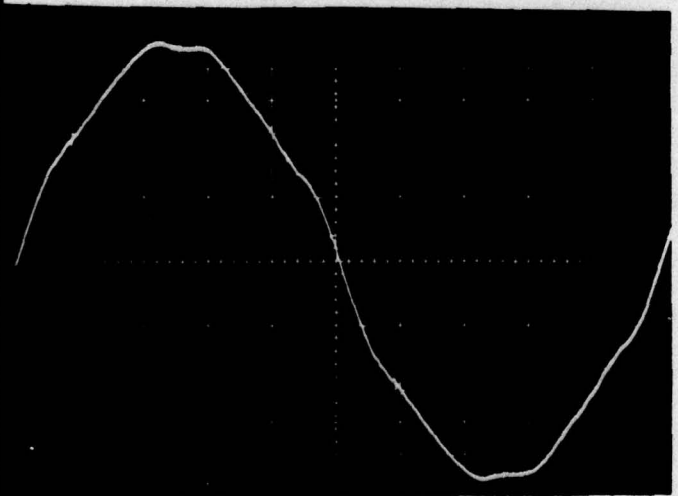
THD = 3.67%

50 V / DIV.



10 KW, PF = 0.8

THD = 5%



10 KW, PF = 1.0

THD = 4.57%

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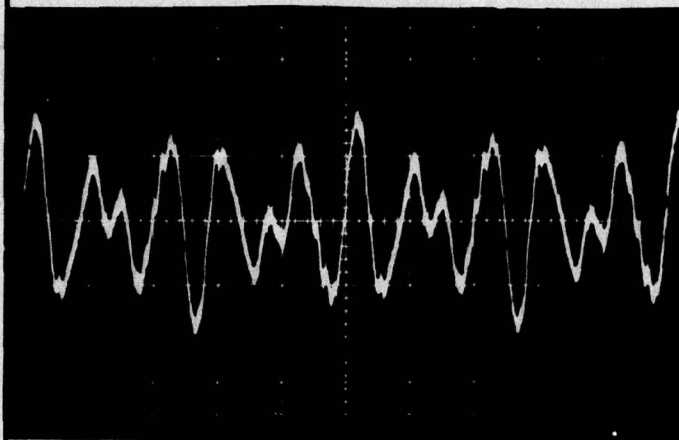
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DEVIATION FACTOR

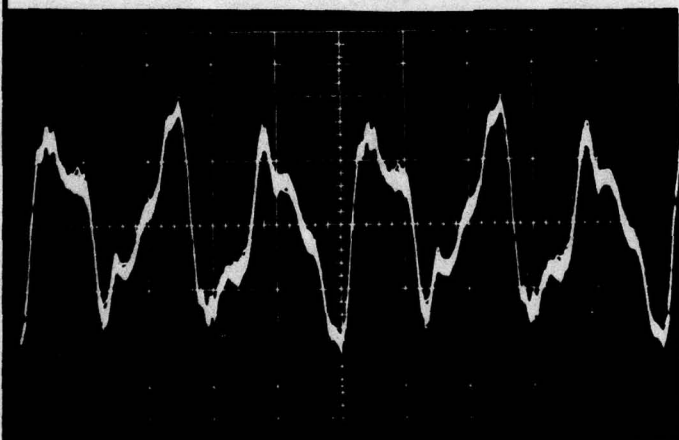


400 HZ SINGLE
PHASE, TWO WIRE

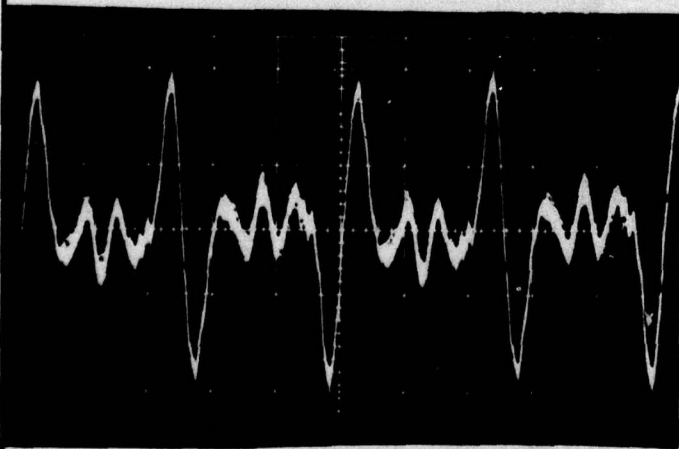
NO LOAD

↓ 0.5V/DIV.

↔ 500 μSEC/DIV.



10KW, PF=0.8



10KW, PF=1.0

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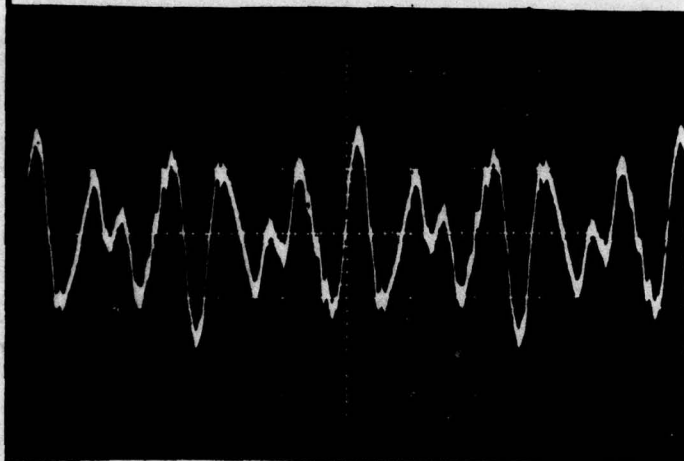
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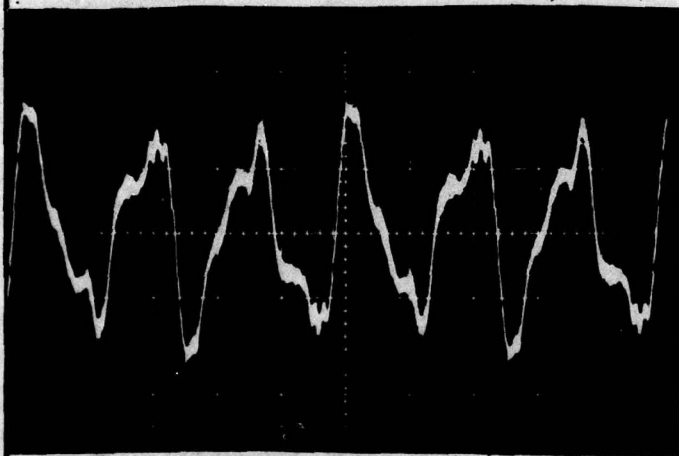


400 HZ SINGLE
PHASE, THREE WIRE

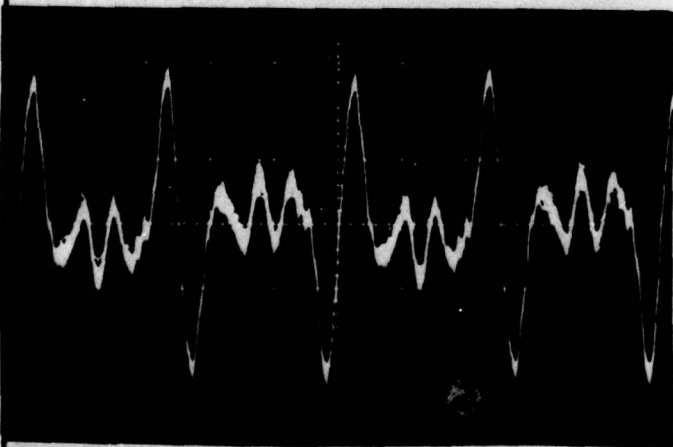
NO LOAD

↓ 0.5V/DIV

↔ 500 μSEC/DIV



10KW, PF=0.8



10KW, PF=1.0

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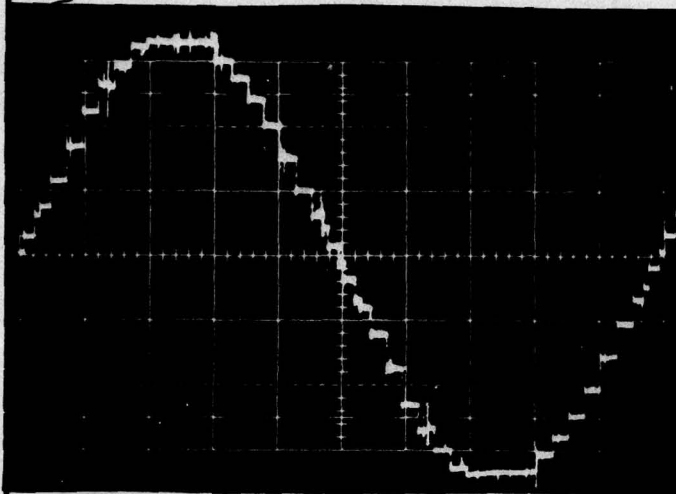
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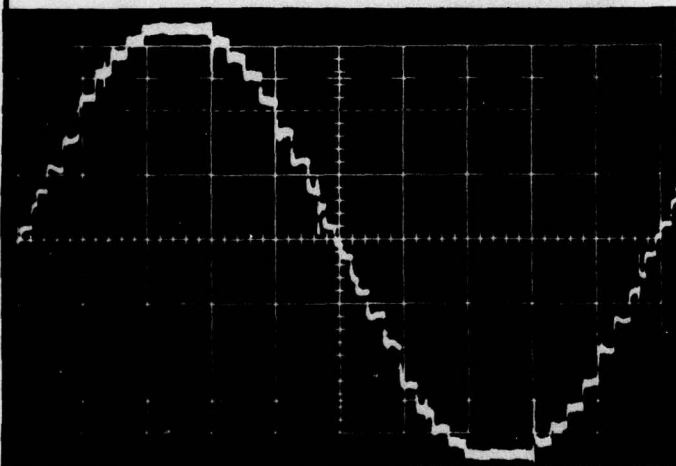
60 HZ SINGLE
PHASE, TWO WIRE

NO LOAD

THD = 4.7%

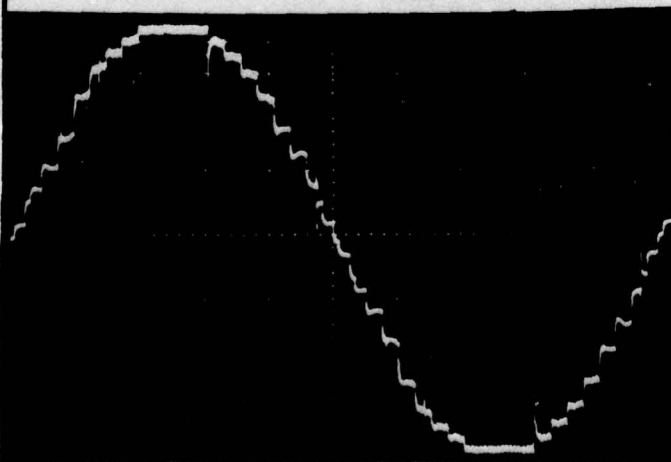
50V/DIV.

(NOTE: NO CAPACITANCE IN
OUTPUT FILTER FOR
THESE 60 HZ, 1 ϕ , 2 WIRE
OR 3 WIRE TESTS)



6.6 KW, PF = 1.0

THD = 4.4%



10 KW, PF = 1.0

THD = 4.48%

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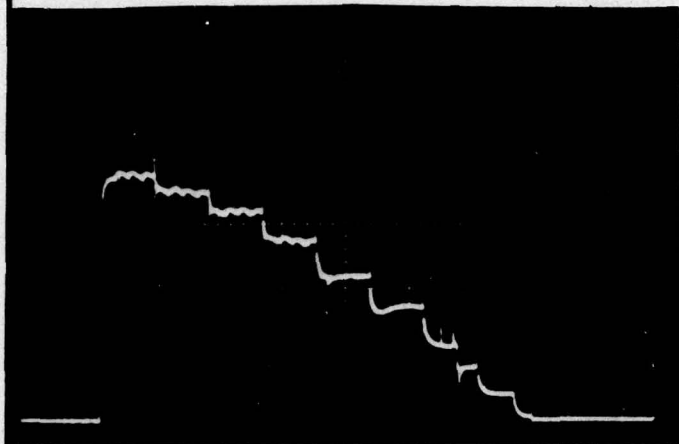
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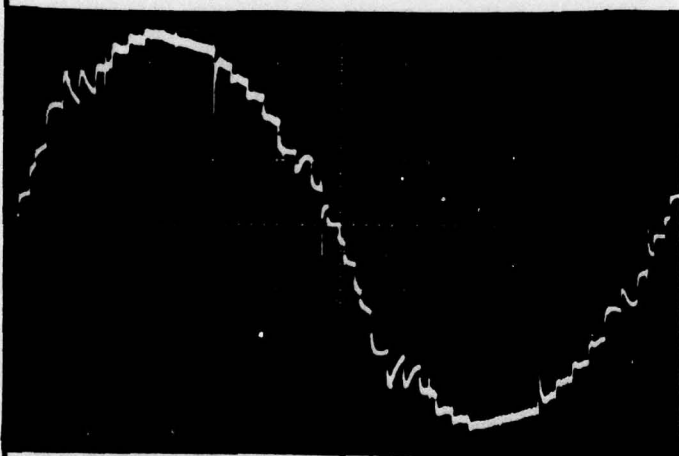


60 HZ SINGLE
PHASE, TWO WIRE

STEP TRANSISTOR
CURRENT

↓ 20 A./DIV. ↔ 500 μSEC/DIV.

10 KW, PF = 1.0

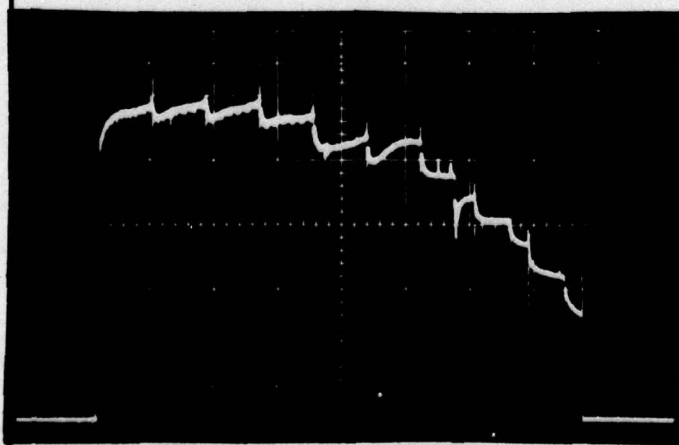


8.5 KW, PF = 0.8

OUTPUT VOLTAGE = 110 V. RMS

LOAD CURRENT = 111 A. RMS

THD = 6.78%



STEP TRANSISTOR
CURRENT FOR
ABOVE LOAD.

↓ 20 A./DIV.

↔ 500 μSEC/DIV.
(MAXIMUM ALLOWABLE
CURRENT)

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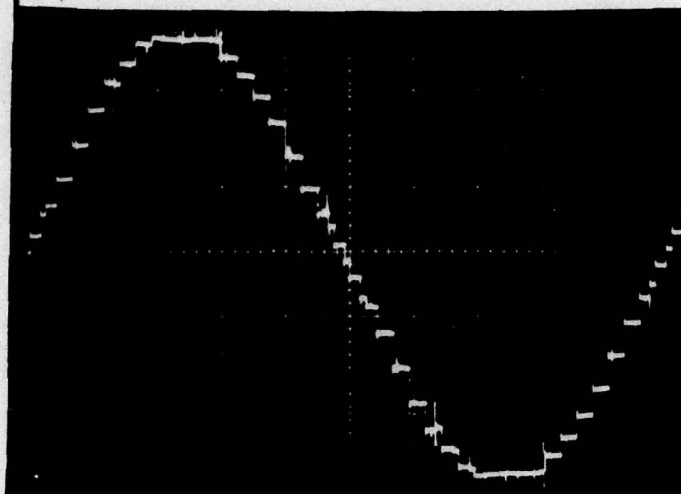
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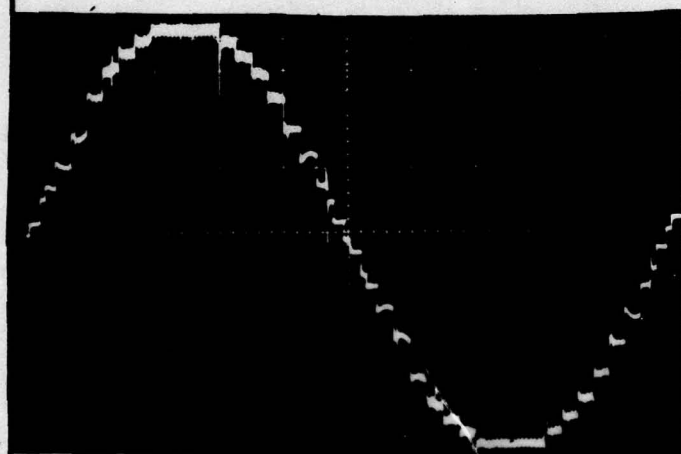


60 HZ SINGLE
PHASE, THREE WIRE

NO LOAD

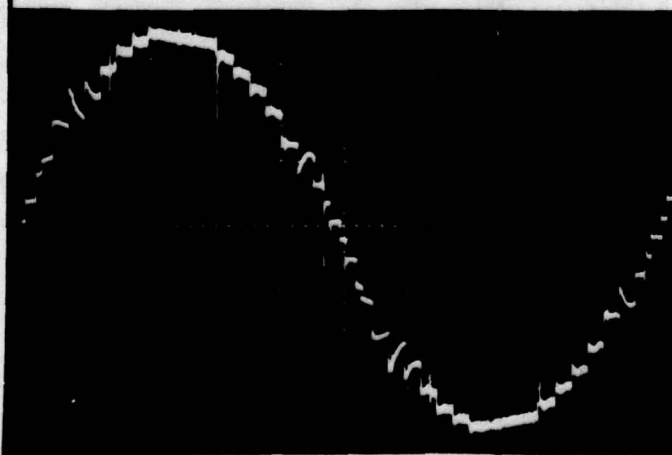
LINE-TO-NEUTRAL
VOLTAGE THD = 4.7%

↕ 50V/DIV.



10 KW, PF = 1.0

THD = 5%



8.5 KW, PF = 0.8

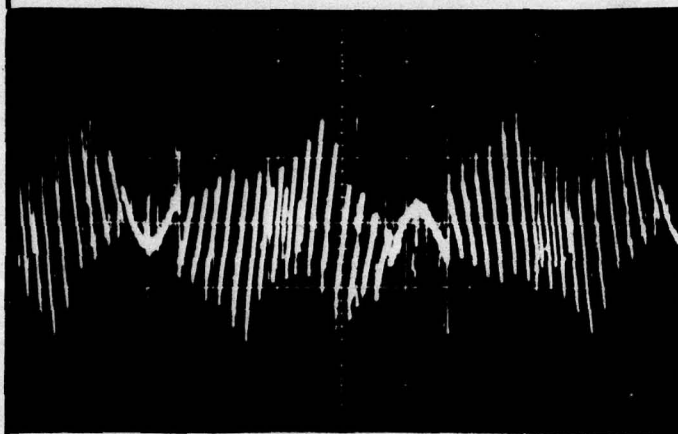
OUTPUT VOLTAGE = 110V RMS
CURRENT = 55 A RMS / LEG

THD = 7.2%

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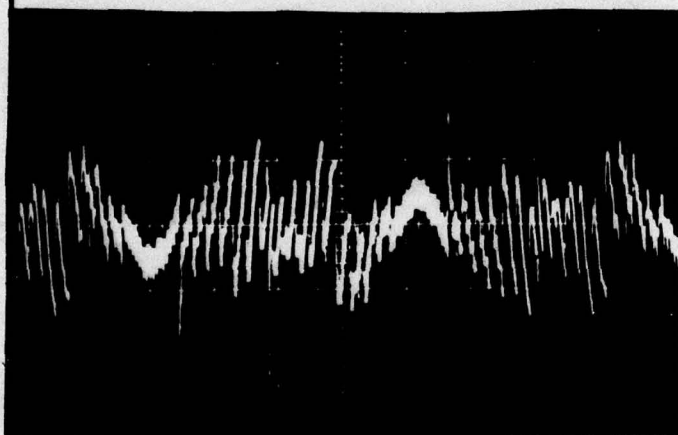
DEVIATION FACTOR



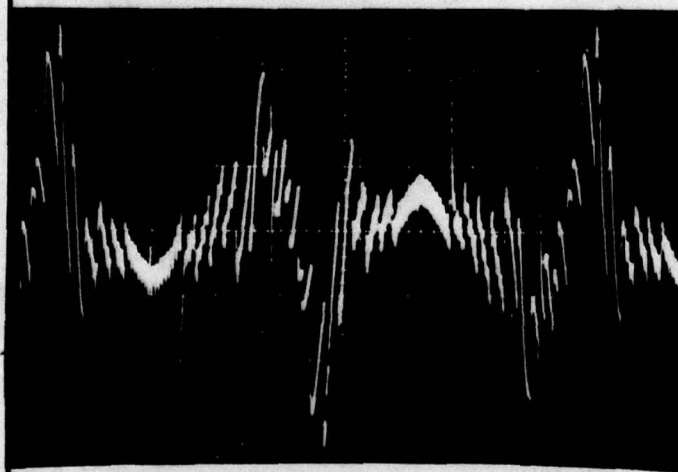
60 HZ SINGLE
PHASE, TWO WIRE

(NOTE: NO CAPACITANCE
IN OUTPUT FILTER)

NO LOAD
↕ 10V/DIV. ← 2ms/DIV.



10 KW, PF=1.0



8.5 KW, PF=0.8

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MEASUREMENTS OF INDIVIDUAL HARMONICS

400HZ, SINGLE PHASE, TWO WIRE

10KW, PF= 0.8

HARMONIC NUMBER	FREQUENCY KHZ	PERCENT OF FUND.
1	0.4	100%
3	1.2	4.0
5	2.0	2.4
7	2.8	2.0
11	4.4	0.85
13	5.2	0.23
29	11.6	0.16
31	12.4	0.10
35	14.0	0.15
37	14.8	0.19
41	16.4	0.25

COMPUTED THD = 5.17%

MEASUREMENTS MADE WITH HP WAVE ANALYZER 302A

TOTAL HARMONIC DEVIATION (THD) IS DEFINED

$$AS = 100 \sqrt{\frac{E_w^2}{E_f^2} - 1}$$

WHERE E_w = RMS VALUE OF STEPPED WAVEFORM

E_f = RMS VALUE OF WAVEFORM FUNDAMENTAL

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MEASUREMENTS OF INDIVIDUAL HARMONICS

60HZ, SINGLE PHASE, THREE WIRE. NO LOAD

HARMONIC NUMBER	FREQUENCY HZ	PERCENT OF FUND.	HARMONIC NUMBER	FREQUENCY HZ	PERCENT FUND.
1	60	100	53	3180	—
3	180	1.3	55	3300	0.10
5	300	1.5	57	3420	—
7	420	0.42	59	3540	—
9	540	0.15	61	3660	—
11	660	1.0	63	3780	—
13	780	0.17	65	3900	—
15	900	—	67	4020	—
17	1020	0.2	69	4140	—
19	1140	0.2	71	4260	—
21	1260	—	73	4380	—
23	1380	0.11	75	4500	—
25	1500	0.17	77	4620	0.64
27	1620	—	79	4740	1.2
29	1740	0.28	81	4860	—
31	1860	0.23	83	4980	—
33	1980	—	85	5100	0.6
35	2100	0.16	87	5220	—
37	2220	1.36	91	5460	0.3
39	2340	—	119	7140	0.8
41	2460	2.35	121	7260	0.8
43	2580	1.30	157	9420	0.3
45	2700	—			
47	2820	0.1			
49	2940	0.17			
51	3060	—			

NO CAPACITORS IN OUTPUT FILTER

COMPUTED THD = 4.27%

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MEASUREMENTS OF INDIVIDUAL HARMONICS

60HZ, SINGLE PHASE, THREE WIRE, 85 KW PF=0.8

HARMONIC NUMBER	FREQUENCY HZ	PERCENT OF FUND.	HARMONIC NUMBER	FREQUENCY HZ	PERCENT OF FUND.
1	60	100	65	3900	0.36
3	180	4.2	67	4020	0.24
5	300	2.2	71	4260	0.3
7	420	2.5	73	4380	0.3
9	540	1.2	77	4620	1.1
11	660	0.61	79	4740	1.5
13	780	1.45	83	4980	0.45
15	900	0.5	85	5100	0.3
17	1020	0.8	89	5340	0.3
19	1140	0.64	95	5700	0.2
21	1260	0.4	97	5820	0.24
23	1380	0.4	99	5940	0.25
25	1500	0.57	101	6060	0.2
29	1740	0.46	105	6300	0.24
31	1860	0.3	107	6420	0.3
33	1980	0.2	111	6660	0.26
35	2100	0.3	117	6960	0.3
37	2220	1.5	119	7140	1.1
39	2340	0.43	121	7260	0.72
41	2460	2.5	125	7500	0.25
43	2580	1.2	131	7860	0.18
45	2700	0.3	133	7980	0.2
47	2820	0.3	137	8220	0.25
49	2940	0.35	139	8340	0.2
51	3060	0.12	143	8580	0.25
53	3180	0.32	145	8700	0.25
55	3300	0.2	149	8940	0.24
59	3540	0.26	151	9060	0.24
61	3660	0.25	153	9180	0.5

COMPUTED THD= 7.26%

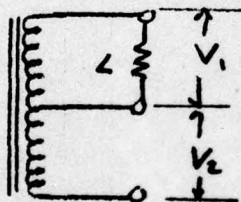
DELCO ELECTRONICS GENERAL MOTORS CORPORATION		REPORT NO.	PAGE	JOB NO. SINGLE PHASE	PAGE 26
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DC VOLTAGE COMPONENT

SINGLE PHASE, TWO WIRE

FREQUENCY HZ	V V.RMS	I A.RMS	PF	LOAD KW	VOL MV.
400	120.2	0	—	0	+16
400	120.2	83.5	1.0	10	+4
400	120.3	104	0.8	10	+5
60	120.12	0	—	0	-13
60	120.5	84	1.0	10	-10
60	120.1	N.A.	0.8	8.5	-5

SINGLE PHASE, THREE WIRE VOLTAGE BALANCE



1φ OUTPUT TRANSFORMER.

V ₁ V.RMS	V ₂ V.RMS	LOAD KW, PF=0.8
121.9	121.9	—
121.6	122.2	2.2
121.3	122.4	4.4
121.4	122.4	5.8
120.2	120.2	—
120.2	121.4	2.2
120.3	122.4	4.4
120.4	123.0	5.8

} 400 HZ

} 60 HZ

SINGLE
PHASE

27

TITLE

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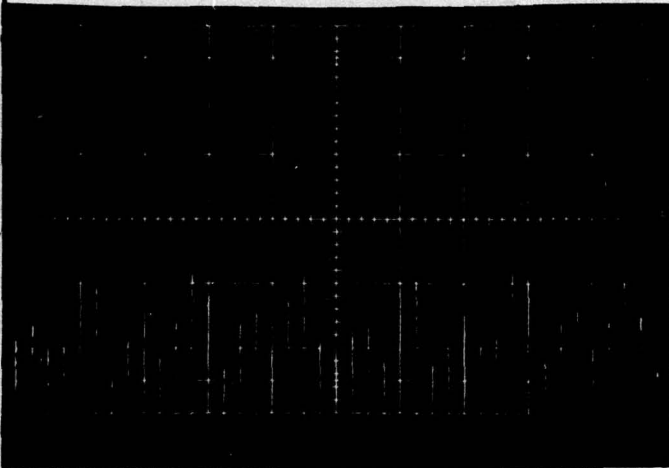
DATE

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3.24.1.7 VOLTAGE MODULATION

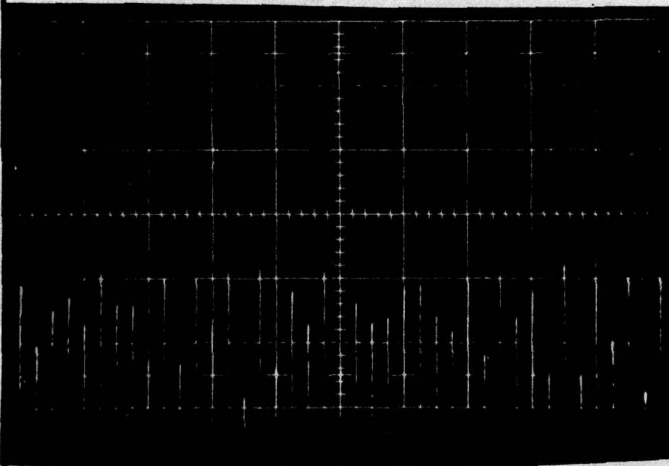


400 HZ SINGLE
PHASE, TWO WIRE

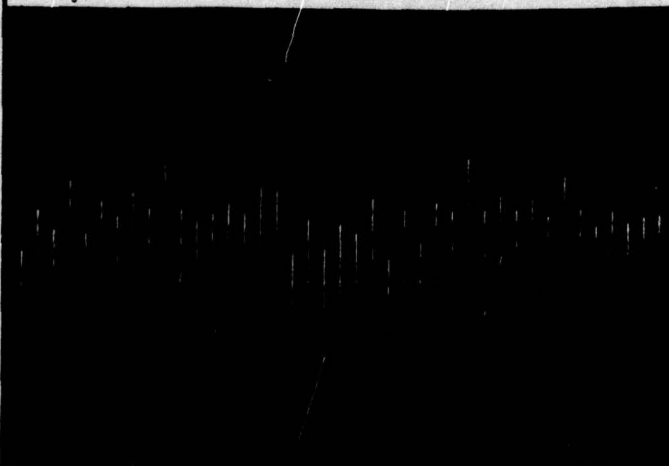
NO LOAD

↑ 2V / DIV.

↔ 10ms / DIV.



10 KW, PF=1.0



10 KW, PF=0.8

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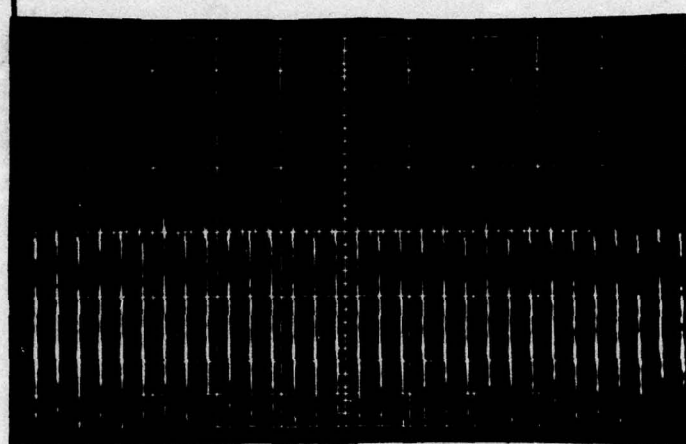
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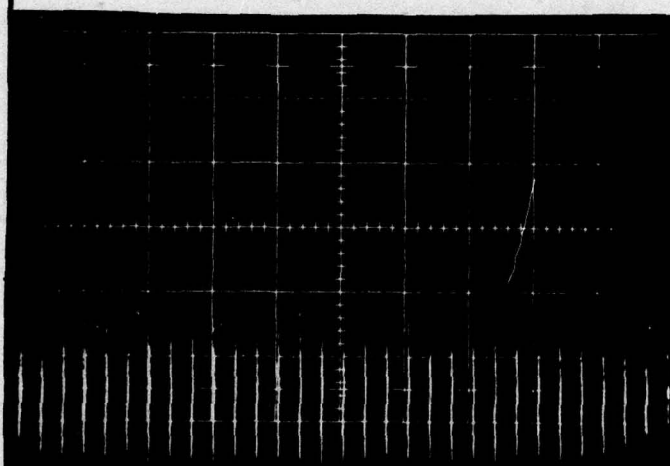


60HZ SINGLE
PHASE, TWO WIRE

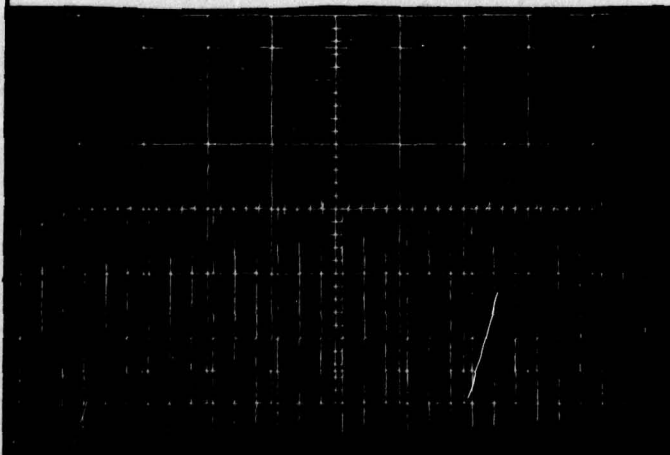
NO LOAD

↑ 2V/DIV.

← 50ms/DIV.



10KW, PF=1.0

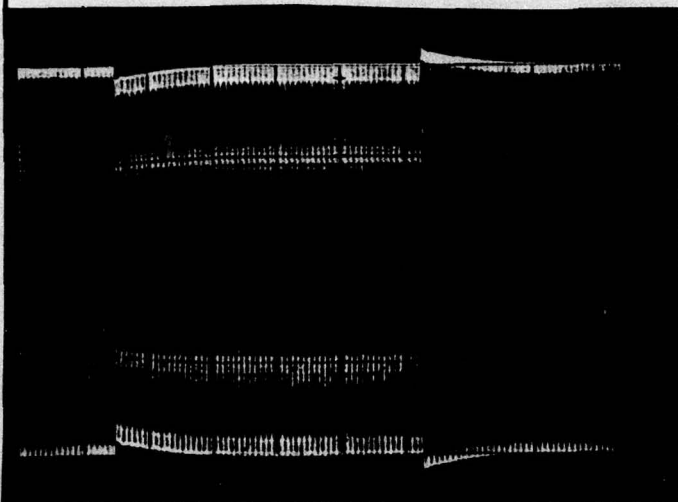


8.5KW, PF=0.8

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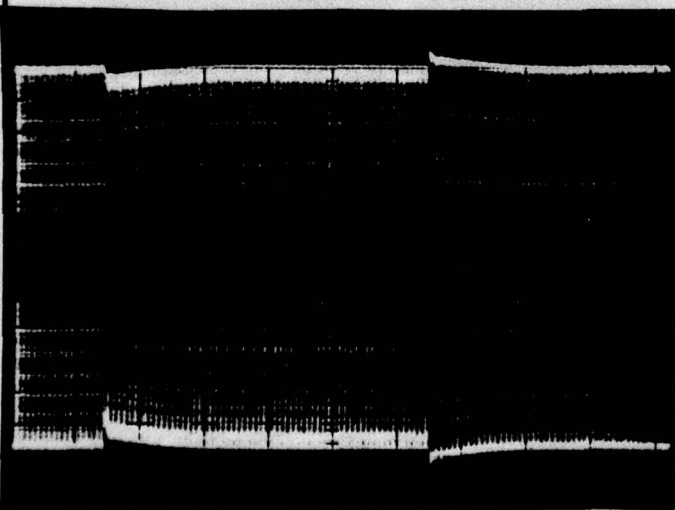
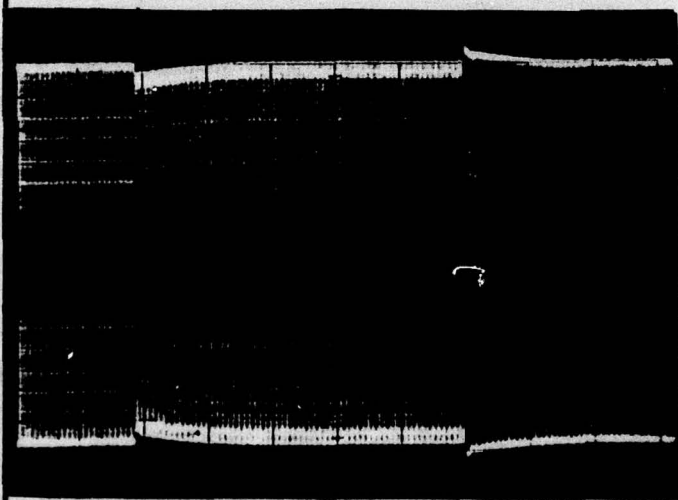
3. 24.1.12 TRANSIENT VOLTAGE PERFORMANCE



400 HZ SINGLE
PHASE, TWO WIRE

1/4 LOAD, PF=0.8

← 0.2 SEC/DIV.



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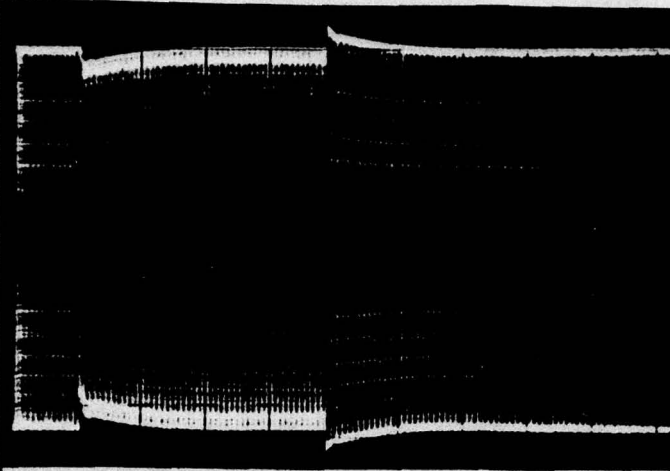
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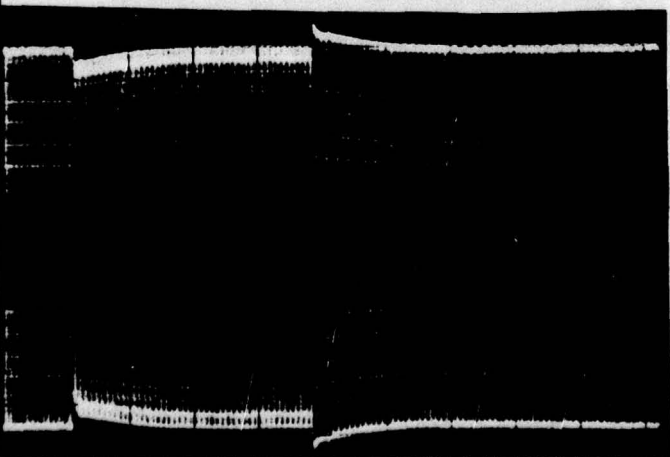
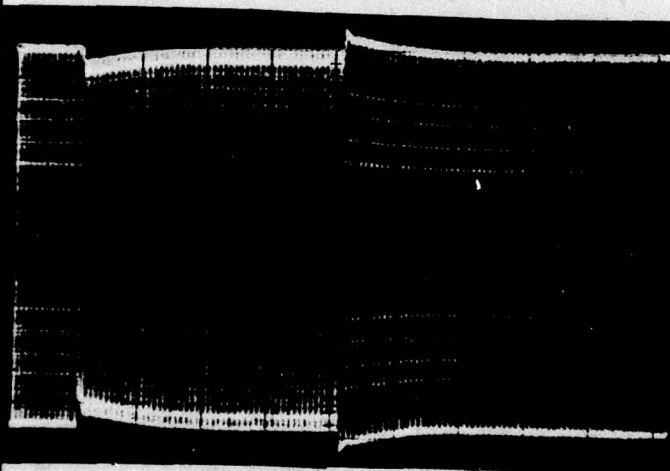
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400 HZ SINGLE
PHASE, TWO WIRE

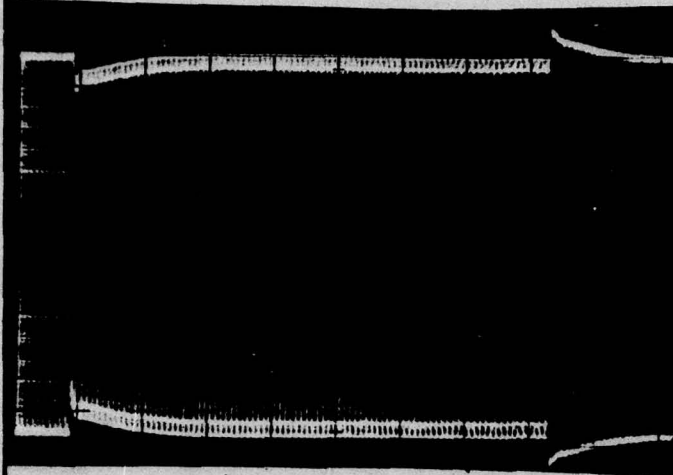
1/2 LOAD, PF = 0.8

←→ 0.2 SEC/DIV.



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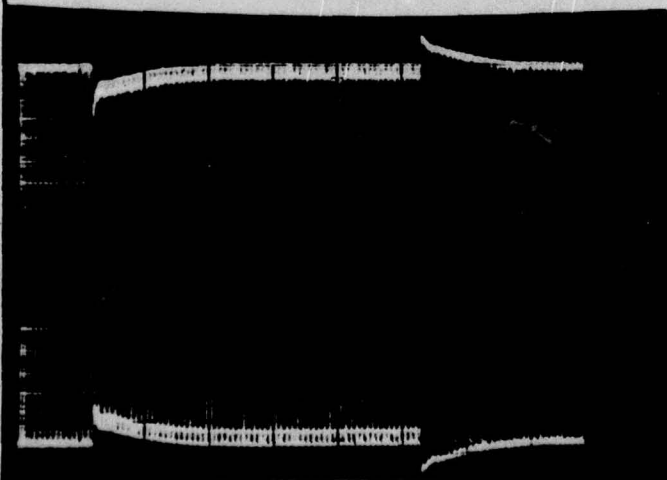
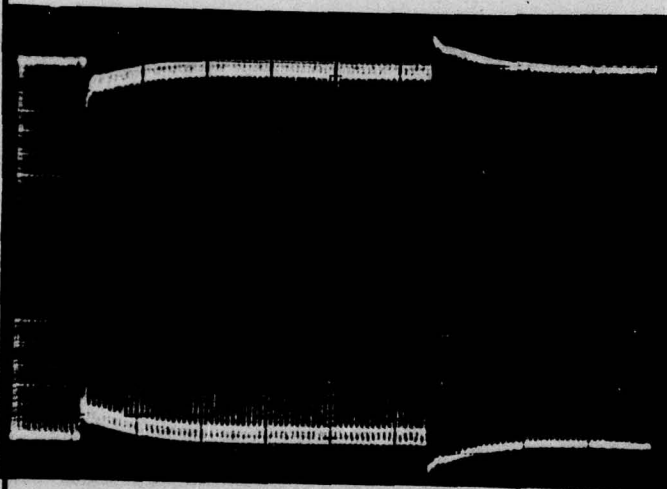
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400 HZ SINGLE
PHASE, TWO WIRE

3/4 LOAD, PF=0.8

← 0.2 SEC/DIV.



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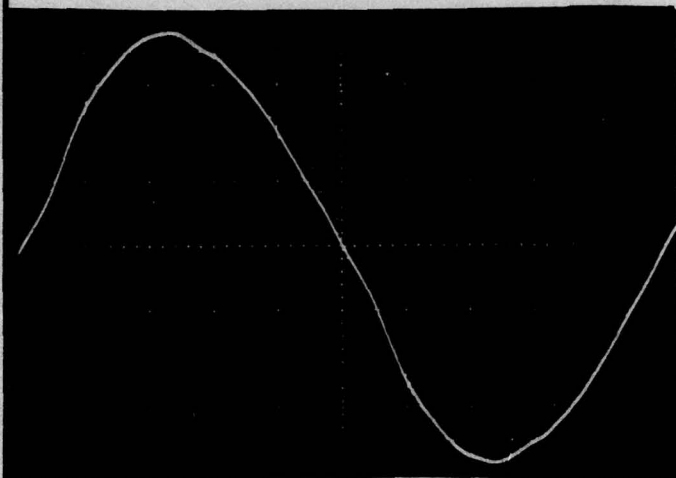
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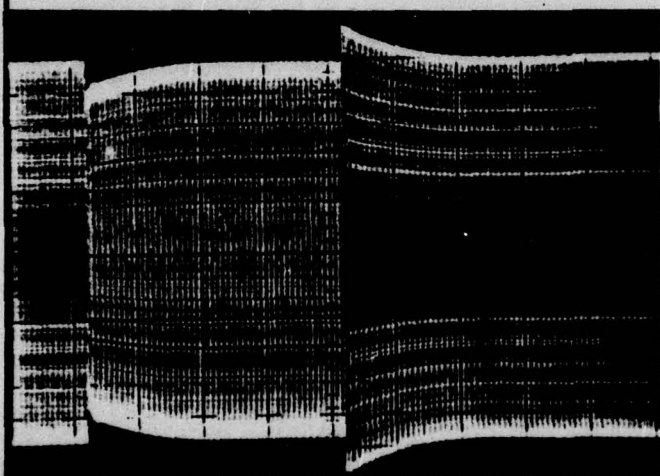
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400 HZ SINGLE
PHASE, TWO WIRE

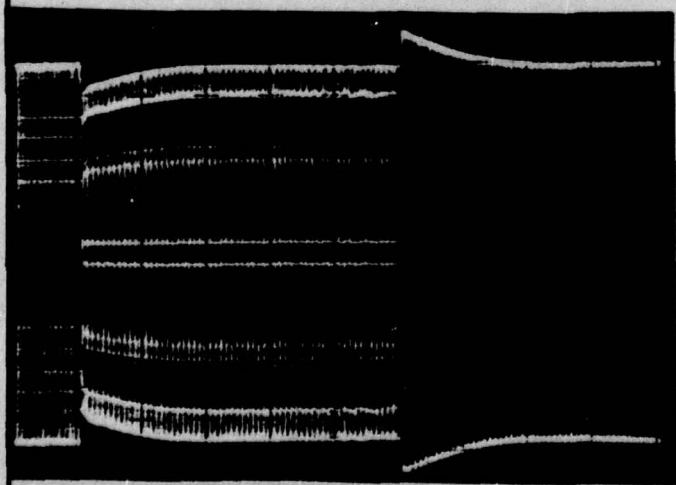
10 KW, PF = 0.8

THD = 4.3%



FULL LOAD, PF = 0.8

← 0.2 SEC / DIV.



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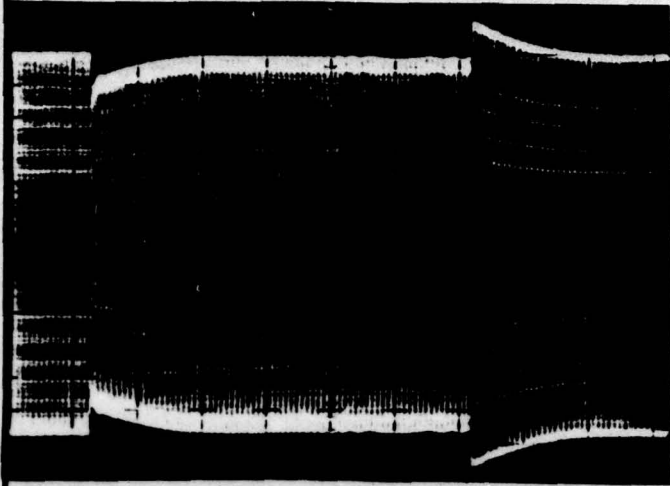
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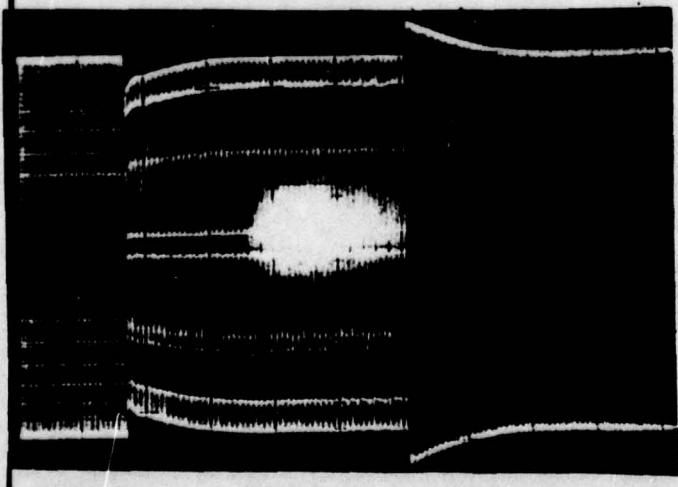
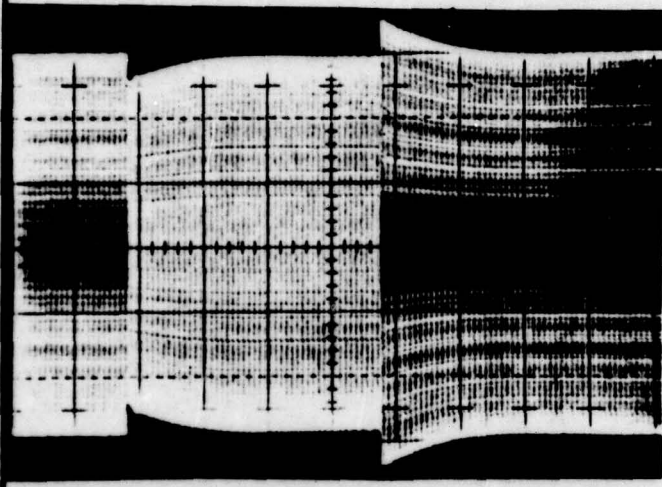
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400 HZ SINGLE
PHASE, TWO WIRE

FULL LOAD, PF=0.8

← 0.2 SEC/DIV.



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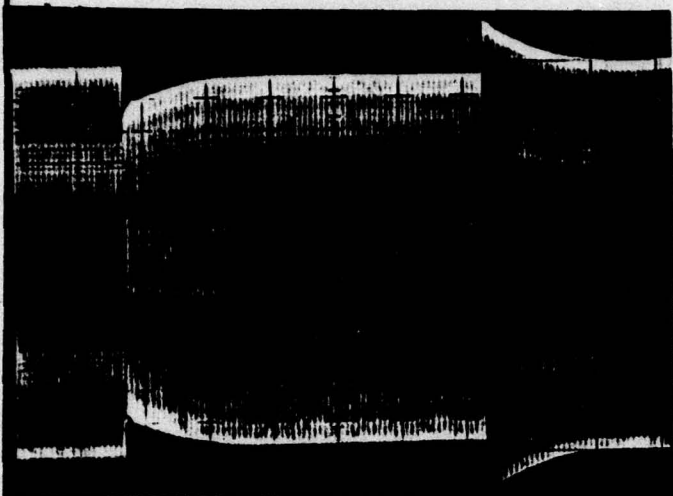
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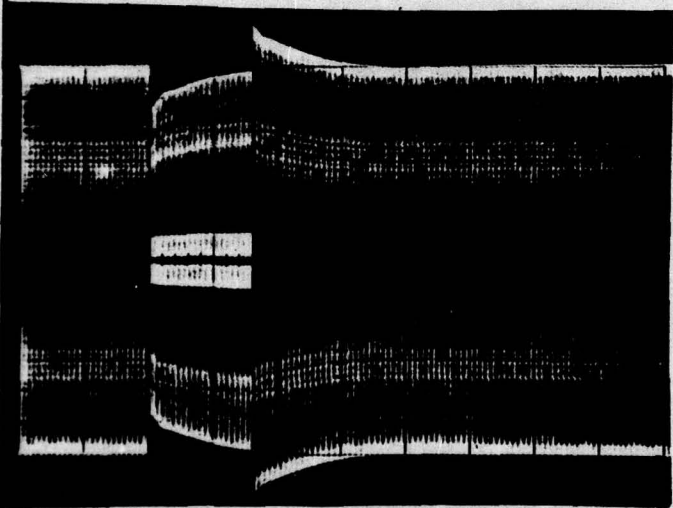
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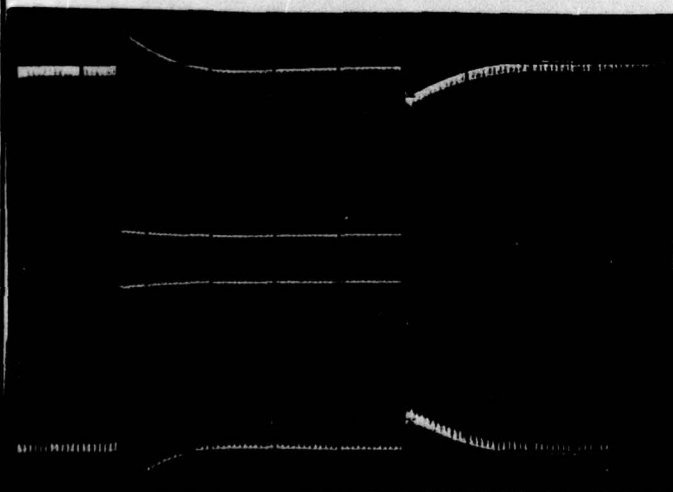
400 HZ SINGLE
PHASE, TWO WIRE

1.25 LOAD, $PF = 0.8$

0.2 SEC/DIV.



2 P.U., $PF = 0.4$



2 P.U., $PF = 0.1$

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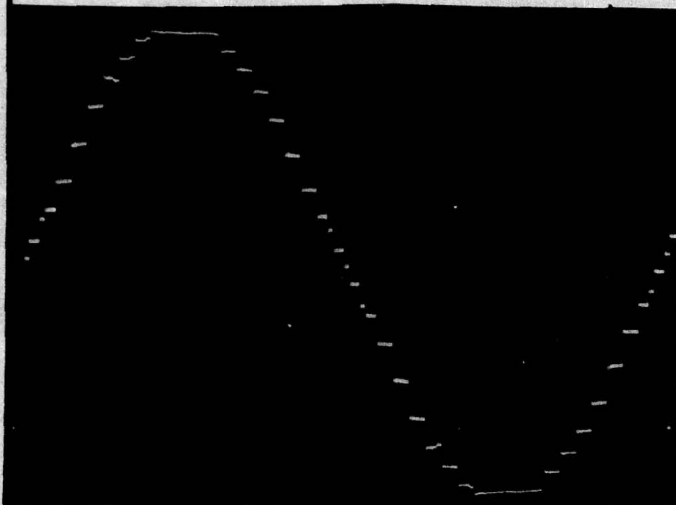
CORRY

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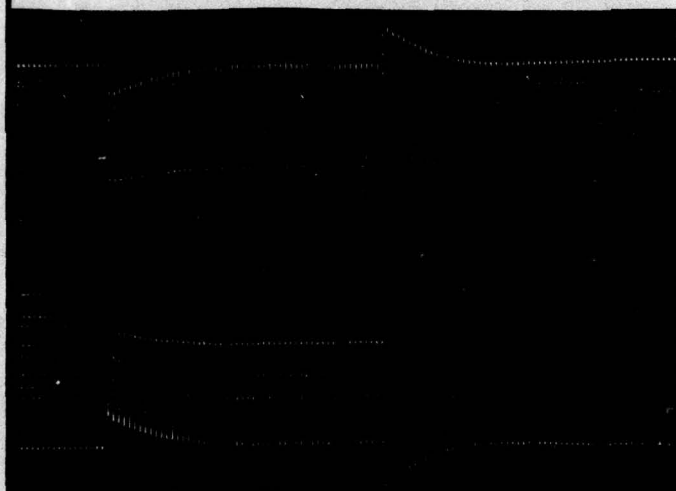


60 HZ SINGLE
PHASE, TWO WIRE

NO LOAD

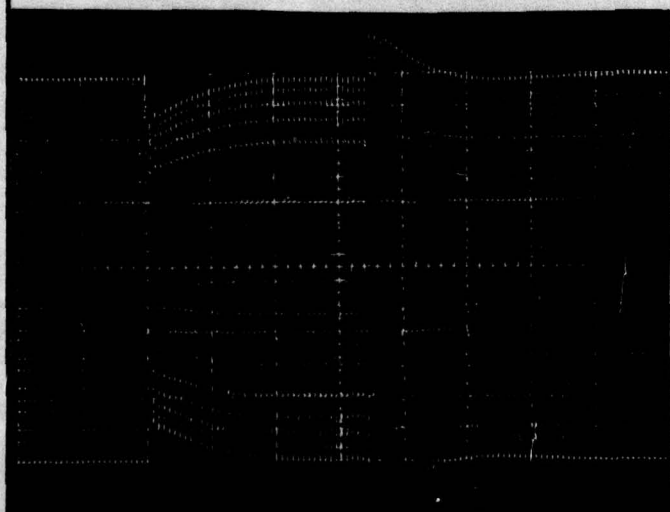
THD = 4.7%

(NOTE: NO CAPACITANCE
IN OUTPUT OF CONVERTER)



1/4 LOAD, PF = 0.8

↔ 0.2 SEC/DIV.



1/2 LOAD, PF = 1.0

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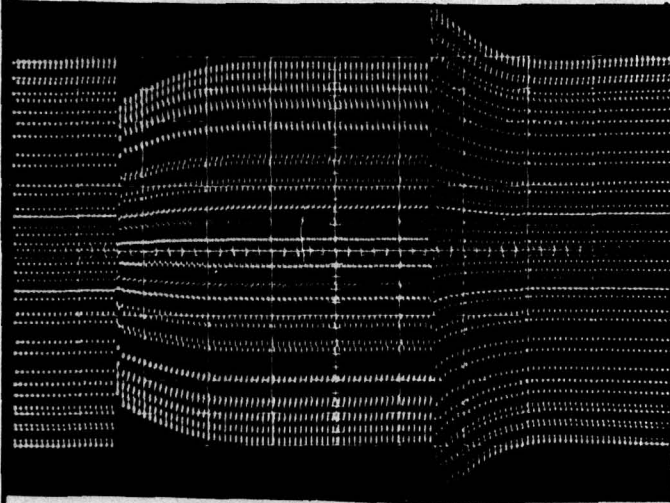
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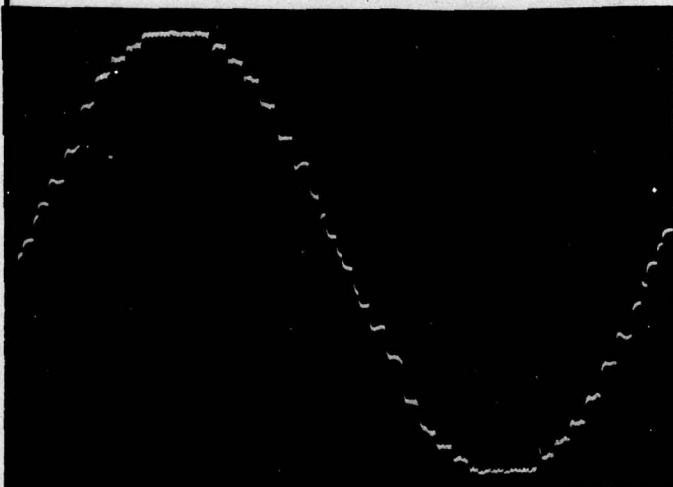
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60 HZ SINGLE
PHASE, TWO WIRE

3/4 LOAD, PF=1.0

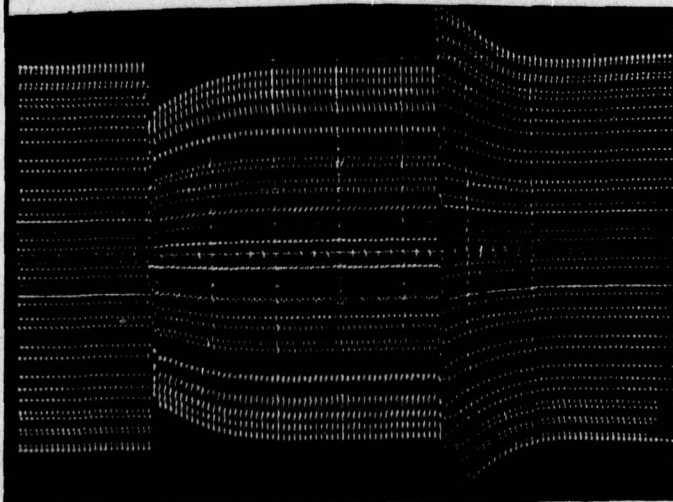
↔ 0.2 SEC / DIV.



10 KW, PF=1.0

THD= 4.3%

↓ 50 V / DIV.



FULL LOAD, PF=1.0

(NOTE: NO CAPACITANCE IN
CONVERTER OUTPUT)

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3.24.3 EFFICIENCY

CIRCUIT DESCRIPTION	FREQ. HZ	INPUT POWER WATTS	OUTPUT POWER WATTS	P.F.	LOSSES WATTS	EFF. %
P.F. (CORRECTED)						
60MFD 6-FL	400	13013	11040	0.8	1973	84.8
	400	13170	11040	1.0	2130	83.8
	400	3888	2231	1.0	1675	57.4
↓	400	1615	NOLoad	—	1615	—

DOES NOT INCLUDE RECTIFIER OR OTHER FIXED LOSSES,

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10 KW FREQUENCY CONVERTER

Test Results Items 0001, 0003, 0004.

Three Phase Performance

CDRL Item AC02

Modification Nos. P0003 & P0006

Contract No. DAAK02-72-C-0210

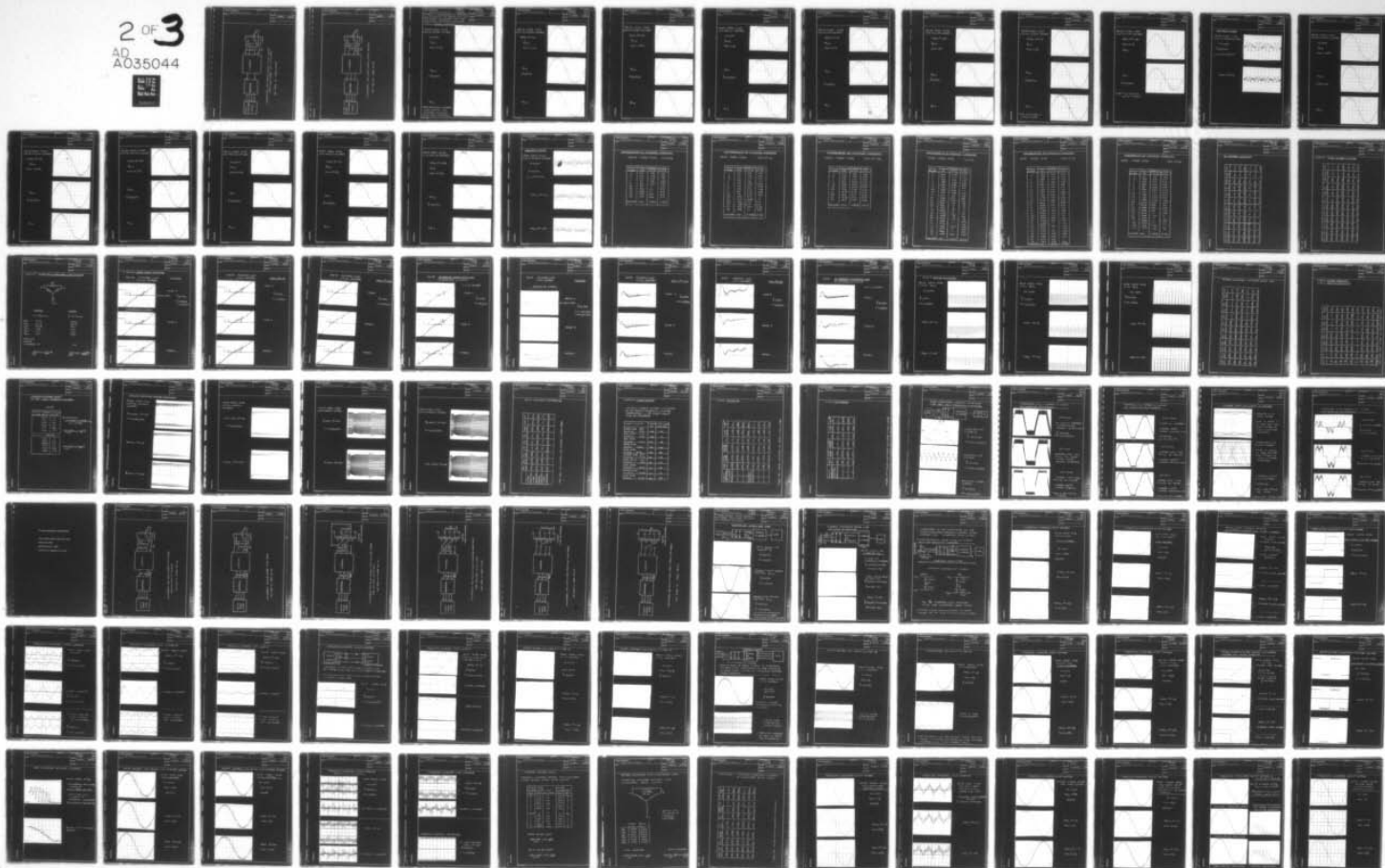
AD-A035 044

GENERAL MOTORS CORP GOLETA CALIF DELCO ELECTRONICS DIV F/G 9/5
FREQUENCY CONVERTER PORTABLE, ALTERNATING CURRENT MULTIFREQUENC--ETC(U)
MAY 74 T CORRY, BARRETT DAAK02-72-C-0210
R74-40-VOL-2 NL

UNCLASSIFIED

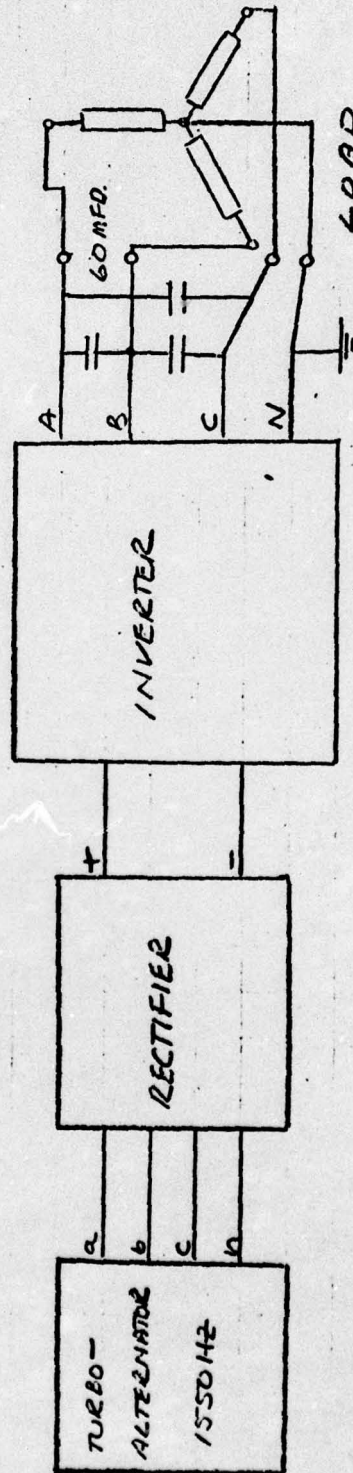
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CONNECTIONS FOR 400 HZ, THREE PHASE POWER
 (STEP TRANSISTORS NOT CONNECTED)

FOR DATA ON PAGES 34-85

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GENERAL MOTORS CORPORATION

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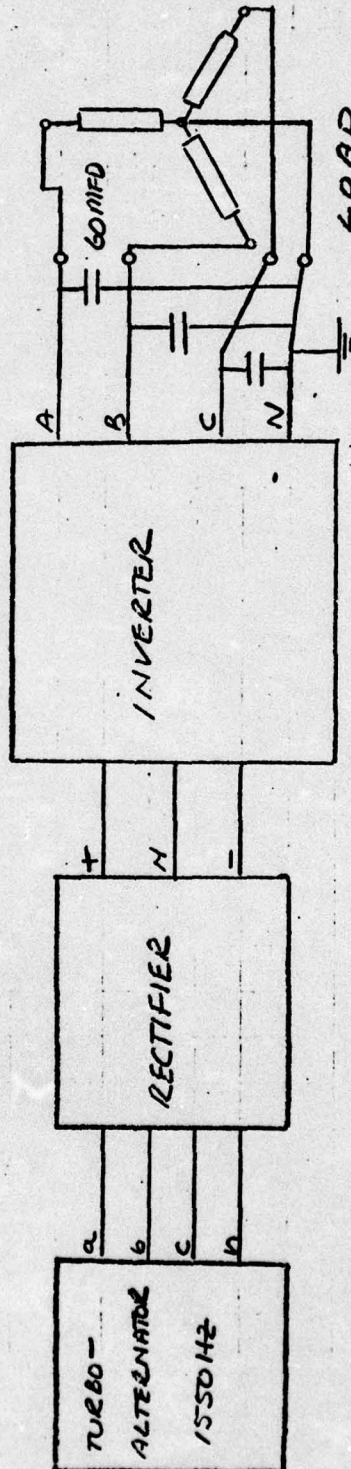
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CONNECTIONS FOR 60HZ, THREE PHASE POWER

FOR DATA ON PAGES 34-85

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TITLE TESTS IN ACCORDANCE WITH ATTACHMENT
NO. 3 OF CONTRACT NO. DAAK02-72-C-0210
MODIFICATION NOS. P0003 & P0006 AND
MIL-STD-705B. ITEMS 0001, 0003, 0004

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CORY

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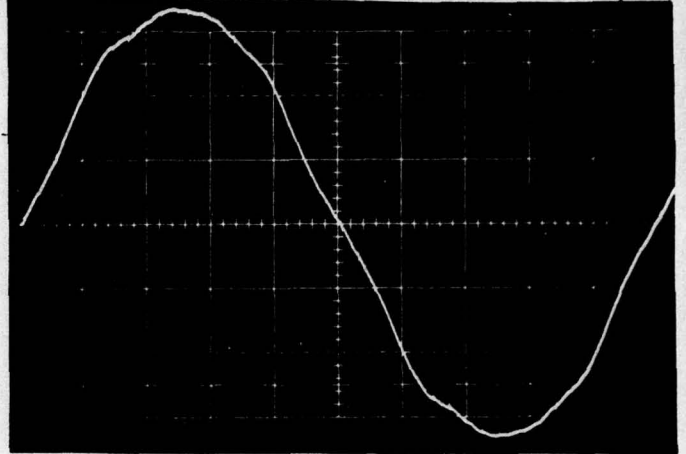
3.24.1.3 VOLTAGE WAVEFORM

400HZ THREE PHASE
LINE-TO-NEUTRAL VOLTAGES

NO LOAD

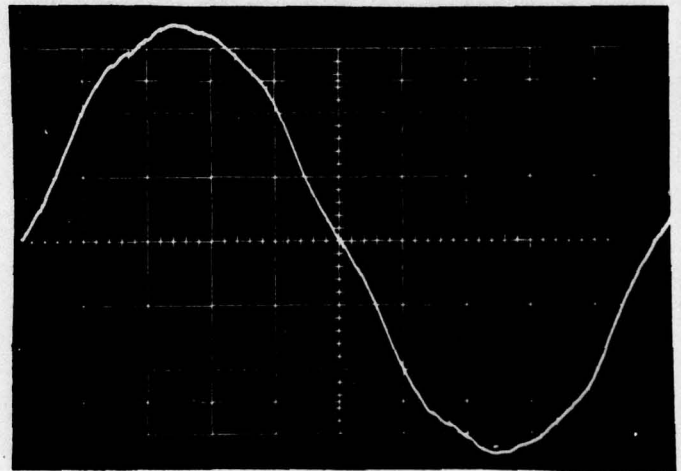
V_{A-N}

THD = 3.2%

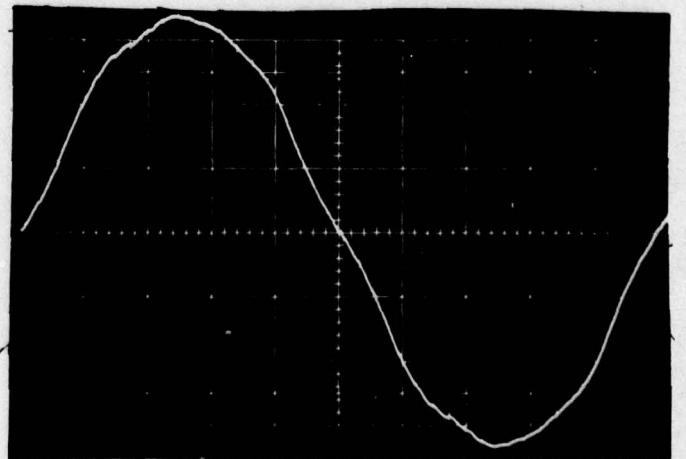


V_{B-N}

↑ 50V / DIV.



V_{C-N}



(NOTE: FREQUENCY CONVERTER
INPUT NEUTRAL NOT
CONNECTED FOR 400HZ,
THREE PHASE OPERATION)

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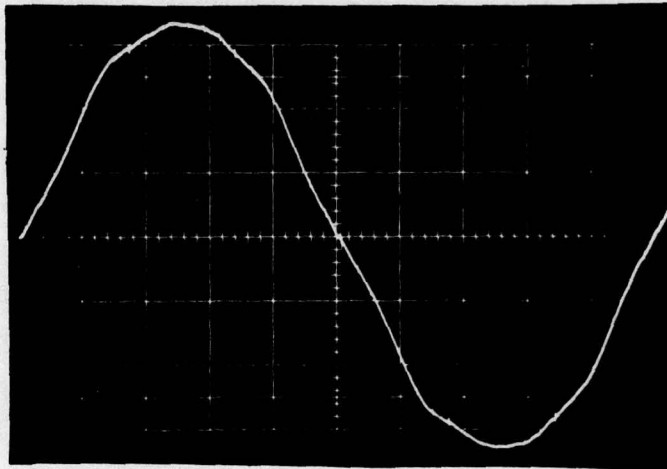
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400 HZ THREE PHASE
LINE-TO-NEUTRAL VOLTAGES

11KW, PF=1.0

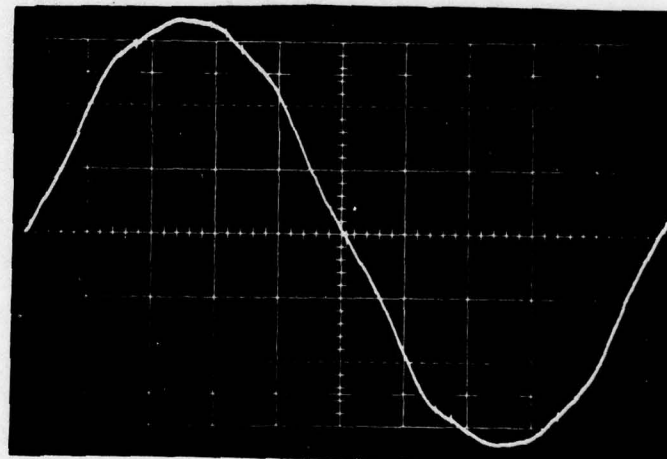
V_{A-N}

THD= 3.13%

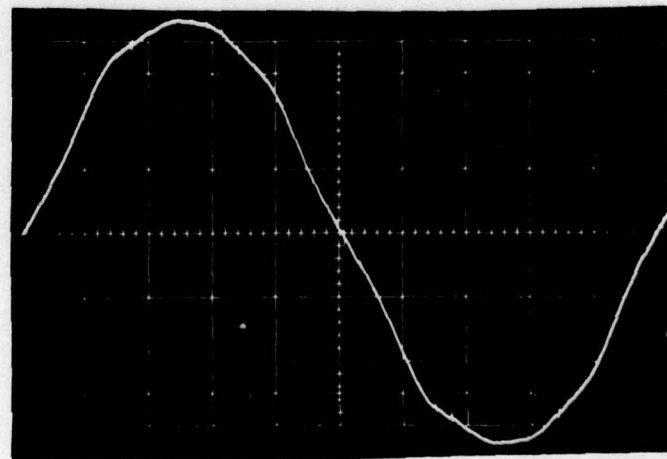


V_{B-N}

↑ 50V/DIV.



V_{C-N}



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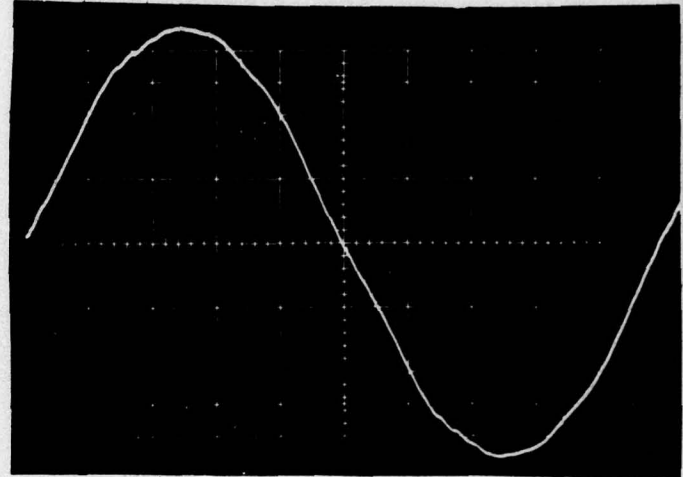
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400 HZ THREE PHASE
LINE-TO-NEUTRAL VOLTAGES

11KW, PF=0.8

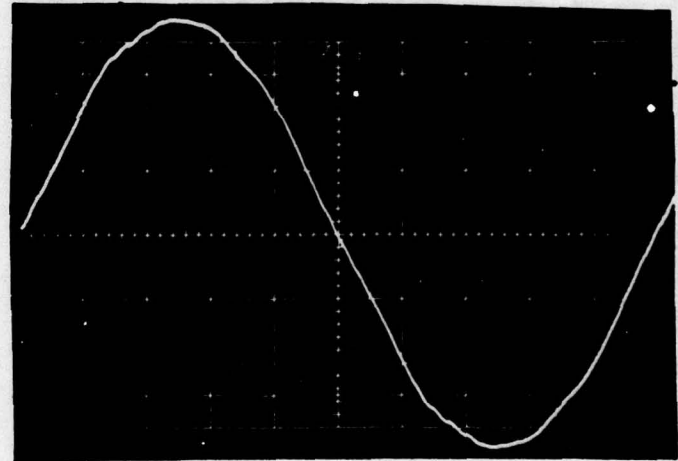
V_{A-N}

THD=1.84%

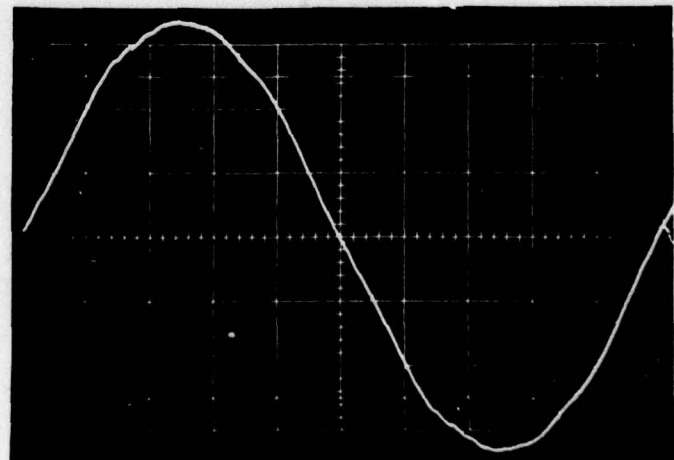


V_{B-N}

↓ 50V/DIV.



V_{C-N}



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THREE
PHASE

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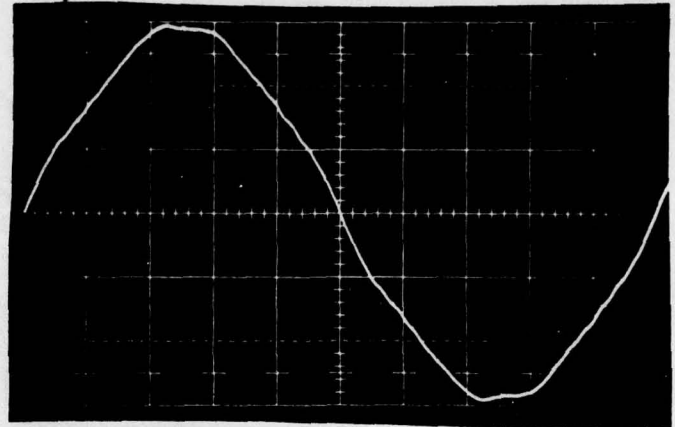
APPROVED

400HZ THREE PHASE
LINE-TO-LINE VOLTAGES

NO LOAD

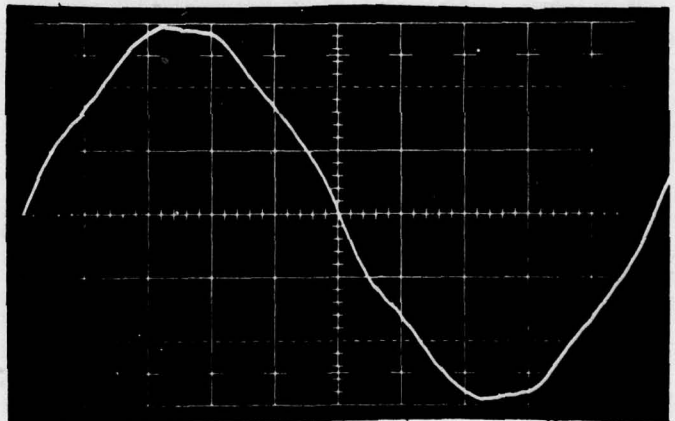
V_{A-B}

THD = 3.2%

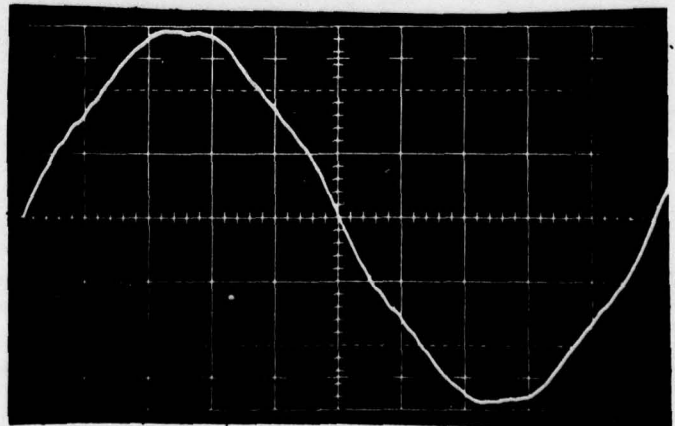


V_{B-C}

↑ 100 V/DIV.



V_{C-A}



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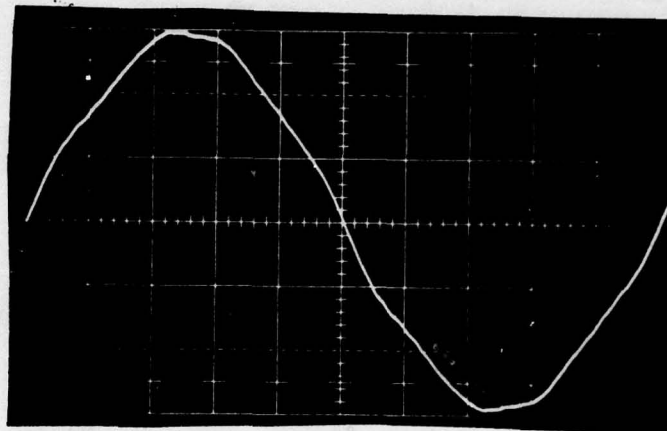
APPROVED

400 HZ THREE PHASE
LINE-TO-LINE VOLTAGES

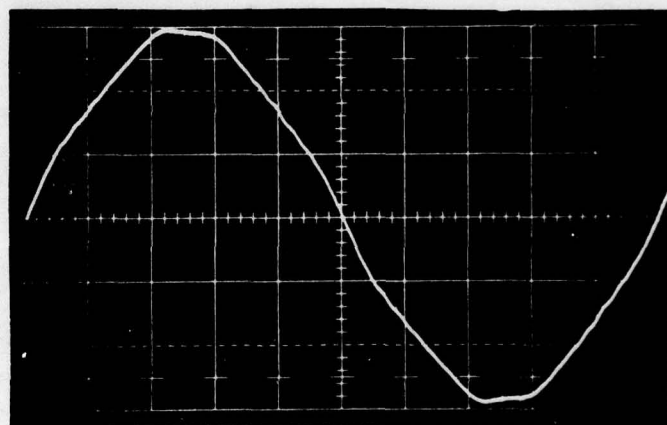
11KW, PF=1.0

V_{A-B}

THD=3.13%

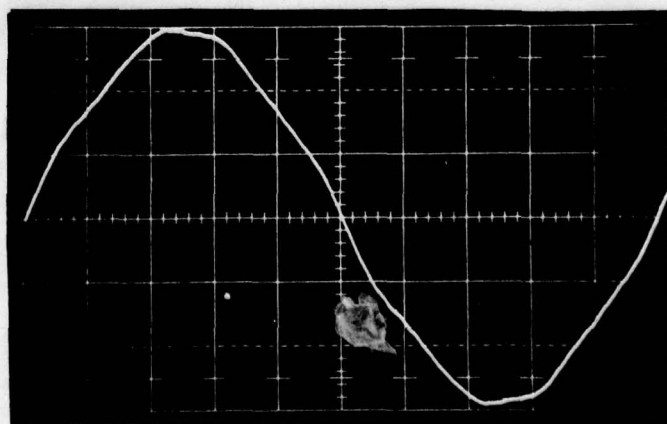


V_{B-C}



↕ 100V/DIV.

V_{C-A}



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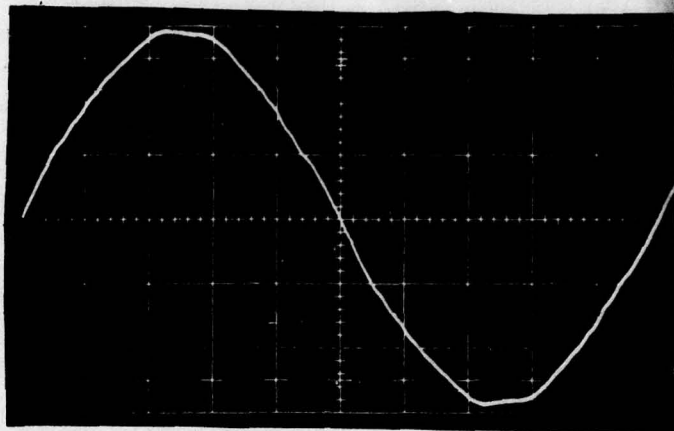
APPROVED

400 HZ THREE PHASE
LINE-TO-LINE VOLTAGES

11KW, PF=0.8

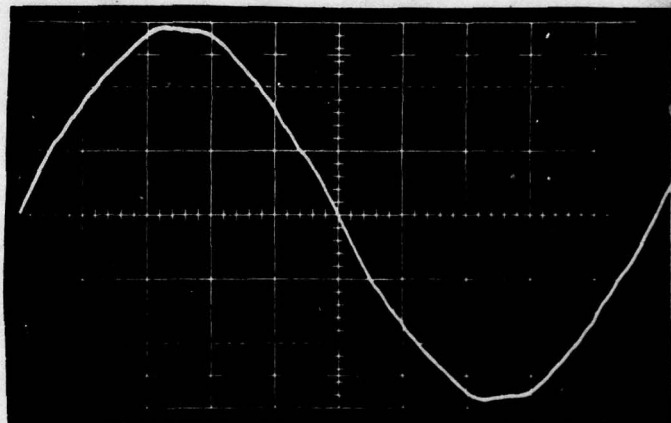
V_{A-B}

THD= 1.8%

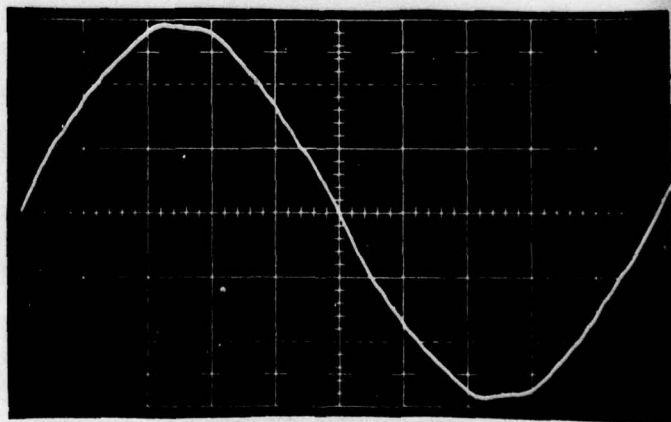


V_{B-C}

100V/DIV.



V_{C-A}



DISTRIBUTION:

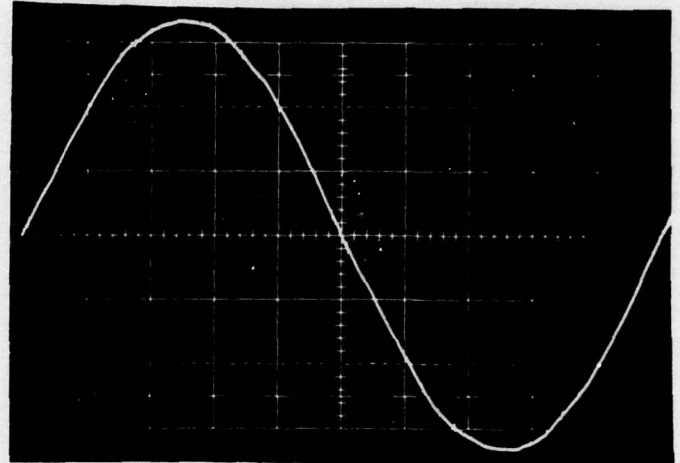
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400 HZ THREE PHASE
LINE-TO-NEUTRAL VOLTAGES

13 KW, PF = 0.8

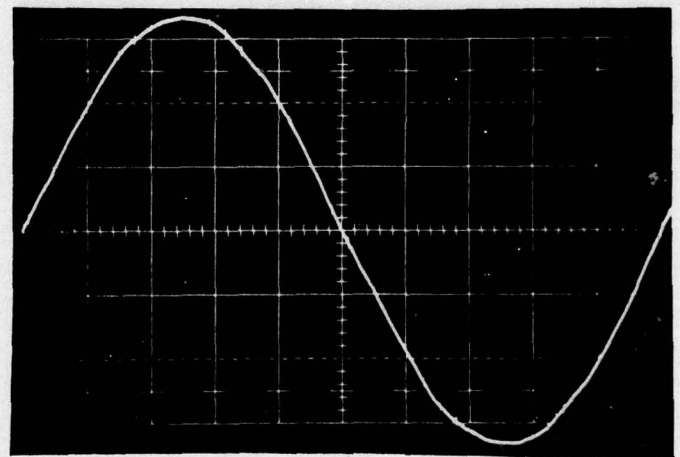
V_{A-N}

THD = 1.2%

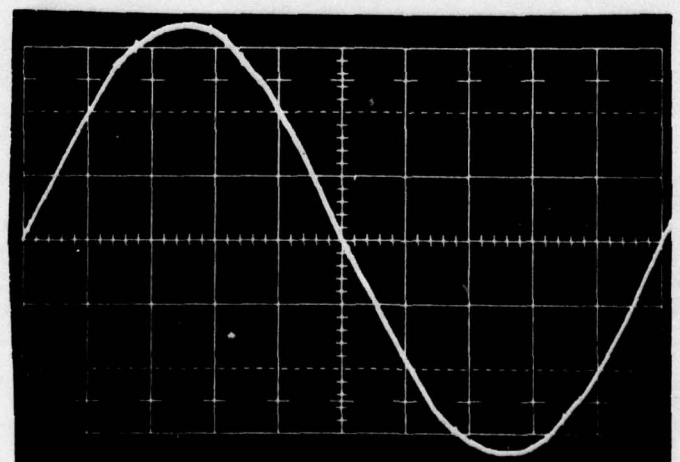


V_{B-N}

↑ 50V/DIV.



V_{C-N}



(NOTE: 7 μH ADDED TO
OUTPUT FILTER)

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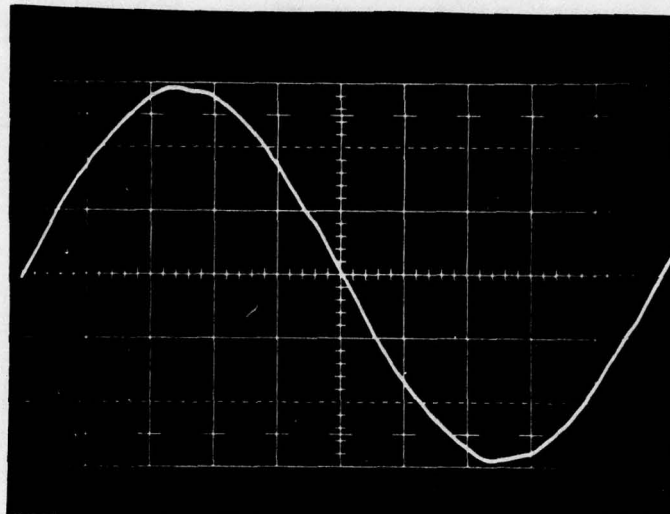
APPROVED

400 HZ THREE PHASE
LINE-TO-LINE VOLTAGES

13KW, PF = 0.8

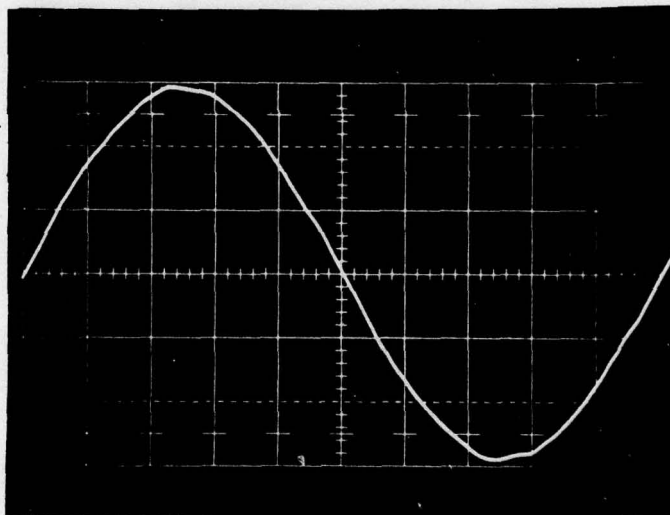
THD = 1.1%

V_{A-B}



V_{B-C}

↑ 100V/DIV.



(NOTE: 7μH ADDED TO
OUTPUT FILTER)

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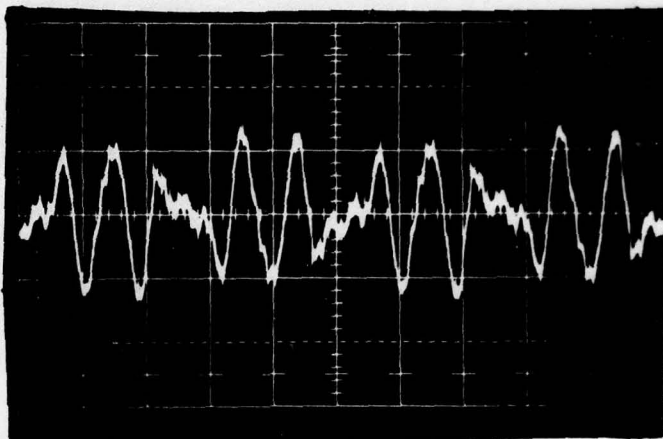
DEVIATION FACTOR

400 HZ THREE PHASE
LINE-TO-NEUTRAL VOLTAGES

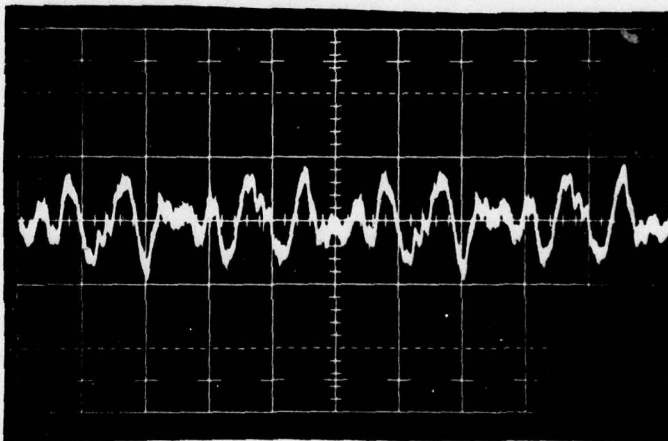
NO LOAD

↓ 0.5V/DIV.

↔ 500 μSEC/DIV.



11KW, PF=0.8



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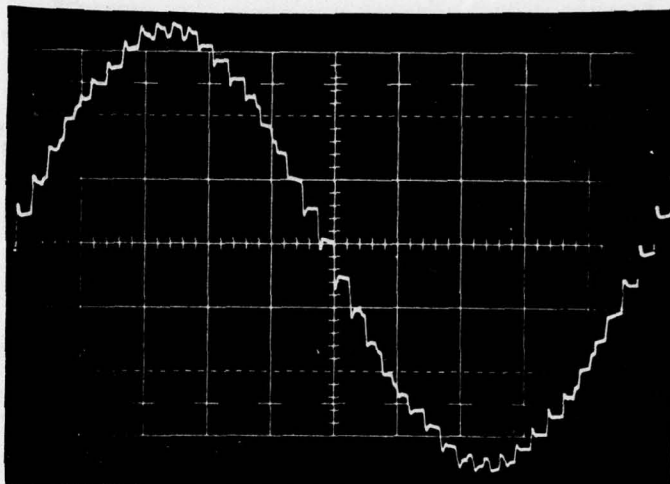
APPROVED

60 HZ THREE PHASE
LINE-TO-NEUTRAL VOLTAGES

NO LOAD

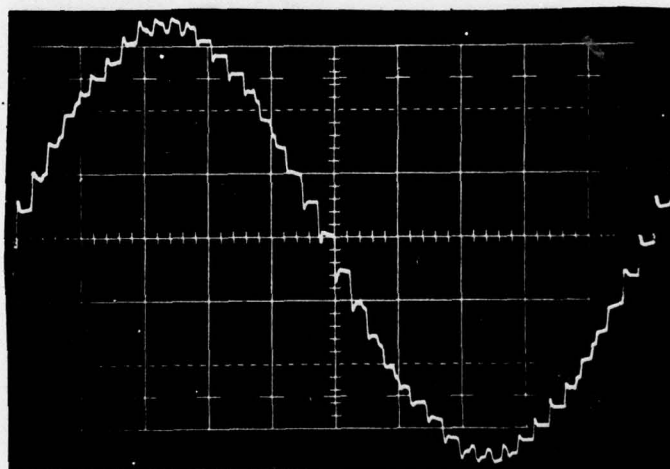
V_{A-N}

THD = 4.28%

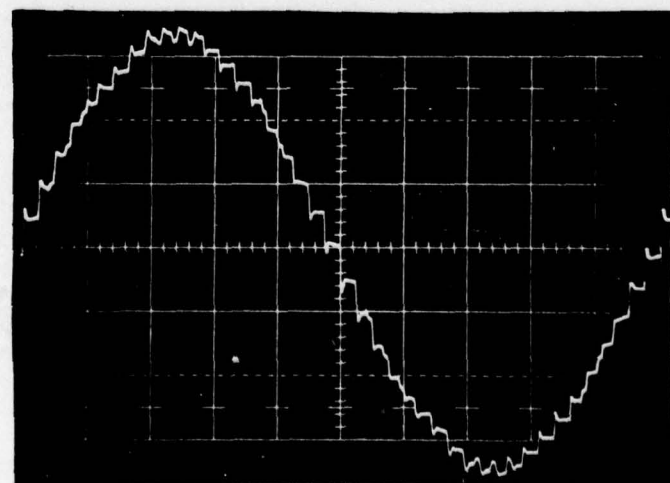


V_{B-N}

↑ 50V/DIV.



V_{C-N}



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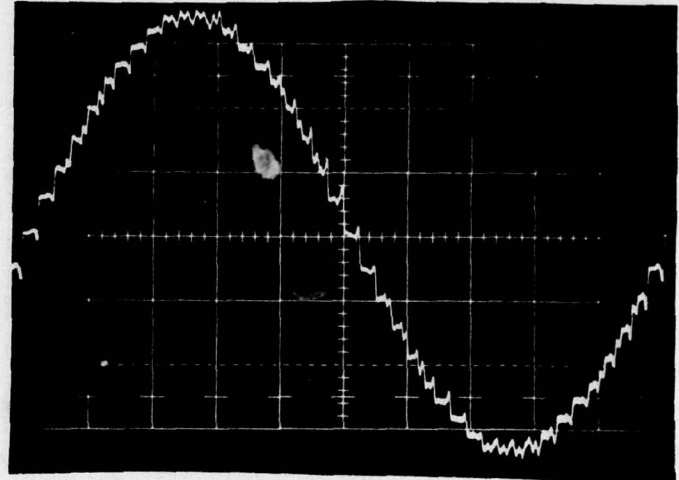
APPROVED

60 HZ THREE PHASE
LINE-TO-NEUTRAL VOLTAGES

11KW, PF=1.0

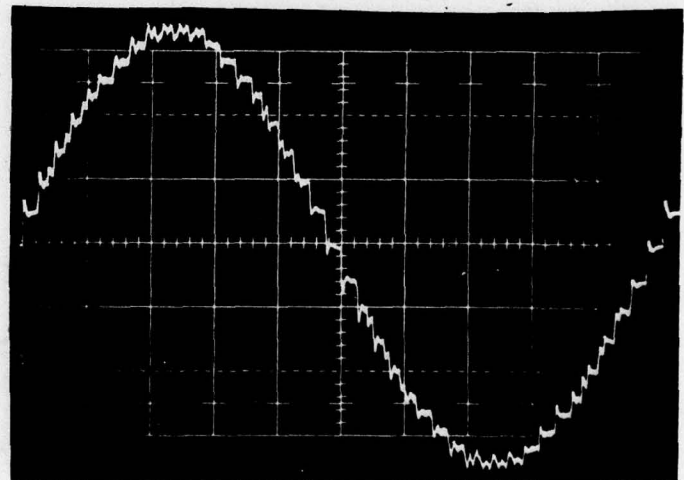
V_{A-N}

THD = 4.18%

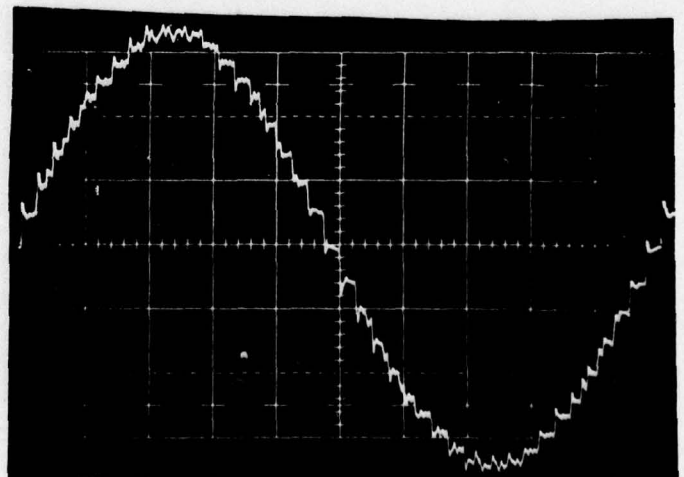


V_{B-N}

↕ 50V/DIV.



V_{C-N}



DISTRIBUTION:

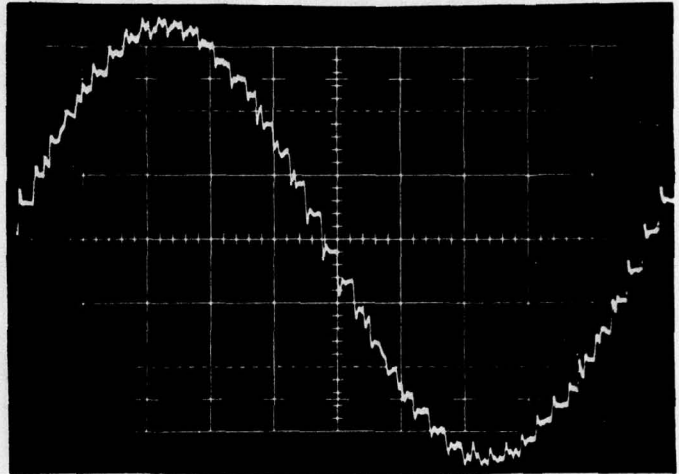
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60 HZ THREE PHASE
LINE-TO-NEUTRAL VOLTAGES

11KW, PF=0.8

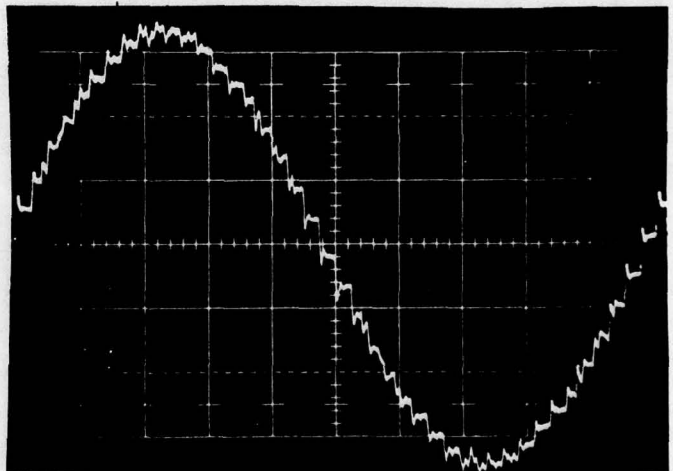
V_{A-N}

THD=4.33%

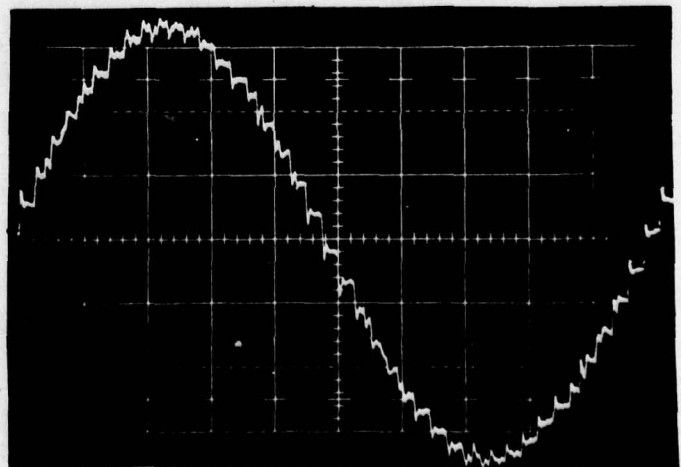


V_{B-N}

↓ 50V/DIV.



V_{C-N}



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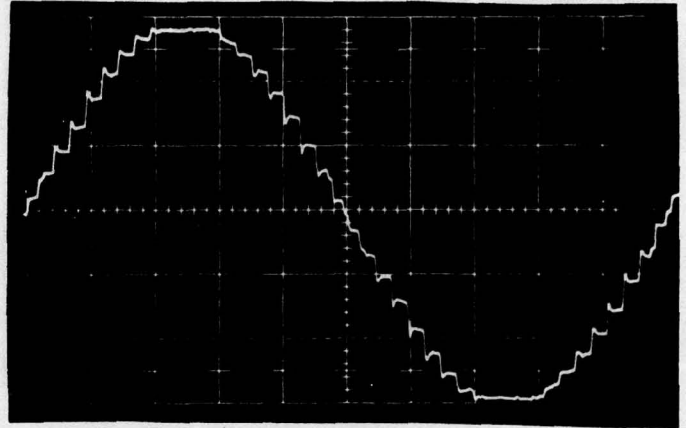
APPROVED

60 HZ THREE PHASE
LINE-TO-LINE VOLTAGES

NO LOAD

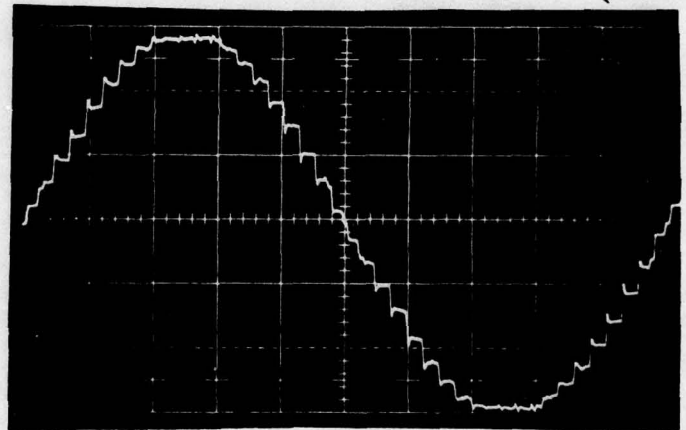
V_{A-B}

THD = 4.25%

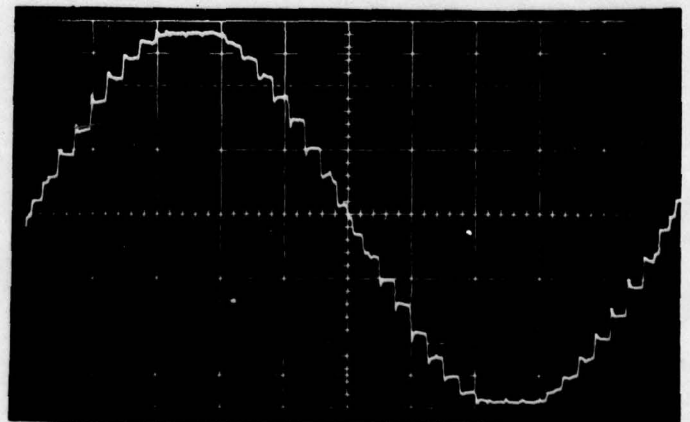


V_{B-C}

↑ 100V/DIV.



V_{C-A}



DISTRIBUTION:

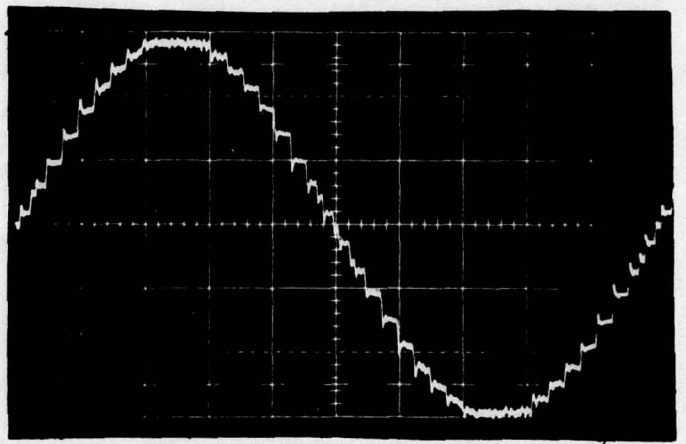
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60 HZ THREE PHASE
LINE-TO-LINE VOLTAGES

11 KW, PF=1.0

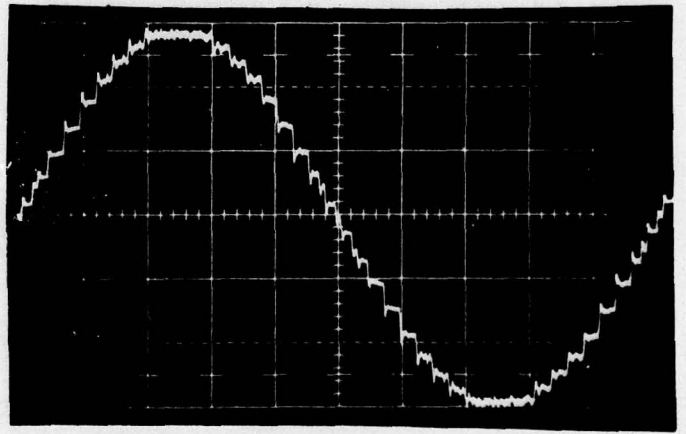
V_{A-B}

THD= 4.15%

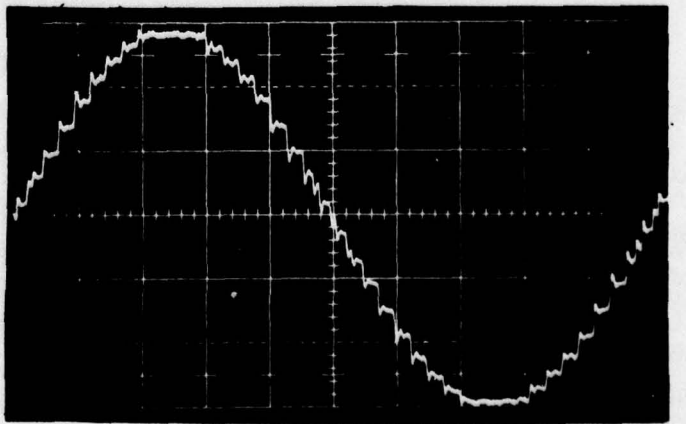


V_{B-C}

↑ 100V/DIV.



V_{C-A}



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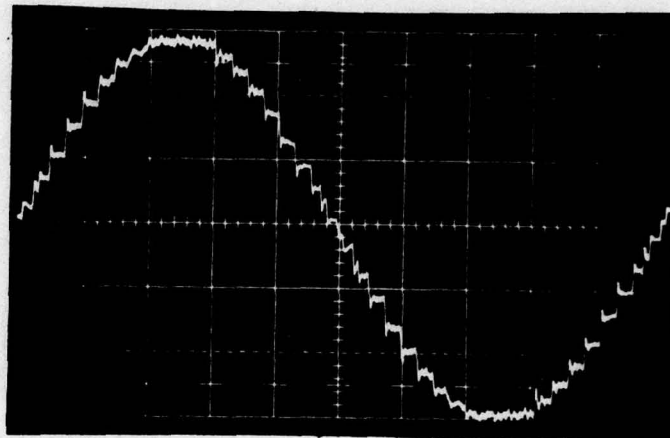
APPROVED

60 HZ THREE PHASE
LINE-TO-LINE VOLTAGES

11KW, PF=0.8

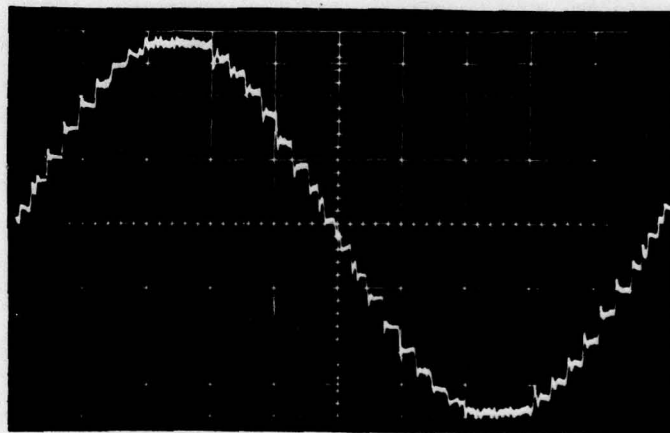
V_{A-B}

THD = 4.32%

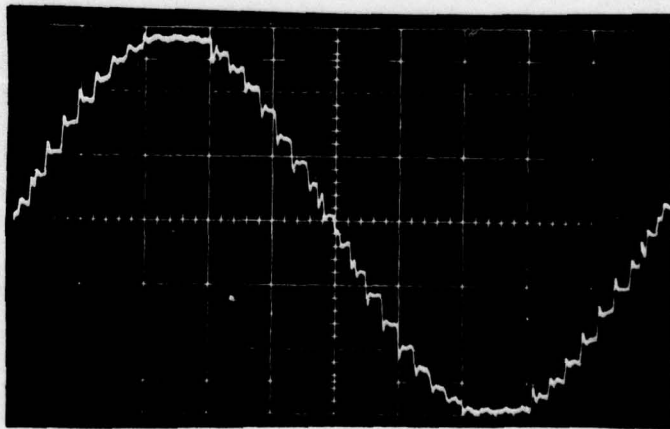


V_{B-C}

↑ 100V/DIV.



V_{C-A}



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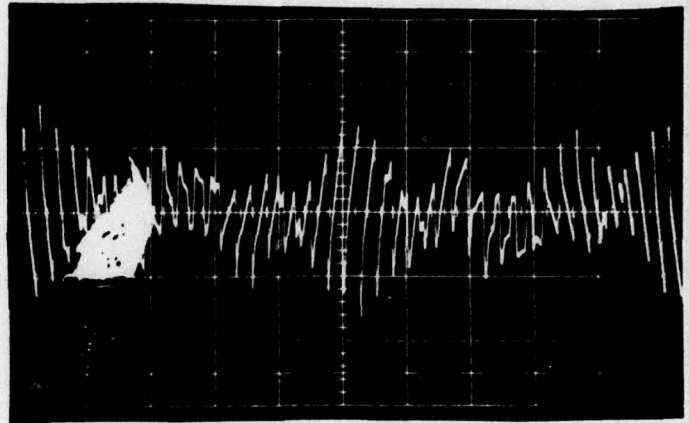
DEVIATION FACTOR

60HZ THREE PHASE
LINE-TO-NEUTRAL VOLTAGES

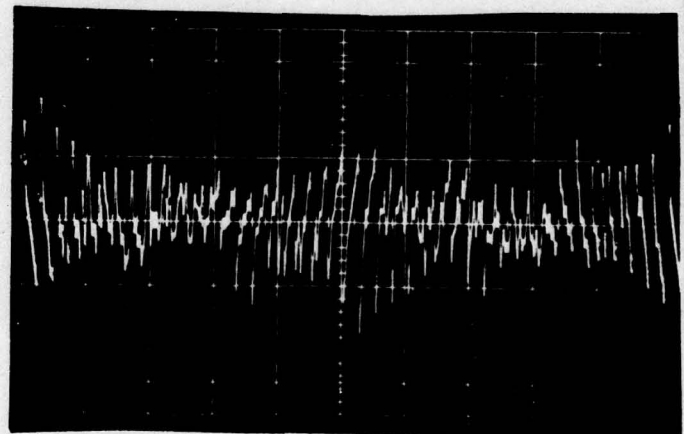
NO LOAD

↑↓ 10V/DIV.

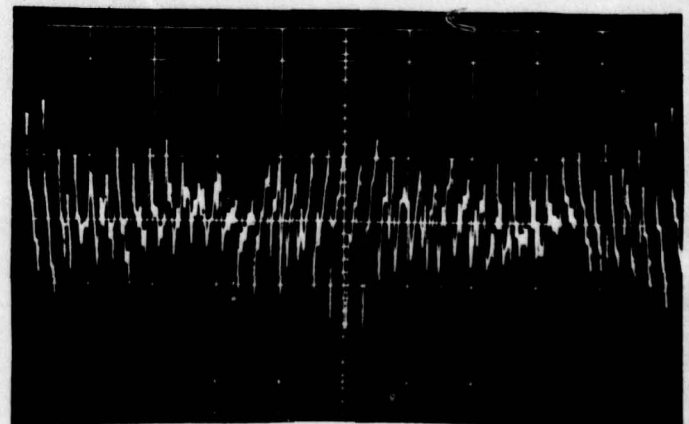
←→ 2MS/DIV.



11KW, PF=1.0



11KW, PF=0.8



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MEASUREMENTS OF INDIVIDUAL HARMONICS

400 HZ THREE PHASE NO LOAD

HARMONIC NUMBER	FREQUENCY KHZ	PERCENT OF FUND.	
		L-T-N	L-T-L
1	0.4	100	100
5	2.0	2.38	2.30
7	2.8	2.23	1.95
11	4.4	0.9	0.87
13	5.2	0.15	0.26
23	9.2	—	0.12
35	14.0	0.1	0.12
37	14.8	0.1	0.12
41	16.4	0.17	0.23
43	17.2	0.06	0.10
COMPUTED THD.		3.38 %	3.16%

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MEASUREMENTS OF INDIVIDUAL HARMONICS

400HZ THREE PHASE

11KW, PF=1.0

HARMONIC NUMBER	FREQUENCY KHZ	PERCENT OF FUND.	
		L-T-N	L-T-L
1	0.4	100	100
3	1.2	0.3	0.15
5	2.0	2.4	2.4
7	2.8	1.8	1.7
11	4.4	0.67	0.82
13	5.2	0.41	0.24
19	7.6	0.12	0.10
21	8.4	0.09	0.08
23	9.2	0.22	0.20
25	10.0	0.17	—
31	12.4	0.08	—
35	14.0	0.13	0.13
37	14.8	0.15	0.12
41	16.4	0.27	0.23
43	17.2	0.1	0.08
COMPUTED THD.		3.146%	3.12%

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MEASUREMENTS OF INDIVIDUAL HARMONICS

400 HZ THREE PHASE

11KW, PF = 0.8

HARMONIC NUMBER	FREQUENCY KHZ	PERCENT OF FUND.	
		L-T-N	L-T-L
1	0.4	100	100
5	2.0	1.22	1.15
7	2.8	1.12	1.02
11	4.4	0.65	0.80
13	5.2	0.37	0.23
17	6.8	0.20	0.18
29	11.6	0.16	0.10
31	12.4	0.10	0.10
35	14.0	0.15	0.13
37	14.8	0.19	0.15
41	16.4	0.24	0.20
COMPUTED THD.		1.86%	1.78%

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MEASUREMENTS OF INDIVIDUAL HARMONICS

60HZ THREE PHASE

NO LOAD

HARMONIC NUMBER	FREQUENCY HZ	PERCENT OF FUND.	
		L-T-N	L-T-L
5	300	0.98	0.94
7	420	1.10	1.10
11	660	0.70	0.65
13	780	0.20	0.20
17	1020	0.28	0.29
19	1140	0.15	0.14
25	1500	0.20	—
35	2100	0.56	0.54
37	2220	1.60	1.60
41	2460	2.70	2.65
43	2580	1.35	1.30
47	2820	.24	.28
53	3180	.11	.15
71	4260	.16	.15
77	4620	.95	.95
79	4740	1.20	1.18
83	4980	.98	.96
85	5100	.16	.18
113	6780	—	0.20
119	7140	—	1.00
121	7260	0.57	0.65
157	9420	—	0.25
161	9660	—	0.54
163	9780	0.20	0.26
COMPUTED THD		4.32%	4.61%

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MEASUREMENTS OF INDIVIDUAL HARMONICS

60 HZ THREE PHASE

11KW, PF=1.0

HARMONIC NUMBER	FREQUENCY HZ	PERCENT OF FUND.	
		L-T-N	L-T-L
5	300	0.52	0.51
7	420	0.38	0.40
11	650	0.70	0.70
13	780	0.20	0.18
17	1020	0.30	0.28
19	1140	0.18	0.16
23	1380	0.12	0.13
25	1500	0.27	0.26
29	1740	0.36	0.35
31	1860	0.32	0.33
35	2100	0.23	0.24
37	2220	1.00	0.96
41	2460	2.40	2.35
43	2580	1.45	1.40
71	4260	0.26	0.25
73	4360	0.26	0.22
77	4620	1.10	1.00
79	4740	1.65	1.46
83	4980	0.91	0.88
101	6060	—	0.20
109	6540	0.22	0.22
113	6780	—	0.23
119	7140	1.35	1.50
121	7260	0.64	0.86
125	7500	0.20	0.23
154	9240	0.60	—
156	9360	0.44	0.60
COMPUTED TTD.		4.25%	4.16%

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MEASUREMENTS OF INDIVIDUAL HARMONICS

60HZ THREE PHASE

11KW, PF = 0.8

HARMONIC NUMBER	FREQUENCY HZ	PERCENT OF FUND.	
		L-T-N	L-T-L
1	60	100	100
5	300	0.46	0.45
7	420	0.47	0.45
11	660	0.56	0.58
13	780	0.26	0.27
17	1020	0.57	0.57
19	1140	0.25	0.25
25	1500	0.42	0.40
29	1740	0.26	0.34
31	1860	0.26	0.26
35	2100	0.32	0.31
37	2220	1.20	1.30
41	2460	2.50	2.50
43	2580	1.40	1.40
49	2640	—	0.24
51	3060	.26	—
53	3180	—	.21
71	4620	—	1.25
79	4740	—	1.40
83	4980	1.54	—
119	7140	1.40	1.60
COMPUTED THD.		3.95%	4.21%

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DC VOLTAGE COMPONENT

VAN Vrms	VAN Vrms	V _{cn} Vrms	V _{an} DC mV	V _{an} DC mV	V _{cn} DC mV	IA A rms	IB A rms	IC A rms	FREQ. Hz	LOAD KW	P.F.
120.1	114.7	120.0	+25	+50	+40	0	0	0	400	0	—
120.2	114.9	120.2	+23	+50	+36	30.77	30.42	31.18	400	11	1.0
119.8	119.2	119.7	+50	+14	+10	39.13	39.86	39.97	400	11	0.8
120.26	120.28	119.76	+5	-3	-6	0	0	0	60	0	—
120.21	120.31	119.7	+5	+4	-13	30.74	30.96	31.65	60	11	1.0
120.21	120.11	119.71	+7	+9	+3	39.0	39.5	39.8	60	11	0.8

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3.24.1.4 PHASE VOLTAGE BALANCE

V _{AN} V _{LINE}	V _{BN} V _{LINE}	V _{CN} V _{LINE}	V _{AB} V _{LINE}	V _{BC} V _{LINE}	V _{CA} V _{LINE}	I _A A _{LINE}	I _B A _{LINE}	I _C A _{LINE}	FREQ. HZ	LOAD KW	P.F.
120.1	119.7	119.9	207.5	207.4	208.3	0	0	0	400	0	—
120.3	119.8	120.1	207.5	208.1	208.5	30.77	30.91	31.58	400	11	1.0
120.0	119.3	119.8	207.1	207.4	207.6	39.13	39.87	39.98	400	11	0.8
120.27	120.27	119.78	208.2	207.6	207.9	0	0	0	60	0	0
120.20	120.30	119.8	208.0	208.0	207.7	30.74	30.95	31.6	60	11	1.0
120.20	120.10	119.70	208.0	208.0	208.0	38.69	39.6	39.8	60	11	0.8

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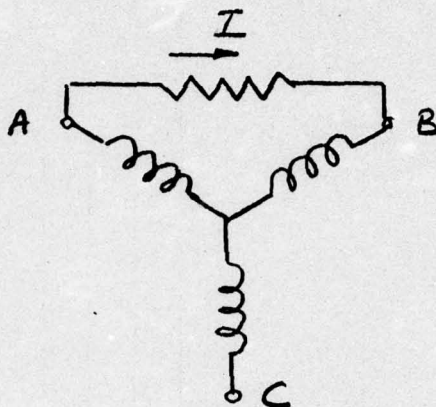
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3.24.1.5 EFFECT OF UNBALANCED LOAD (3PHASE)400 HZ $I = 8.73 \text{ A rms}$

V_{AB}	207.7
V_{BC}	211.4
V_{CA}	212.8
V_{AN}	121.3
V_{BN}	117.5
V_{CN}	121.5

MAX. L-T-L
VOLTAGE
DIFFERENCE 5.1

$$\frac{5.1 \times 100}{208} = \underline{\underline{2.45\%}}$$

60 HZ $I = 8.7 \text{ A rms}$

206.6
220.5
218.1
121.2
122.7
128.9

13.9

$$\frac{13.9 \times 100}{208} = \underline{\underline{6.68\%}}$$

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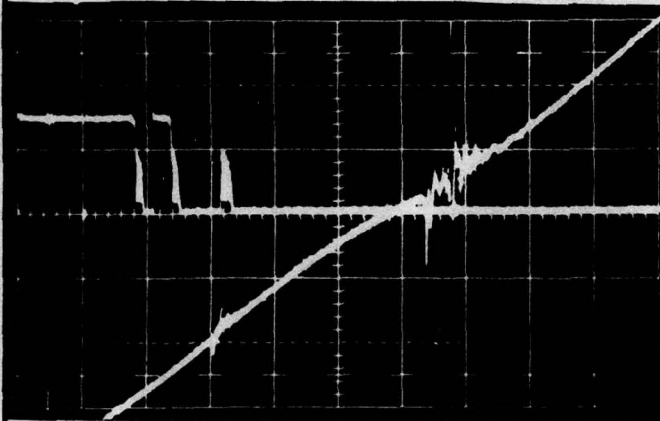
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3.24.1.6 PHASE ANGLE BALLANCE

400 HZ BALANCED LOAD
L-T-N VOLTAGES

NO LOAD

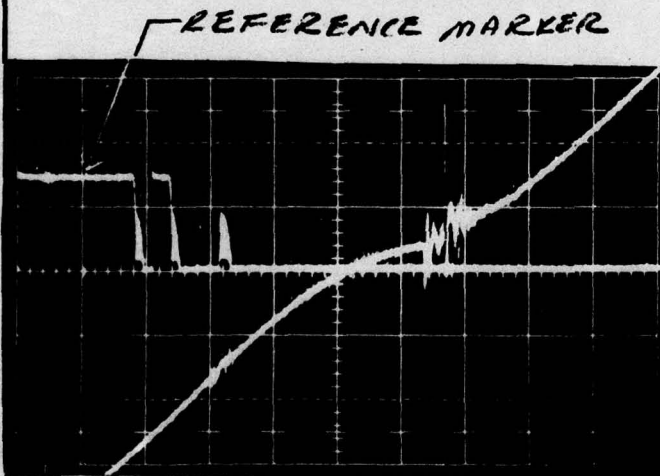


PHASE A

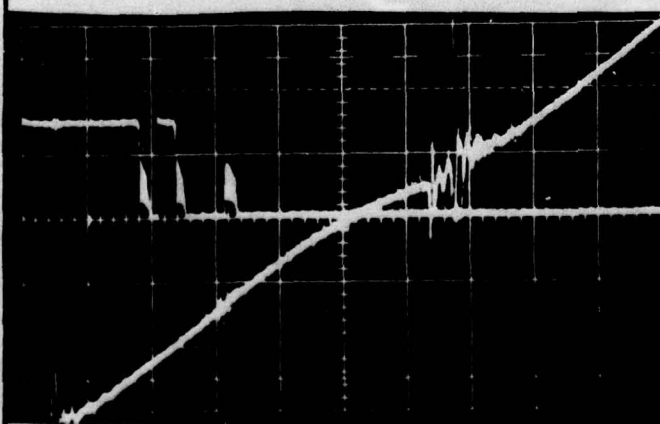
O CROSS-OVER

↓ 5V/DIV.

↔ 1.44°/DIV.
(10 μSEC/DIV.)



PHASE B



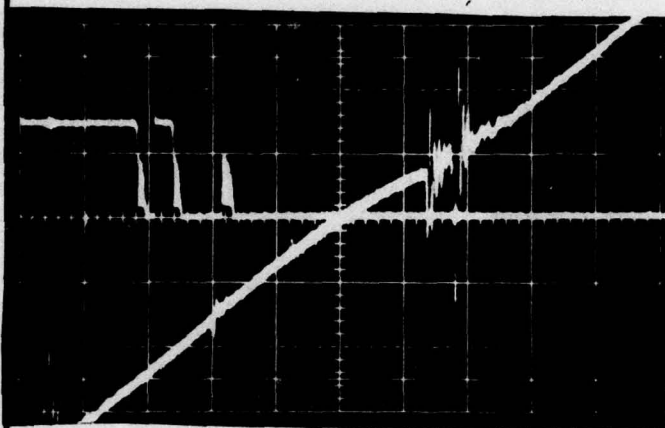
PHASE C

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400 HZ BALANCED LOAD
L-T-N VOLTAGES

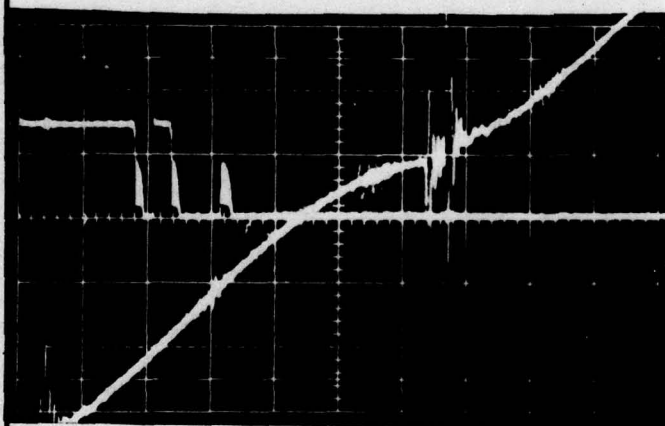
11KW, PF=1.0



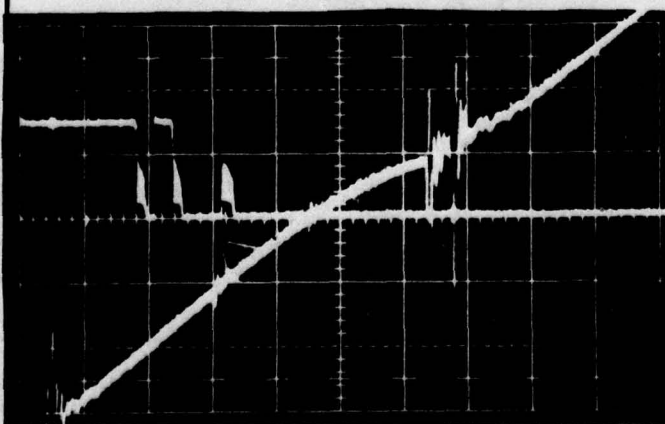
PHASE A

↑ 5V/DIV.

↔ 1.44°/DIV.



PHASE B



PHASE C

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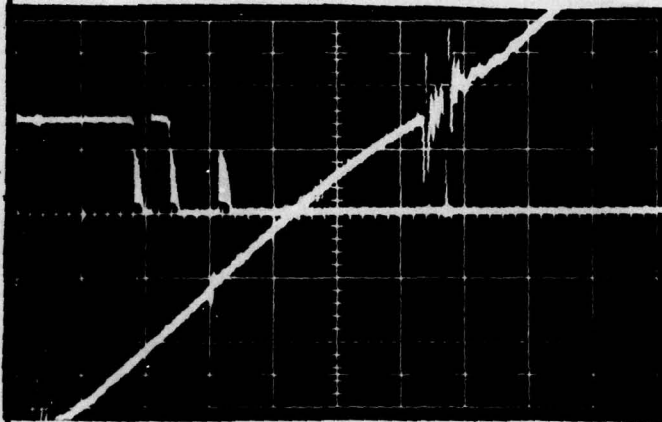
1/12/79

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400 HZ BALANCED LOAD
L-T-N VOLTAGES

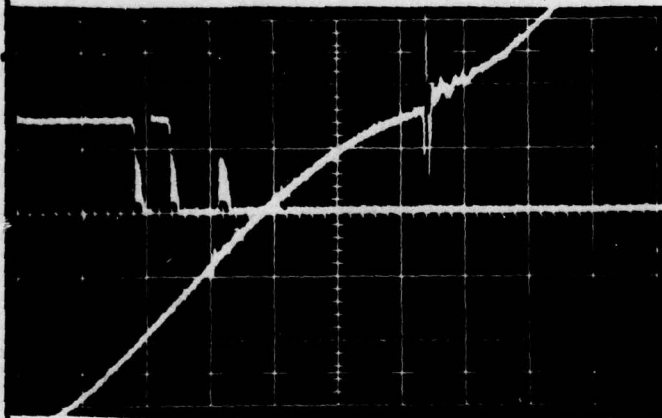
11KW, PF=0.8



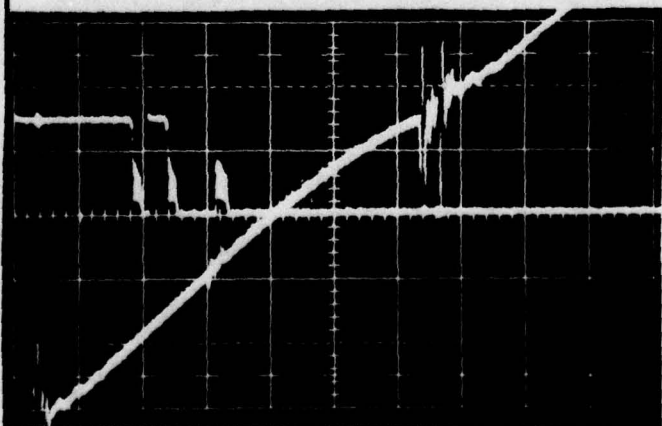
PHASE A

↓ 5V/DIV.

↔ 1.44°/DIV.



PHASE B



PHASE C

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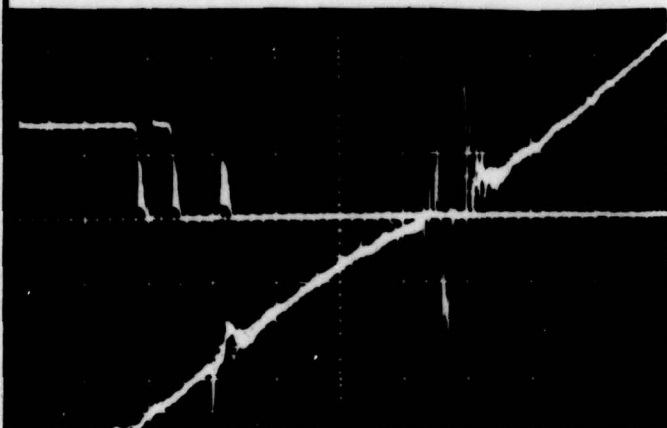
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1/18/74

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400 HZ 25 PERCENT UNBALANCED LOAD
AS DESCRIBED IN 3.24.1.5

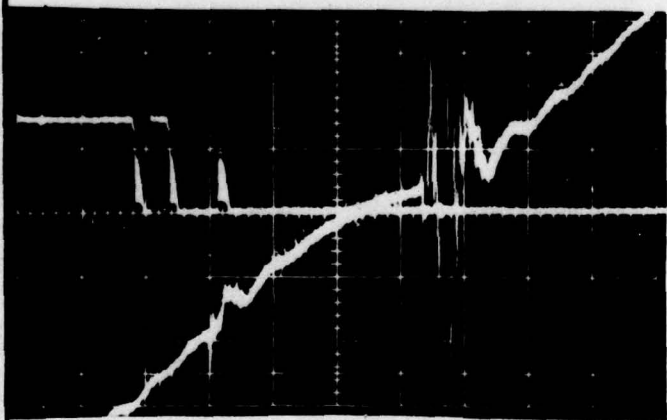


L-T-N VOLTAGES

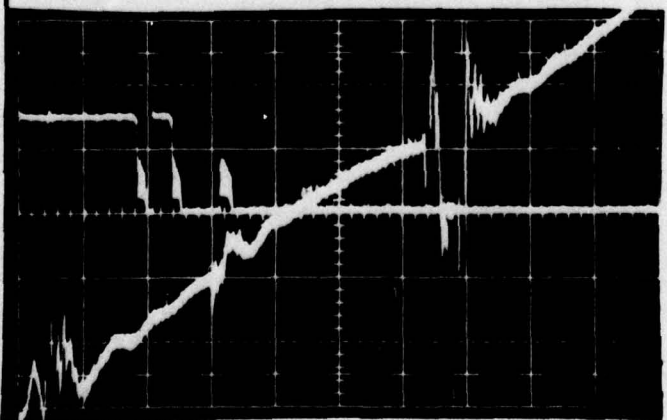
PHASE A

↕ 5V/DIV.

↔ 1.44°/DIV.



PHASE B



PHASE C

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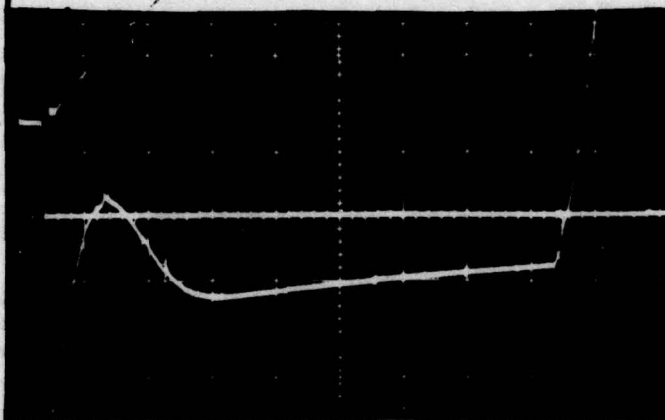
CHECKED

APPROVED

60 HZ BALANCED LOAD
L-T-N VOLTAGES

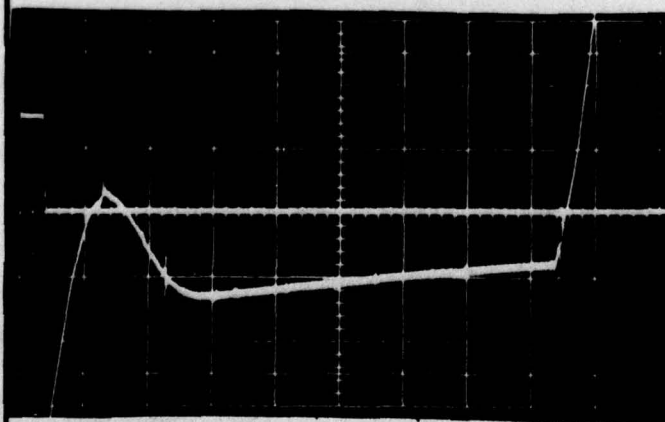
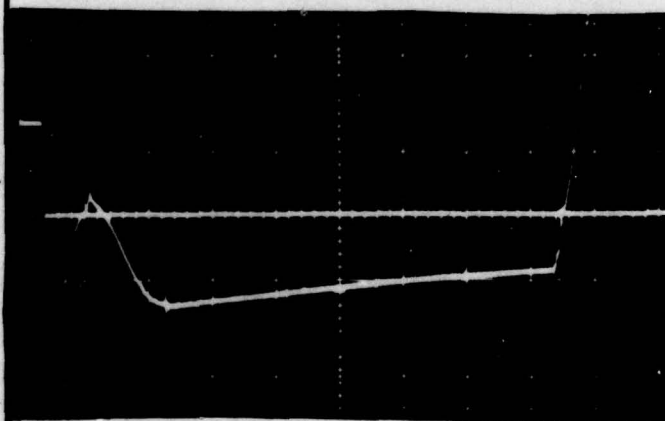
NO LOAD

REFERENCE MARKER



↑ 5V / DIV.

← 1.09° / DIV.
(50 μSEC / DIV.)



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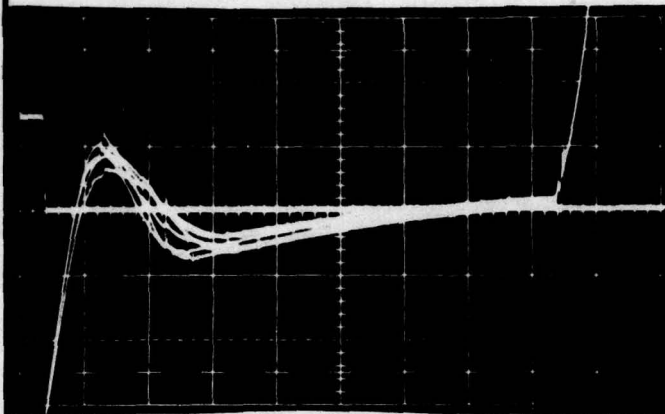
1/18/79

CHECKED

APPROVED

60HZ BALANCED LOAD
L-T-N VOLTAGES

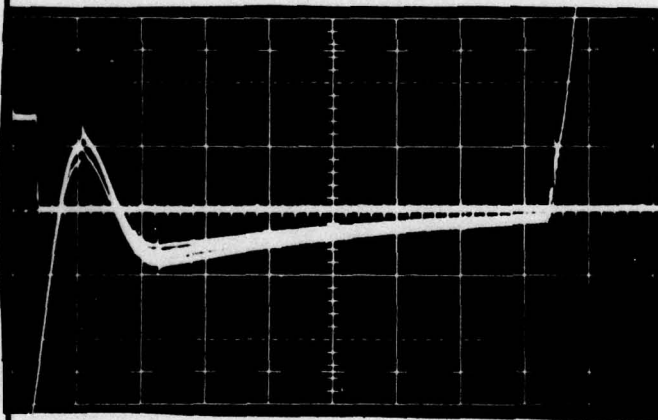
11KW, PF = 1.0



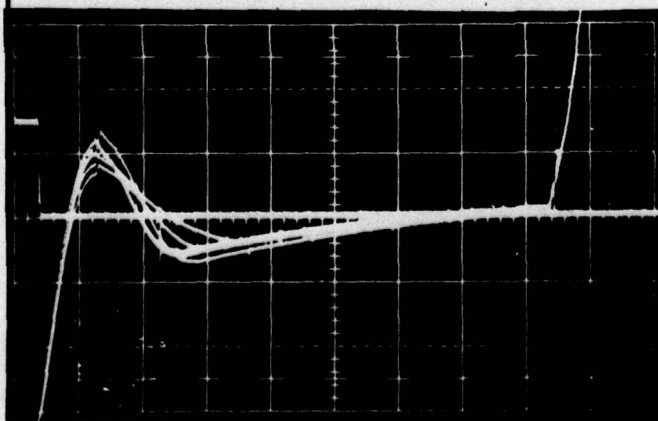
PHASE A

↓ 5V/DIV.

← 1.09°/DIV.



PHASE B



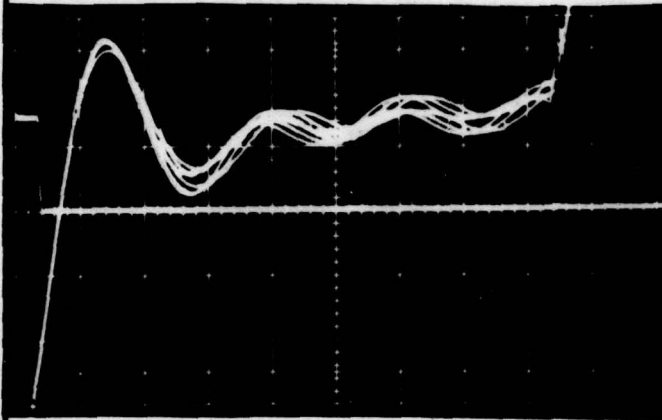
PHASE C

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**60HZ BALANCED LOAD
L-T-N VOLTAGES**

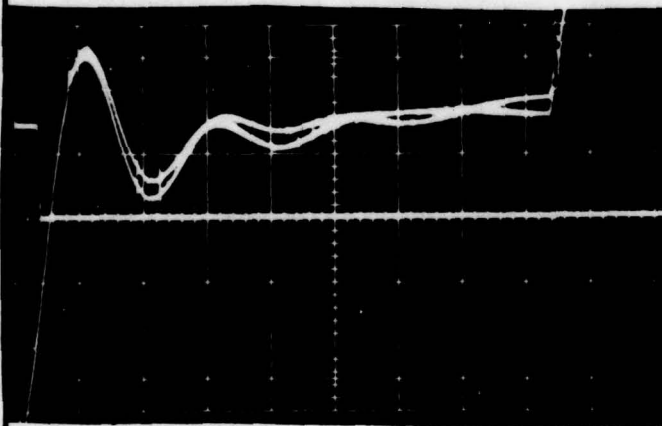
11KW, PF=0.8



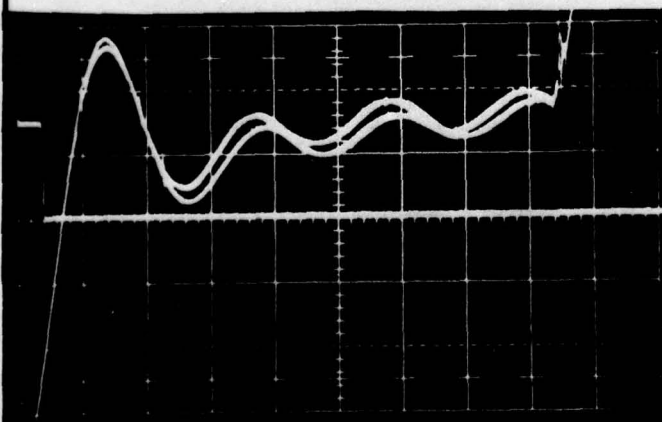
PHASE A

↑ 5V/DIV.

← 1.09°/DIV.



PHASE B



PHASE C

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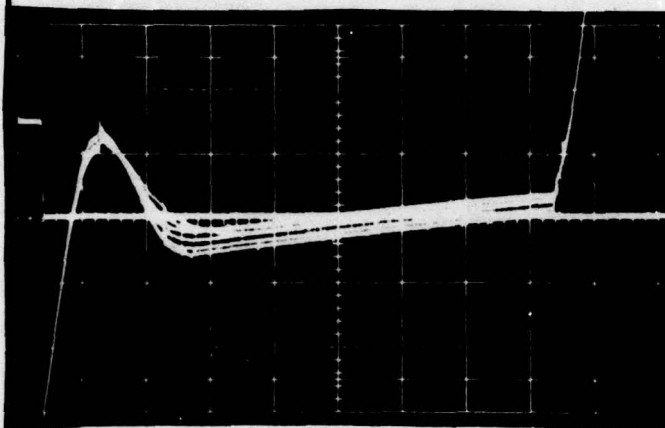
DATE

1/18/79

CHECKED

APPROVED

60HZ 25 PERCENT UNBALANCED LOAD
AS DESCRIBED IN 3.24.15

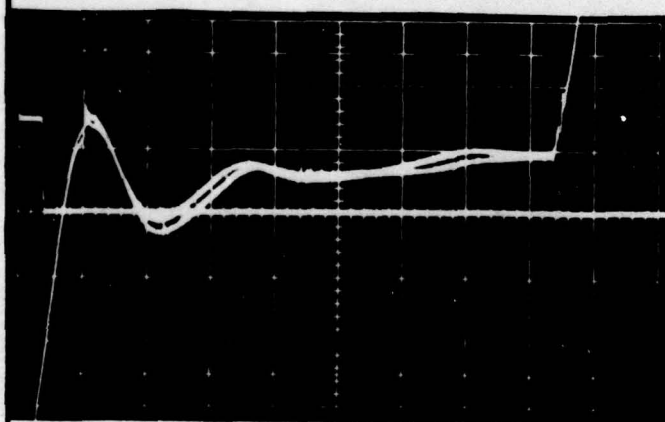


L-T-N VOLTAGES

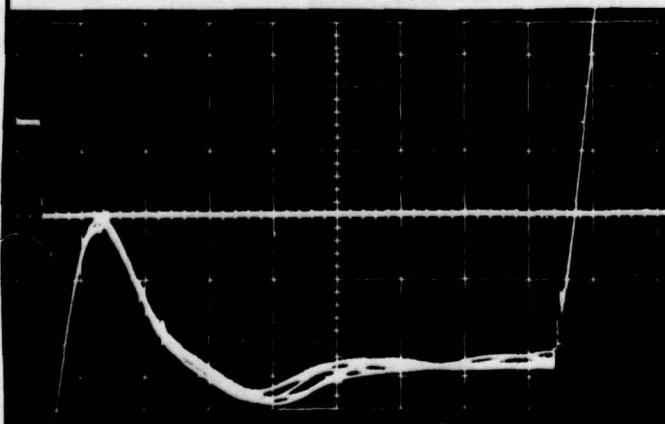
PHASE A

↑ 50V/DIV.

← 1.04°/DIV.



PHASE B



PHASE C

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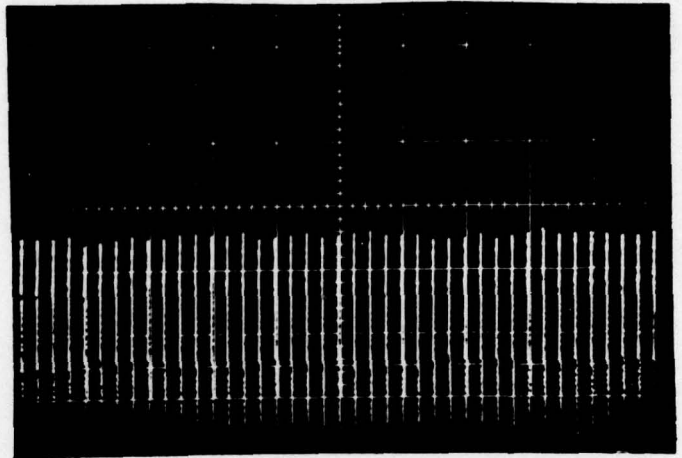
3.24.1.7 VOLTAGE MODULATION

400 HZ THREE PHASE
L-T-N V-A-N

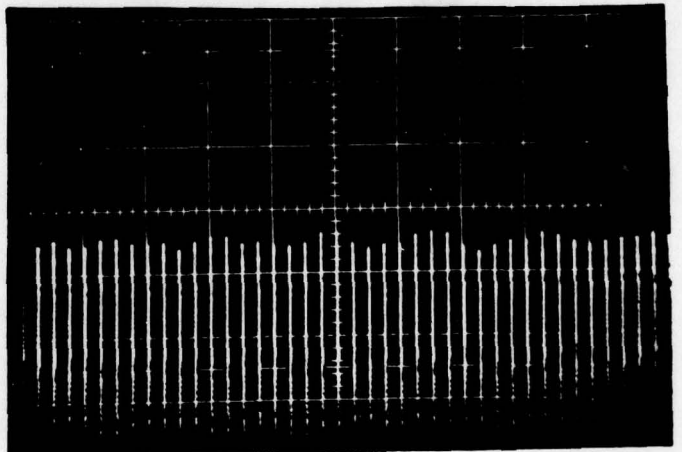
NO LOAD

↑ 2V/DIV.

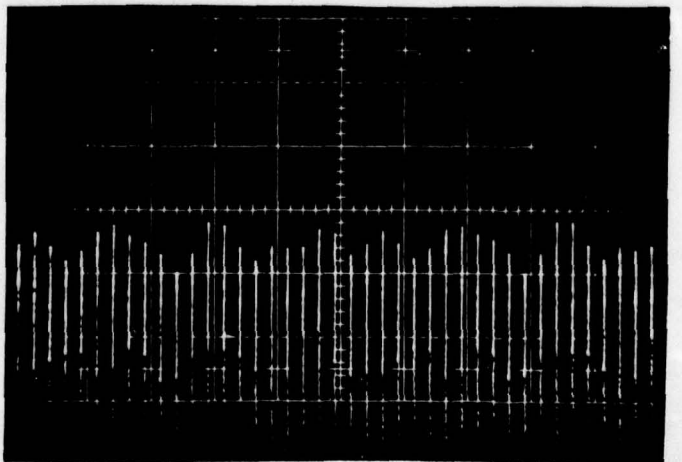
↔ 10MS/DIV.



11KW, PF = 1.0



11KW, PF = 0.8



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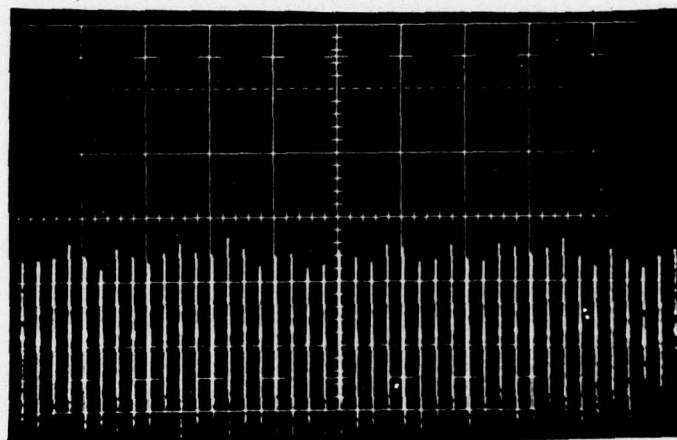
APPROVED

400 HZ THREE PHASE
L-T-L VA-B

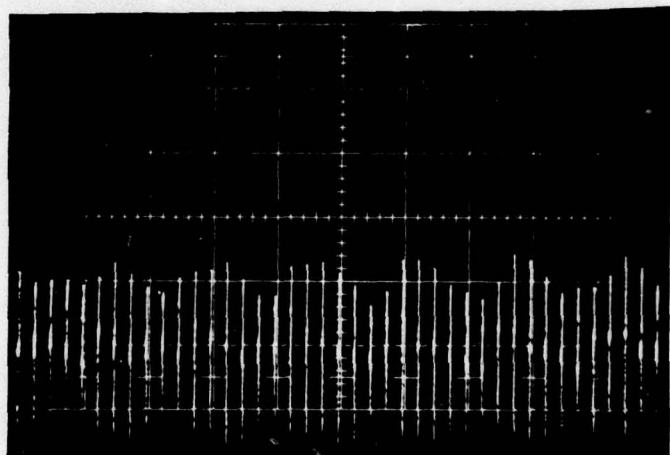
NO LOAD

↑ 2V/DIV.

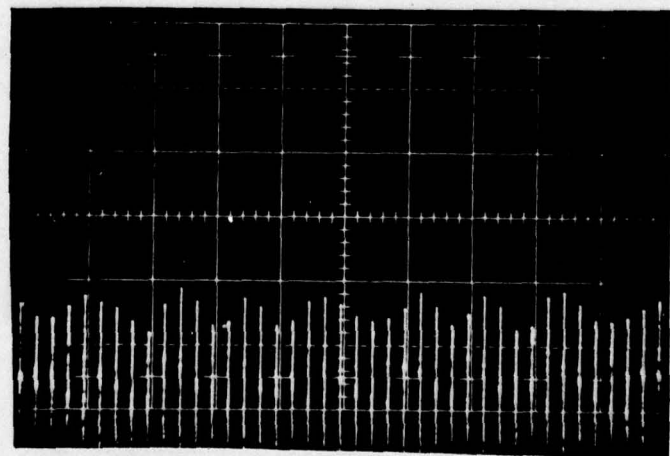
← 10MS/DIV.



11KW, PF=1.0



11KW, PF=0.8



DISTRIBUTION:

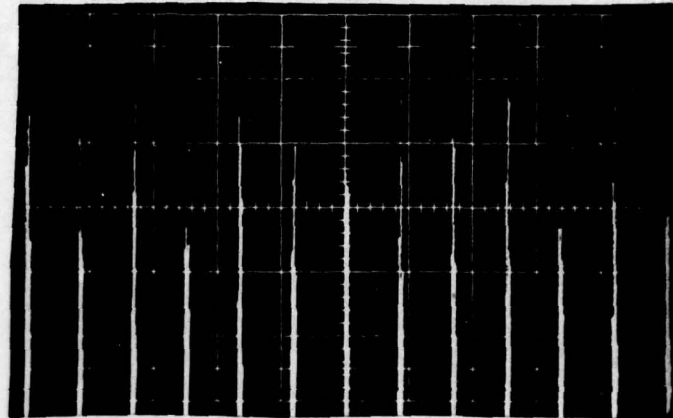
DELCO ELECTRONICS GENERAL MOTORS CORPORATION		REPORT NO.	PAGE	JOB NO. THREE. PHASE	PAGE 73
TITLE			PREPARED	CORRY 1/18/7	
			CHECKED		
			APPROVED		

60 HZ THREE PHASE
L-T-L VA-8

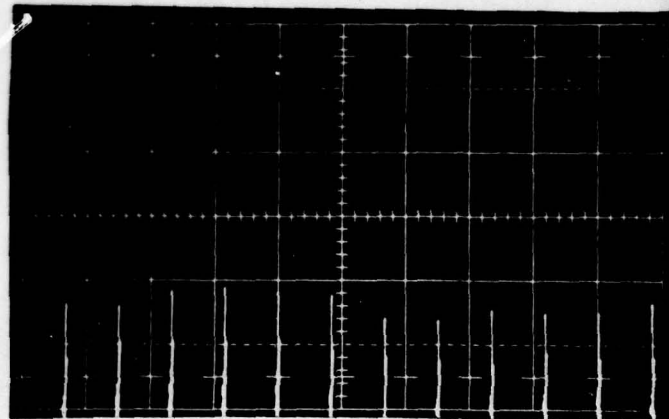
NO LOAD

↕ 2V / DIV.

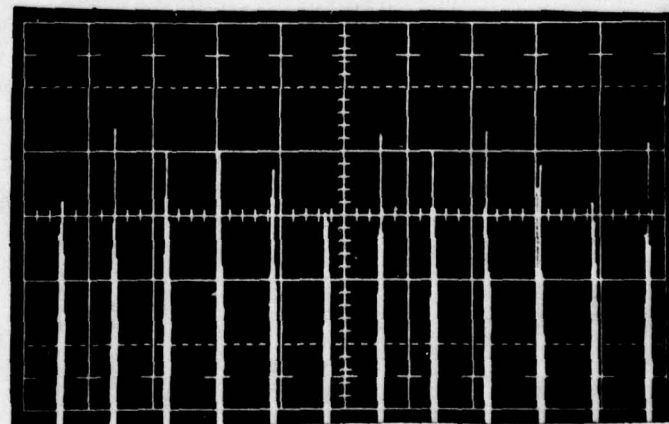
↔ 20 ms / DIV.



11 KW, PF = 1.0



11 KW, PF = 0.8



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VOLTAGE MODULATION - CONVERTER OUTPUT DATA

FREQ. Hz	V _{AN} V _{rms}	V _{BN} V _{rms}	V _{CN} V _{rms}	V _{AB} V _{rms}	V _{BC} V _{rms}	V _{CA} V _{rms}	I _A A _{rms}	I _B A _{rms}	I _C A _{rms}	LOAD KW	P.F.
400	119.8	119.7	119.9	206.8	207.6	206.8	—	—	—	—	—
400	119.8	119.7	119.9	206.8	207.9	206.8	30.8	30.8	31.5	11KW	1.0
400	119.8	119.6	119.8	206.3	206.9	206.8	34.0	39.8	39.9	11KW	0.8
60	120.0	120.1	120.1	208.1	208.1	208.1	—	—	—	—	—
60	120.1	120.1	120.0	208	207.9	207.8	30.74	30.96	31.60	11KW	1.0
60	120.2	120.1	119.7	208	207.9	207.9	39.1	39.2	39.5	11KW	0.8

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3.24.1.8 VOLTAGE REGULATION

3.24.2.2 FREQUENCY REGULATION

LOAD	PF	V _{AN} V _{RMS}	V _{BN} V _{RMS}	V _{CN} V _{RMS}	I _A A _{RMS}	I _B A _{RMS}	I _C A _{RMS}	FREQ. Hz
0	—	120.1	119.7	119.9	—	—	—	400
1/4	0.8	120.1	119.7	120.1	7.9	7.99	8.0	400
1/2	0.8	119.8	119.3	119.9	23.6	23.9	24.0	400
3/4	0.8	119.8	119.3	119.9	31.3	31.8	32.0	400
FULL	0.8	119.8	119.3	119.9	39.13	39.87	39.98	400
0	—	—	—	—	—	—	—	60
1/4	0.8	120.2	120.2	120.0	8.0	8.0	8.1	60
1/2	0.8	120.1	120.1	120.1	23.7	23.9	24.0	60
3/4	0.8	120.0	120.0	120.1	31.9	31.9	31.9	60
FULL	0.8	120.0	120.1	120.1	39.13	39.85	39.88	60

NOTE: CURVES WERE APPLIED AND DROPPED THREE TIMES

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INHERENT VOLTAGE DROOP
OF THE 10KW FREQUENCY CHANGER

400 HZ

LINE-TO-NEUTRAL VOLTAGE (VRMS)	LOAD (KW) PF = 0.8
120.0	—
119.1	3.2
118.5	5.4
118.0	7.6
117.4	9.8
116.6	13.4

%REGULATION =

$$\frac{N.L. \text{ VOLTAGE} - F.L. \text{ VOLTAGE}}{F.L. \text{ VOLTAGE}} \times 100$$

$$\frac{120 - 117.4}{117.4} \times 100 = \underline{\underline{2.21\%}}$$

60 HZ

LINE-TO-NEUTRAL VOLTAGE (VRMS)	LOAD (KW) PF = 0.8
120.0	—
118.7	3.2
118.25	5.4
117.7	7.6
117.5	9.8
116.7	13.4

$$\frac{120 - 117.5}{117.5} \times 100 = \underline{\underline{2.21\%}}$$

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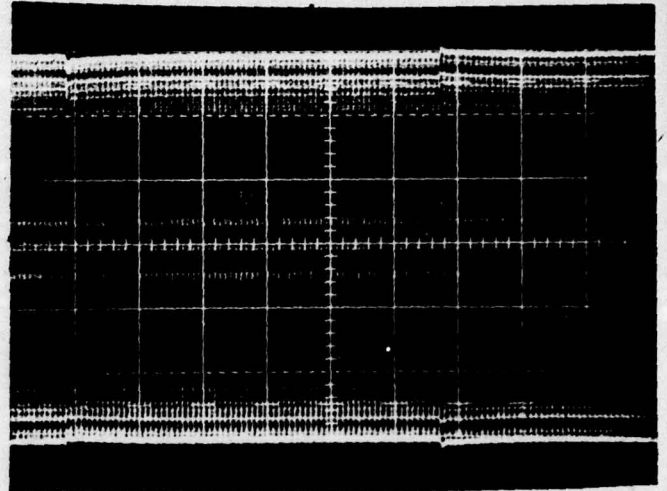
APPROVED

3.24.1.12 TRANSIENT VOLTAGE PERFORMANCE

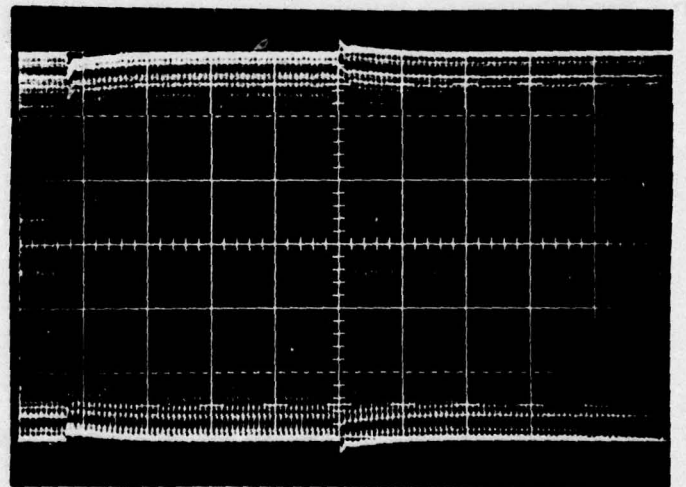
400 HZ THREE PHASE
LINE-TO-NEUTRAL
VOLTAGES

1/4 LOAD, PF=0.8

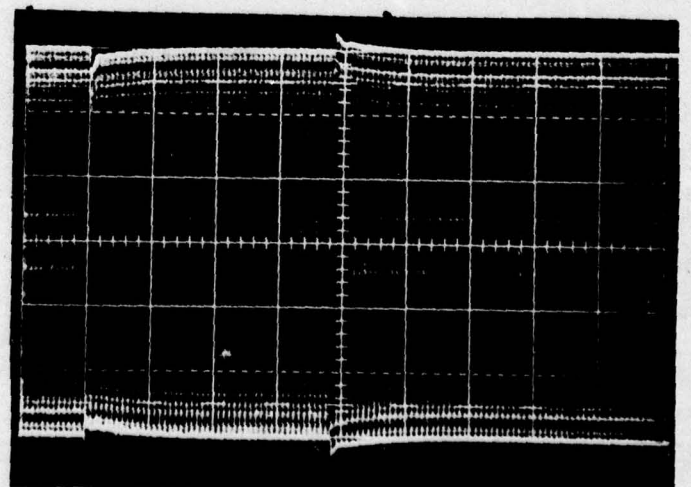
← 0.2 SEC / DIV.



1/2 LOAD, PF=0.8



3/4 LOAD, PF=0.8



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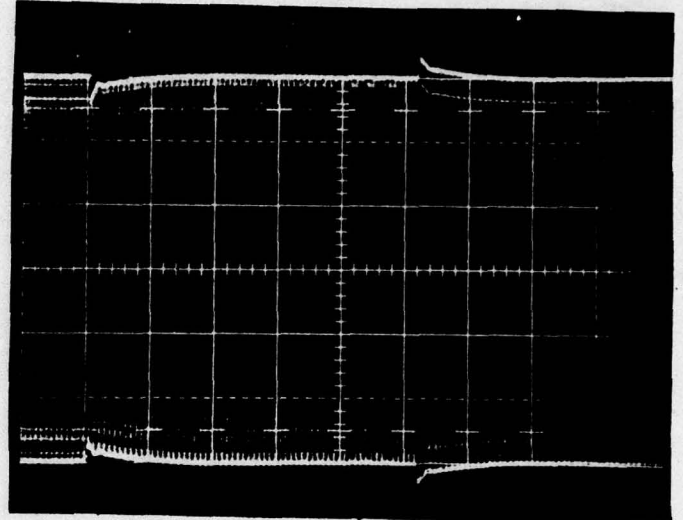
CHECKED

APPROVED

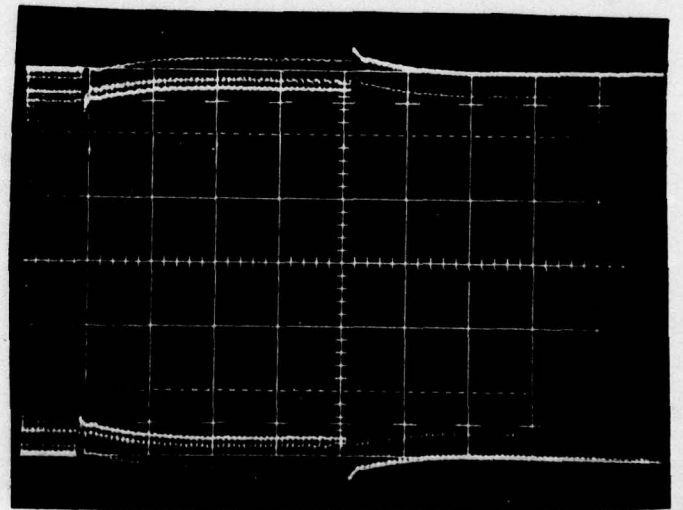
400HZ THREE PHASE
LINE-TO-NEUTRAL
VOLTAGES

FULL LOAD, PF=0.8

↔ 0.2 SEC/DIV.



2 P.U., P.F.=0.4



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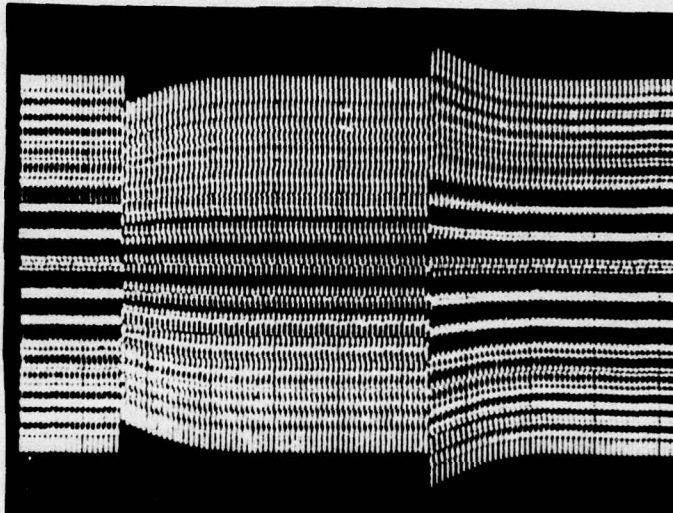
CHECKED

APPROVED

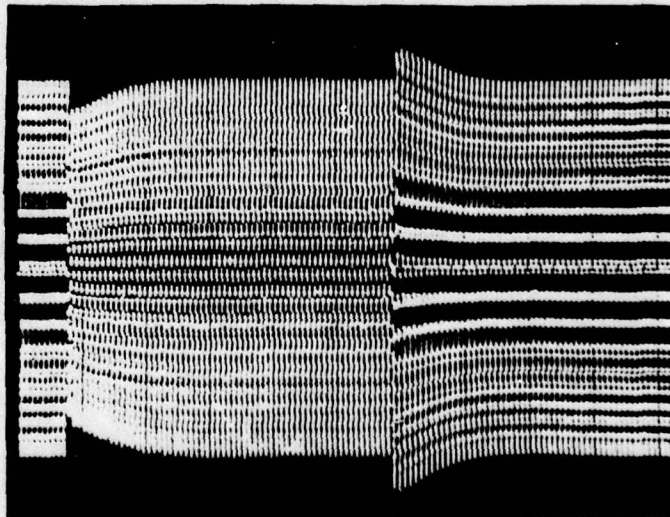
60 HZ THREE PHASE
LINE-TO-NEUTRAL VOLTAGES

$\frac{1}{4}$ LOAD, $PF \approx 0.8$

$\longleftrightarrow 0.2 \text{ SEC/DIV.}$



$\frac{1}{2}$ LOAD, $PF \approx 0.8$



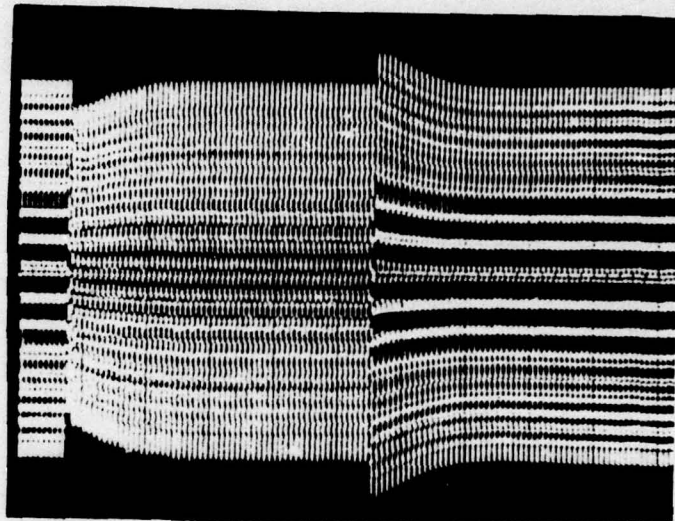
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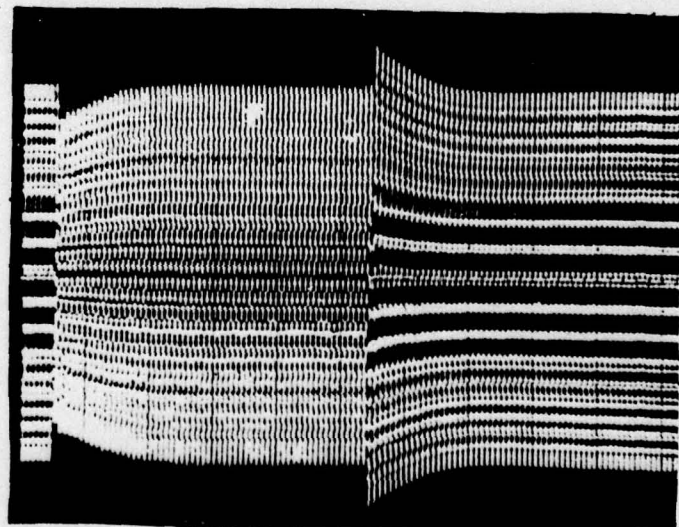
60HZ THREE PHASE
LINE-TO-NEUTRAL VOLTAGES

$\frac{3}{4}$ LOAD, PF=0.8

→ 0.2 SEC/DIV.



FULL LOAD, PF=0.8



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400 HZ TRANSIENT PERFORMANCE

	V_{AN} V_{RMS}	V_{BV} V_{RMS}	V_{CN} V_{RMS}	I_A A_{RMS}	I_B A_{RMS}	I_C A_{RMS}	FREQ. Hz	LOAD	PF
BEFORE LOAD STEP	120.1	119.8	120.0	0	0	0	400	—	—
AFTER LOAD STEP	119.8	119.2	119.7	39.1	39.8	39.9	400	1 P.U.	0.4
BEFORE LOAD STEP	120.1	119.8	120.0	0	0	0	400	—	—
AFTER LOAD STEP	118.7	117.9	118.4	66.9	67.9	67.3	400	2 P.U.	0.48

NOTE: EACH LOAD APPLIED AND REMOVED THREE TIMES

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3.24.1.13 SHORT CIRCUIT

MAXIMUM CURRENT LIMITING CAPABILITIES
OF THE PRESENT FREQUENCY CONVERTER
BREADBOARD IN THE SHORT CIRCUIT
MODE OF OPERATION.

SHORT CIRCUIT	FREQ. HZ	LINE CURRENT AMPS RMS
THREE PHASE A-N B-N C-T-N C-N	400	100
TWO PHASE A-N L-T-N B-N	400	30
ONE PHASE L-T-N A-N	400	38
THREE PHASE L-T-L A-B-C	400	100
ONE PHASE L-T-L A-B	400	38
THREE PHASE A-N B-P L-T-N C-N	60	100
TWO PHASE A-N L-T-N B-N	60	110
ONE PHASE L-T-N A-N	60	120
THREE PHASE L-T-L A-B-C	60	100
ONE PHASE L-T-L A-B	60	55

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3.24.3 EFFICIENCY

CIRCUIT DESCRIPTION	FREQ. HZ	INPUT POWER WATTS	OUTPUT POWER WATTS	P.F.	LOSSES WATTS	EFF. %
P.F. CORRECTED						
60 MFD. 2-T-2	400	1532	NO LOAD	—	1532	—
	400	3779	2221	1.0	1558	58.8
	400	12854	11088	1.0	1766	86.3
	400	12714	11088	0.8	1626	87.2
WITH STEP TRANSISTORS- NO OUTPUT CAP	400	310	NO LOAD	—	310	—
	400	2579	2221	1.0	358	86.1
	400	11901	11106	1.0	795	93.3
	400	12677	11106	0.8	1571	87.6

* DOES NOT INCLUDE RECTIFIER OR OTHER FIXED LOSSES.

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3.24.3 EFFICIENCY

CIRCUIT DESCRIPTION	FREQ. HZ	INPUT POWER WATTS	OUTPUT POWER WATTS	P.F.	LOSSES WATTS	EFF. %
WITH STEP TRANSISTORS	60	142	—	—	142	—
60 MPD L-T-N	60	2452	2218	1.0	234	90.43
	60	11505	11038	1.0	467	95.9
✓	60	12101	11038	0.8	1063	91.2

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DOES NOT INCLUDE RECTIFIER OR OTHER FIXED LOSSES

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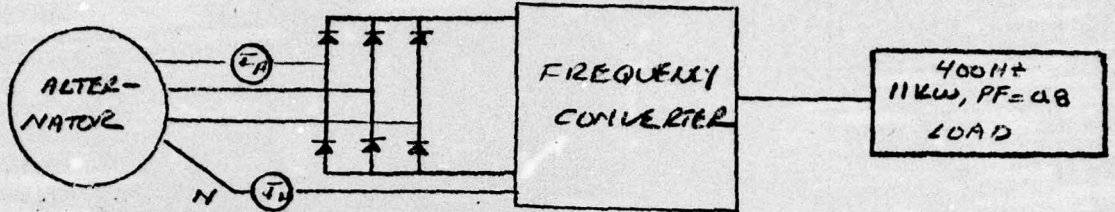
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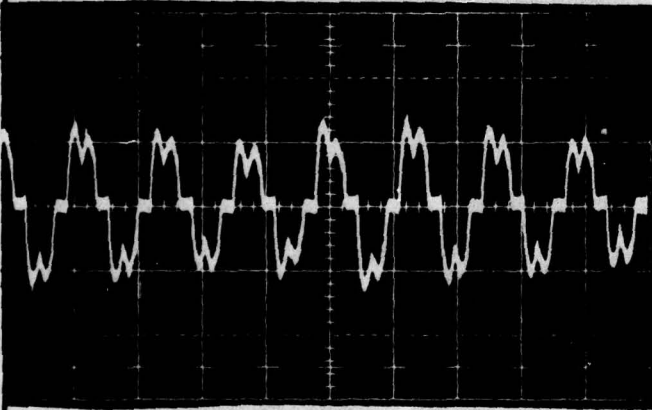
TURBO-ALTERNATOR CURRENT WAVEFORMS INTO THE 10KW FREQUENCY CONVERTER



ALTERNATOR LINE
CURRENT

↑ 20A/DIV.

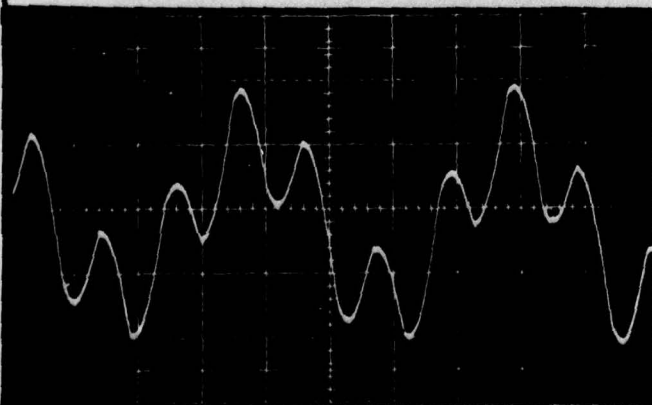
← 100μSEC/DIV.



ALTERNATOR LINE
CURRENT

↑ 50A/DIV.

← 500μSEC/DIV.



ALTERNATOR NEUTRAL
CURRENT

↑ 10A/DIV.

← 200μSEC/DIV.

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TITLE

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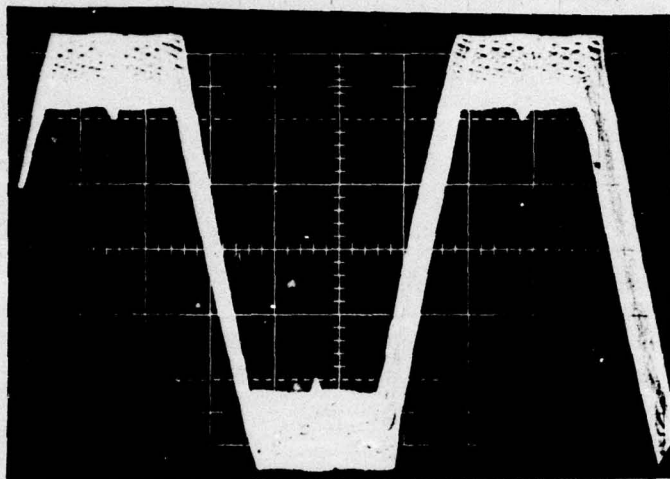
DATE

CORRY 3/8/74

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APPROVED

ALTERNATING L-T-N VOLTAGES AT OUTPUT OF MATCHING TRANSFORMERS

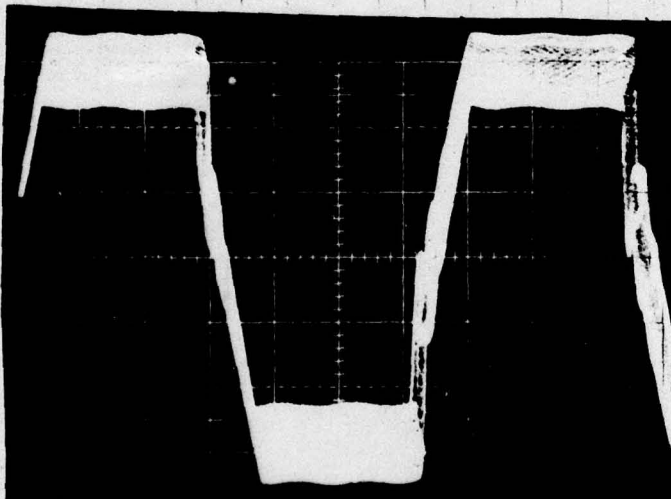


a

125.3 Vrms

NO LOAD ON INVERTER -
INVERTER OUTPUT
VOLTAGE = 120 Vrms L-T-N

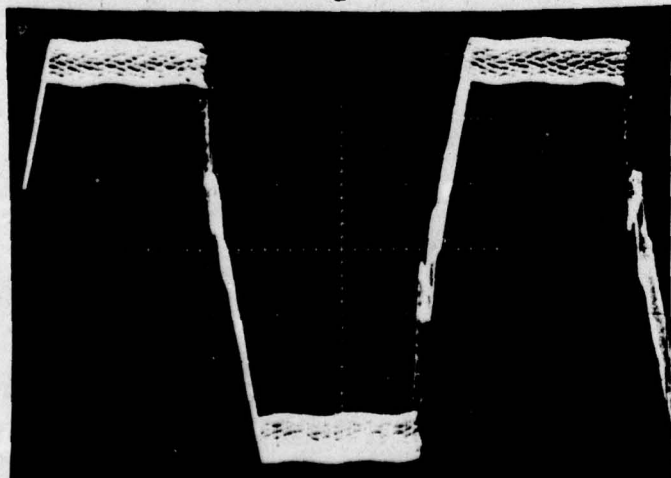
↑ 50V/DIV.
↔ 100 μSEC/DIV.



b

135 Vrms

INVERTER LOAD 11 KW,
PF = 1.0 3Φ, 400 Hz
INVERTER OUTPUT
VOLTAGE = 120.0 Vrms



c

133.9 Vrms

INVERTER LOAD 11 KW,
PF = 0.8 3Φ 400 Hz

INVERTER OUTPUT
VOLTAGE = 119.8 Vrms

(TWO WIRE INPUT TO
INVERTER)

DELCO ELECTRONICS

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BSB

TITLE

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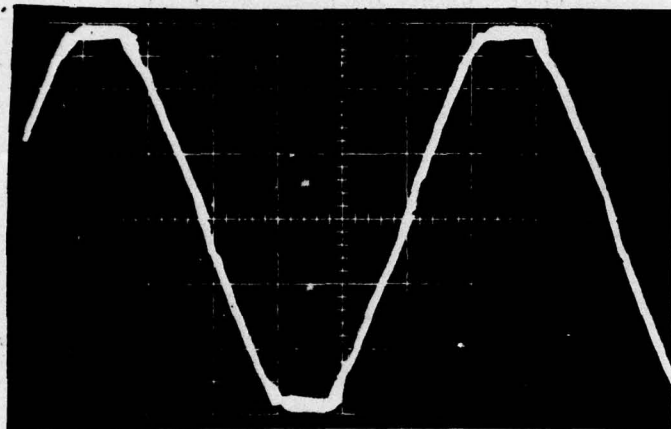
DATE

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CORY 3/8/74

ALTERNATE L-T-L VOLTAGES AT OUTPUT OF MATCHING TRANSFORMERS



a

209.4 Vrms

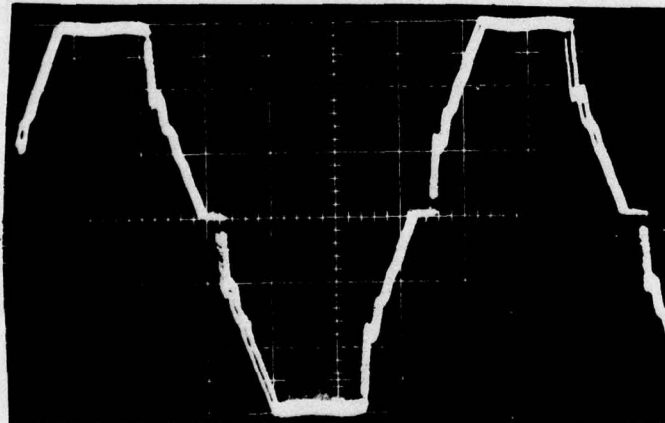
NO LOAD ON INVERTER

INVERTER OUTPUT

VOLTAGE = 208 Vrms L-T-L

↓ 100V / DIV

↔ 100μSEC / DIV.



b

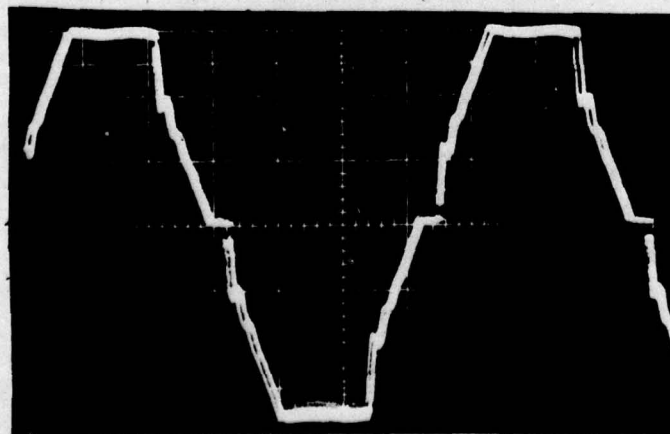
222.9 Vrms

INVERTER LOAD 11 KW

PF=1.0 3φ 400 Hz

INVERTER OUTPUT

VOLTAGE = 209.0 Vrms L-T-L



c

223 Vrms

INVERTER LOAD 11 KW

PF=0.8 3φ 400 Hz

INVERTER OUTPUT

VOLTAGE = 207.5 Vrms L-T-L

(TWO WIRE INPUT TO INVERTER)

DISTRIBUTION:

TITLE

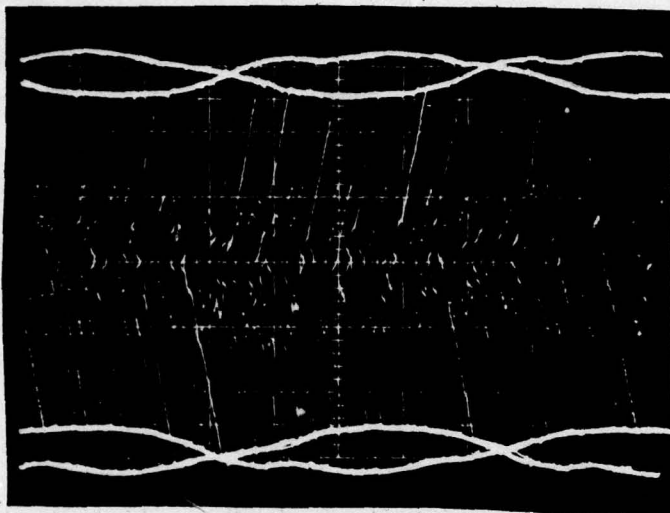
PREPARED

DATE

CHECKED

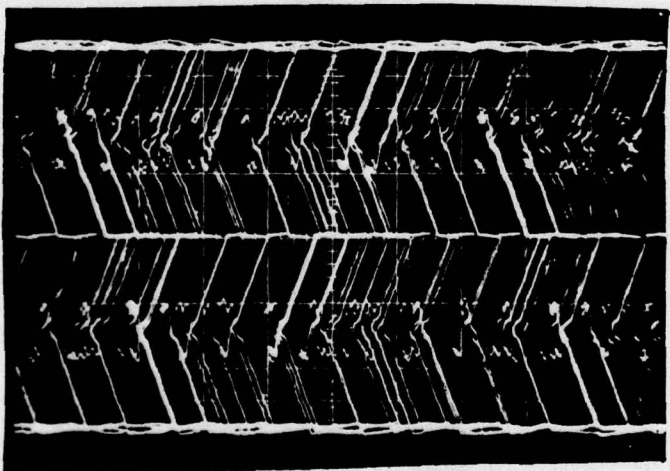
APPROVED

CORY 3/8/74

INVERTER INPUT AND OUTPUT AC VOLTAGES

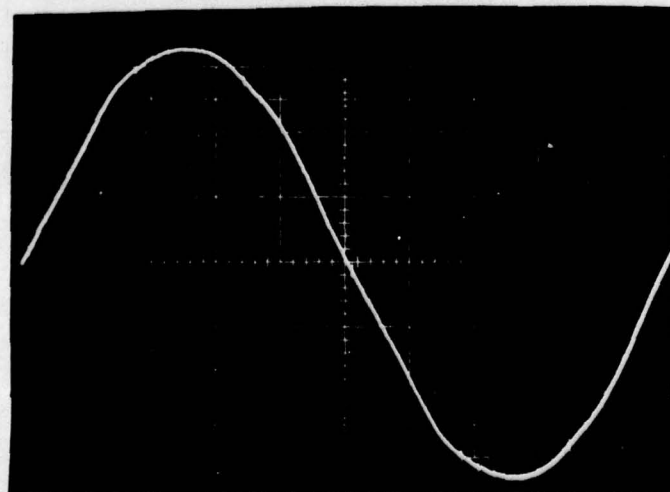
ALTERNATOR L-T-N
OUTPUT VOLTAGE

SAME AS PHOTO C
ON PAGE 85A BUT
SYNC. CHANGED TO
SHOW AMPLITUDE
MODULATION.



ALTERNATOR L-T-L
OUTPUT VOLTAGE

SAME AS PHOTO C
ON PAGE 85B BUT
SYNC. CHANGED TO
SHOW AMPLITUDE
MODULATION.



INVERTER OUTPUT
L-T-N VOLTAGE.

119.8 V RMS

LOAD 11KW, PF=0.8
3Φ, 400 HZ

(TWO WIRE INVERTER INPUT)

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85D

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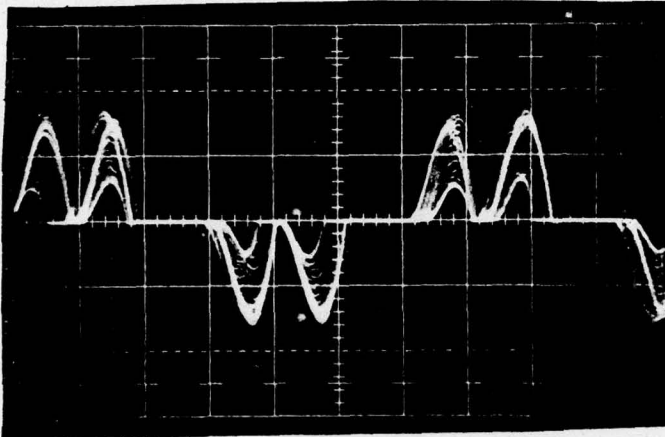
DATE

CORRY 3/8/74

CHECKED

APPROVED

ALTERNATOR LINE CURRENTS AT OUTPUT
OF MATCHING TRANSFORMERS

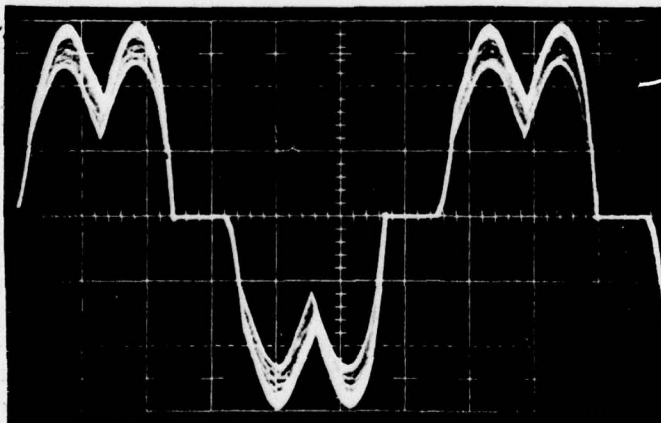


6.34 A rms

NO LOAD ON INVERTER

↓ 10 A / DIV.

↔ 100 μsec / DIV.

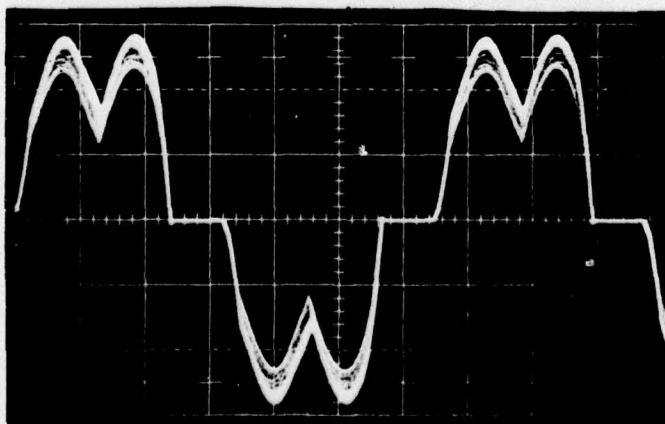


37.14 A rms

INVERTER LOAD 11 KW

PF=1.0 3φ 400 HZ

↓ 20 A / DIV. ↔ 100 μsec / DIV.



36.0 A rms

INVERTER LOAD 11 KW

PF=0.8 3φ 400 HZ

↓ 20 A / DIV. ↔ 100 μsec / DIV.

DISTRIBUTION:

15 KVA FREQUENCY CONVERTER

Test Results (Design Data) Item 0005

CDRL Item A002

Modification No. P0006

Contract No. DAAK02-72-C-0210

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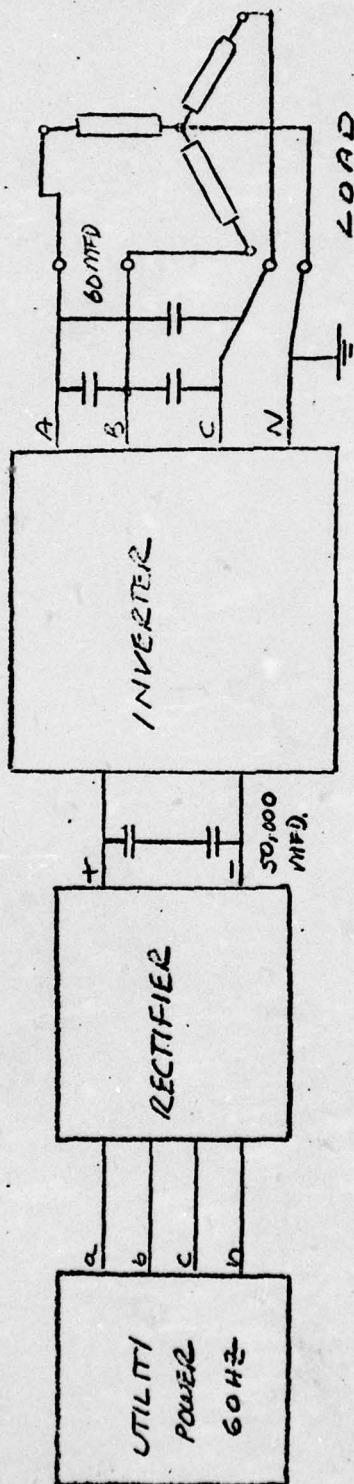
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APPROVED

CORRY 1/31/79



CONNECTIONS FOR 400 HZ, THREE PHASE POWER.
(STEP TRANSISTORS NOT CONNECTED)

FOR DATA ON PAGES 86-113

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GENERAL MOTORS CORPORATION

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TITLE

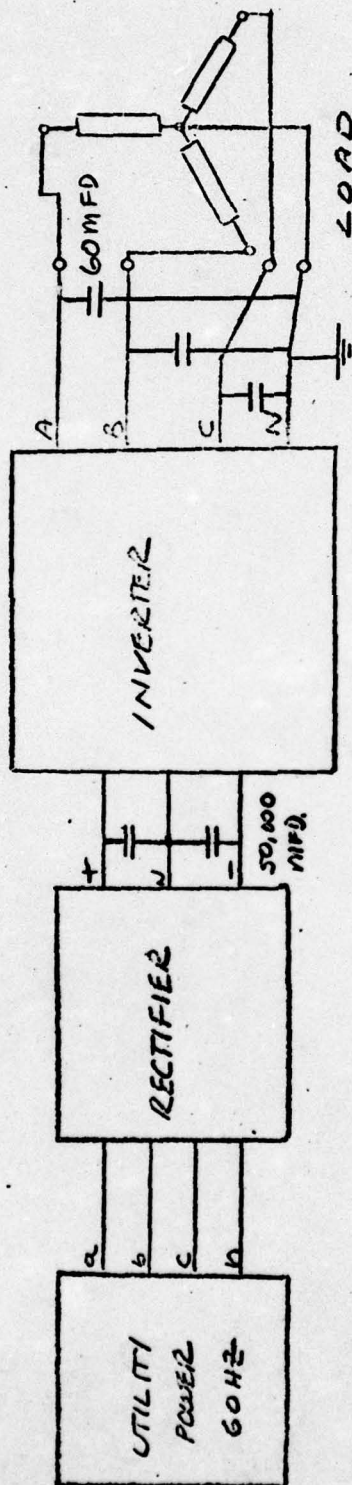
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1/31/74

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APPROVED



CONNECTIONS FOR 60 HZ, THREE PHASE POWER
FOR DATA ON PAGES 86-113

TITLE

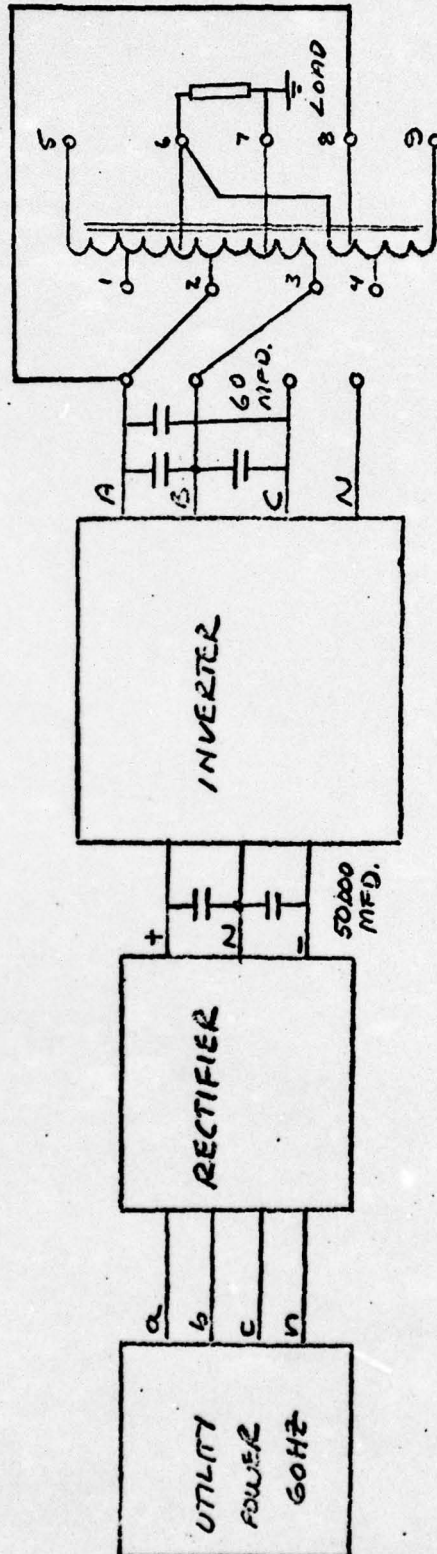
PREPARED

DATE

CHECKED

APPROVED

CORRY 1/31/74



CONNECTIONS FOR 400 HZ, SINGLE PHASE, TWO WIRE POWER
(STEP TRANSISTORS NOT CONNECTED)

FOR DATA ON PAGES 86-113

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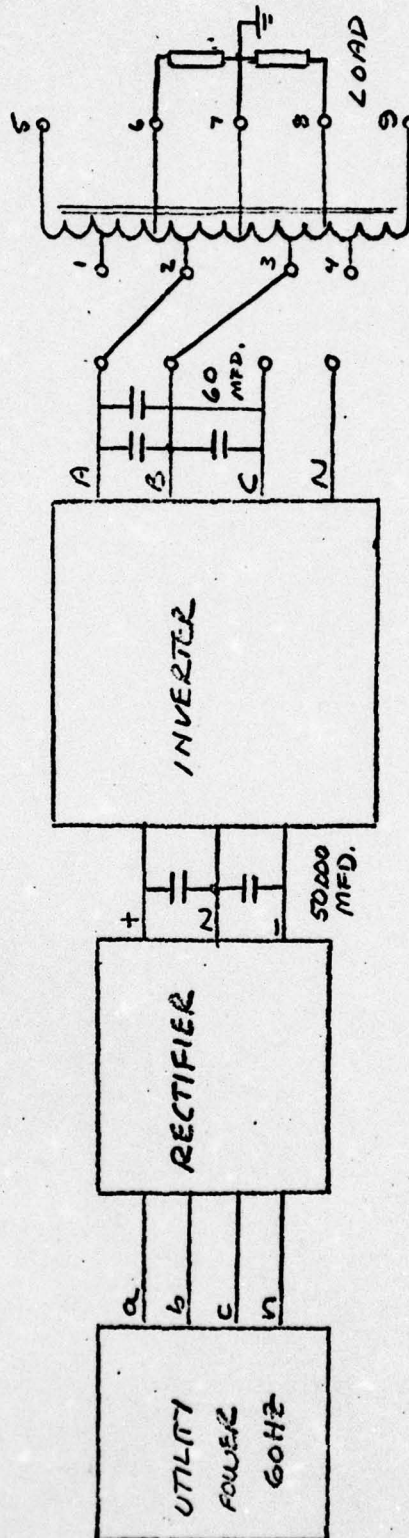
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CORRY 1/31/74

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SINGLE
PHASE TRANSFORMER

CONNECTIONS FOR 400 HZ, SINGLE PHASE, THREE WIRE POWER

(STEP TRANSISTORS NOT CONNECTED)

FOR DATA ON PAGES 86-113

DELCO ELECTRONICS

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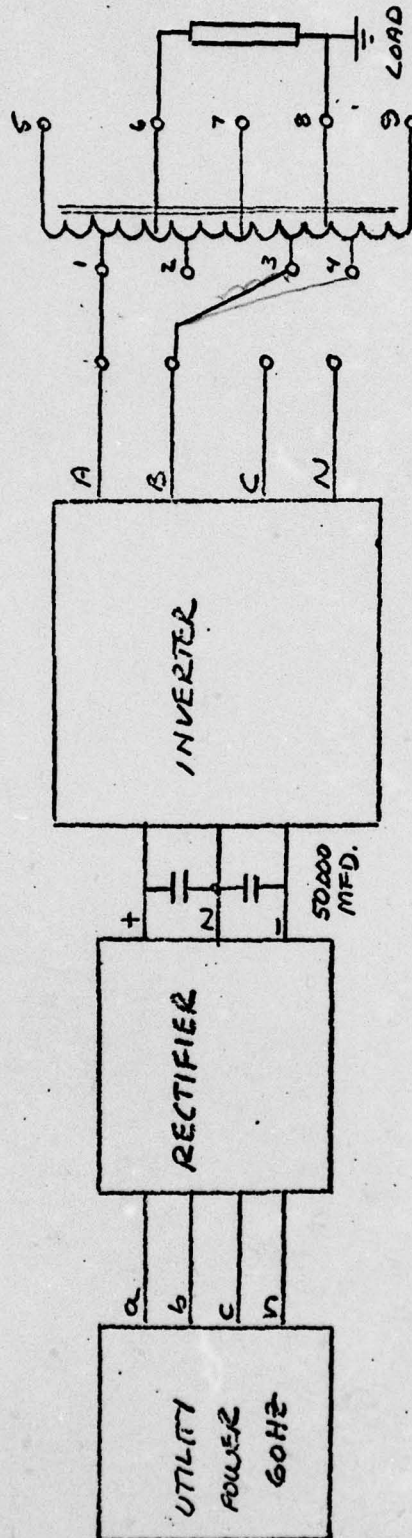
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CORR-1 1/29/74



SINGLE
PHASE TRANSFORMER

CONNECTIONS FOR 60 HZ, SINGLE PHASE, TWO WIRE POWER

FOR DATA ON PAGES 86-113

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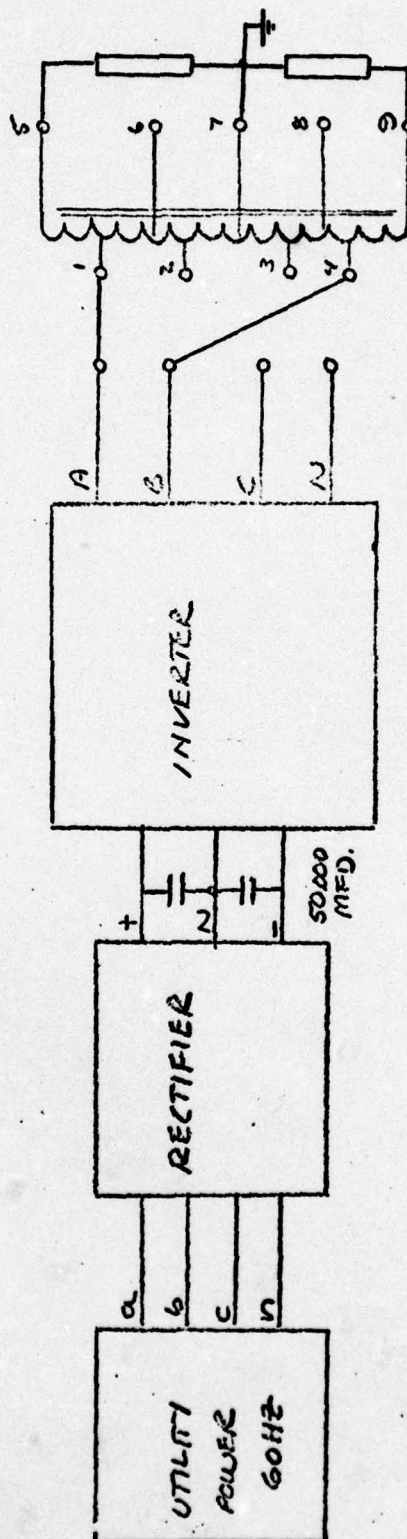
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SINGLE
PHASE TRANSFORMER

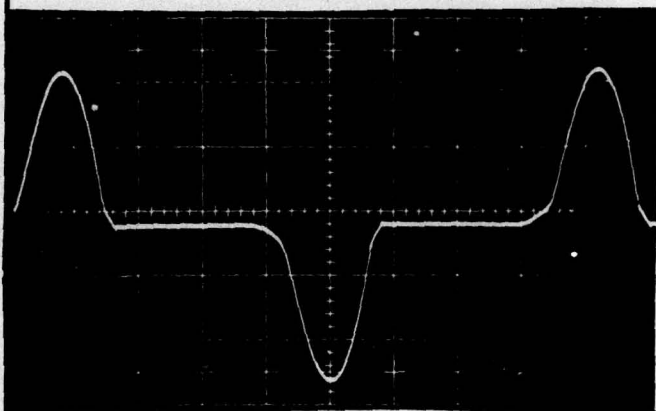
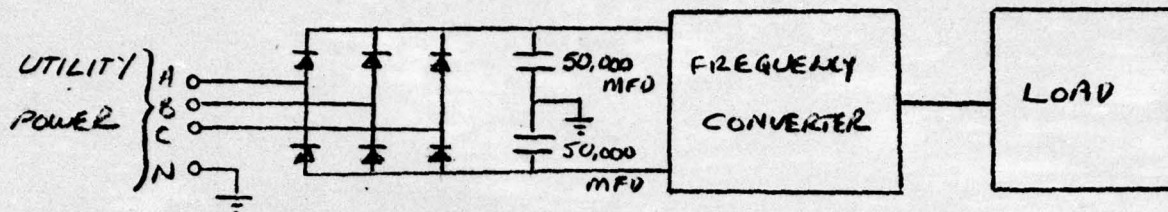
CONNECTIONS FOR 60 HZ, SINGLE PHASE, THREE WIRE POWER

FOR DATA ON PAGES 86-113

TITLE TEST RESULTS 15KVA FREQUENCY
CONVERTER ITEM 0005 CONTRACT
NO. DAAK02-72-C-0210

PREPARED CORRY DATE 1/23/79
CHECKED
APPROVED

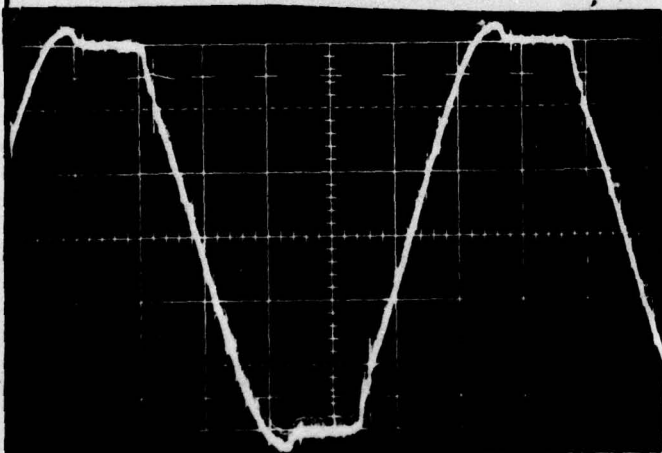
REFERENCE DESIGN TEST DATA



60 HZ UTILITY LINE
CURRENT I_A

↓ 50A/DIV.

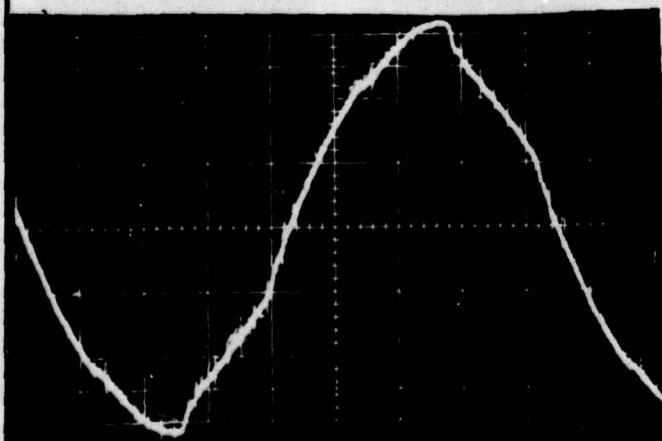
↔ 2ms/DIV.



UTILITY LINE-TO-NEUTRAL
VOLTAGE V_{A-N}

↓ 50V/DIV

↔ 2ms/DIV.



UTILITY LINE-TO-LINE
VOLTAGE V_{A-B}

↓ 100V/DIV.

↔ 2ms/DIV.

FREQUENCY CONVERTER
LOAD = 11KW, PF = 0.8, 400 HZ

TITLE

PREPARED

CORY

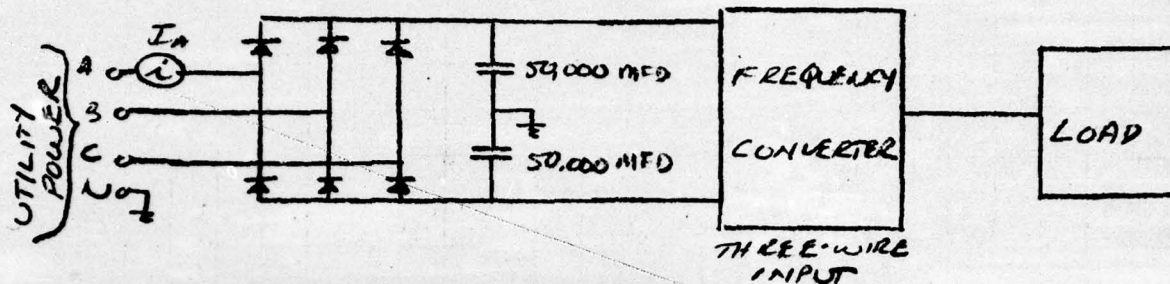
DATE

1/23/74

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APPROVED

CURRENT WAVEFORMS-POWER LINES AT INPUT TO RECTIFIER



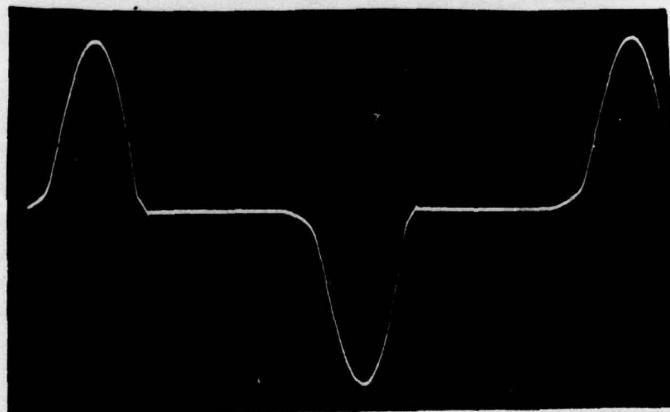
60 HZ UTILITY LINE
CURRENTS I_A



NO LOAD ON
FREQUENCY CONVERTER

↑ 10A/DIV. ↔ 2ms/DIV.

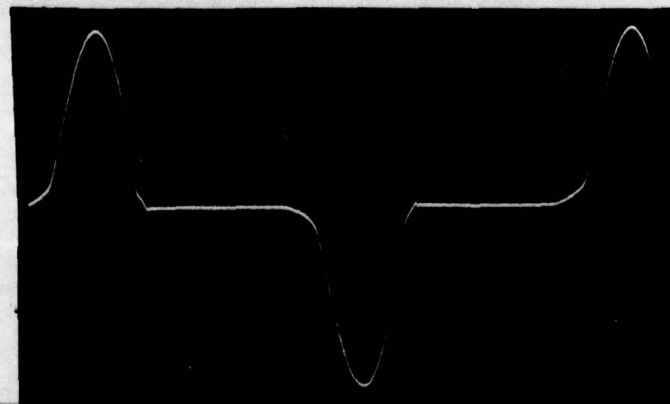
8.38 AMPS RMS



11KW, PF=1.0, 400 HZ
3Φ LOAD ON F.C.

↑ 50A/DIV. ↔ 2ms/DIV.

56.6 AMPS RMS



11KW, PF=0.8

↑ 50A/DIV. ↔ 2ms/DIV.

56 AMPS RMS

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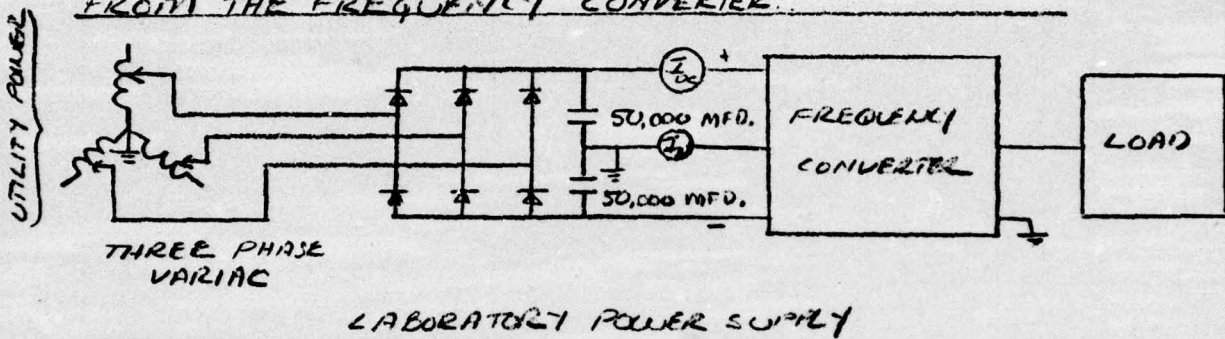
11/29/79

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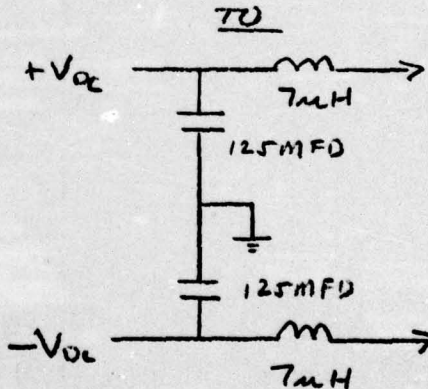
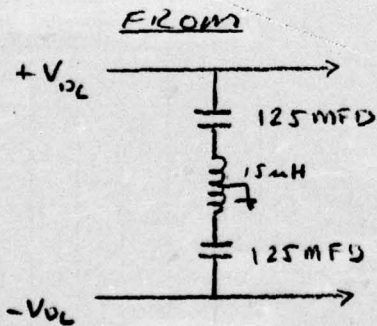
APPROVED

◦ INVESTIGATION OF THE PERFORMANCE OF THE
TURBO-ALTERNATOR FREQUENCY CONVERTER WHEN
OPERATED FROM A LABORATORY POWER SUPPLY.

◦ DEMONSTRATION OF 15KVA POWER CAPABILITY
FROM THE FREQUENCY CONVERTER.



FREQUENCY CONVERTER INPUT CHANGED



FOR $\frac{di}{dt}$ PROTECTION WHEN OPERATING
FROM THE LABORATORY POWER SUPPLY

(REACTIVE RETURN DIODES CONNECTED TO POWER
SOURCE SIDE OF 7mH INDUCTORS SHOWN ABOVE)

DISTRIBUTION:

TITLE

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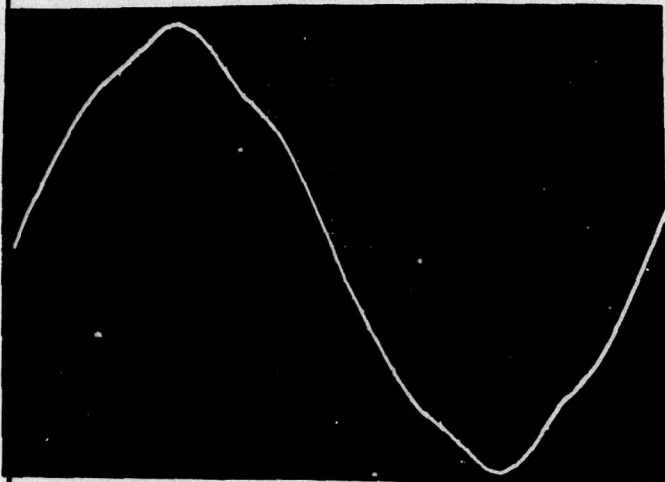
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FREQUENCY CONVERTER OUTPUT VOLTAGES



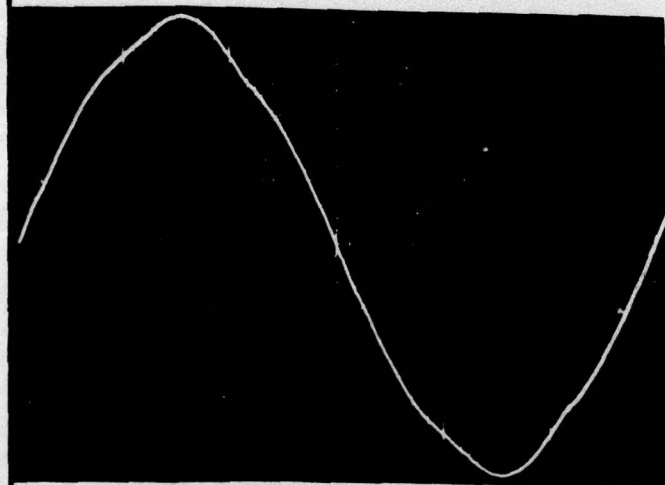
400 HZ THREE PHASE
(NO TRANSISTORS)

L-T-N VOLTAGES

NO LOAD

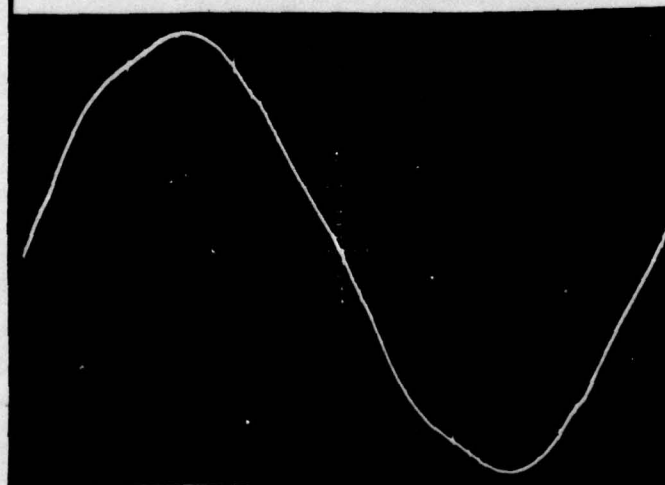
THD = 3.68%

50V/DIV.



16 KW, PF = 1.0

THD = 2.44%



16 KW, PF = 0.8

THD = 2.8%

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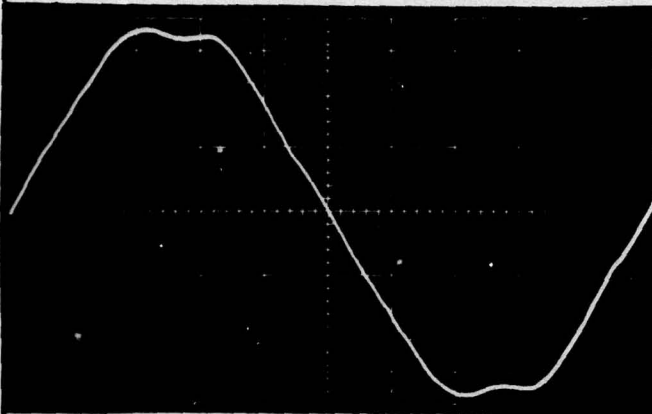
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FREQUENCY CONVERTED OUTPUT VOLTAGES



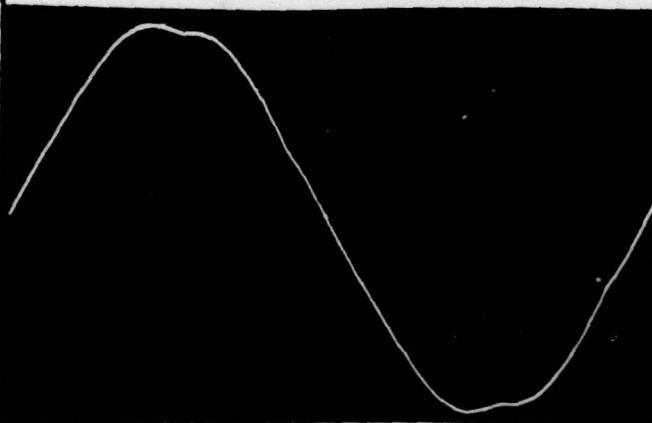
400Hz THREE PHASE
(NO TRANSISTORS)

L-T-L VOLTAGES

NO LOAD

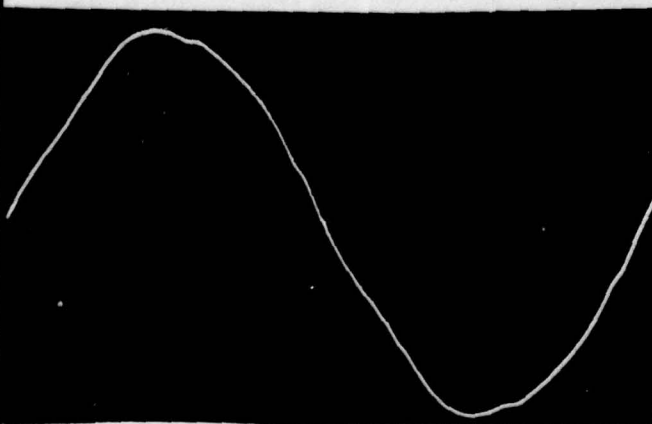
THD = 3.68%

100V/DIV.



16KW, PF = 1.0

THD = 2.44%



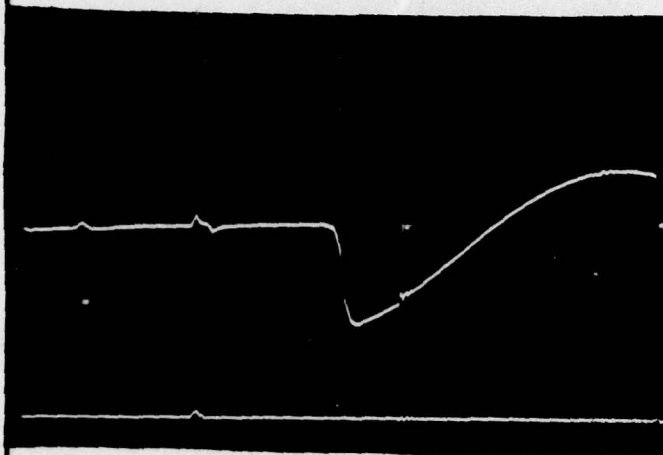
16KW, PF = 0.8

THD = 2.8%

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POWER CENTER THYRISTOR REVERSE
COMMUTATION VOLTAGE AND ANODE CURRENT



400 HZ THREE PHASE
NO LOAD

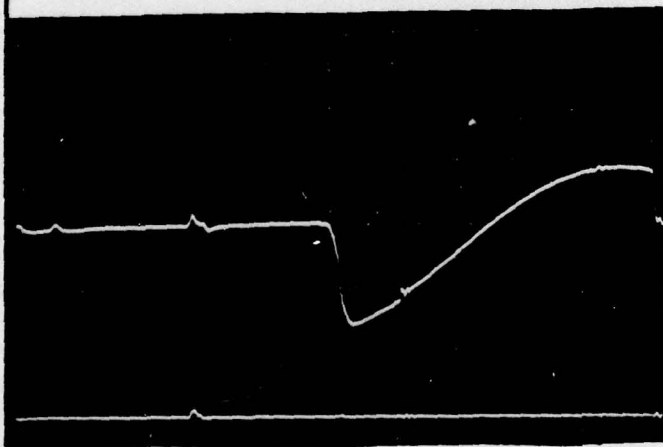
THYRISTOR ANODE VOLTAGE

↑ 50V/DIV.

← 10 μSEC/DIV.

ANODE CURRENT

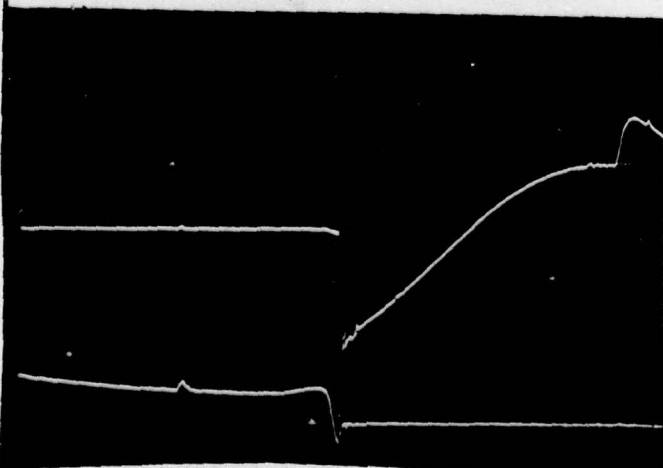
↑ 50A/DIV.



16 KW, PF = 1.0

THYRISTOR ANODE VOLTAGE

ANODE CURRENT



16 KW, PF = 0.8

THYRISTOR ANODE VOLTAGE

ANODE CURRENT

(COMMUTATION ROOT VOLTAGE = ± 2.8VDC)

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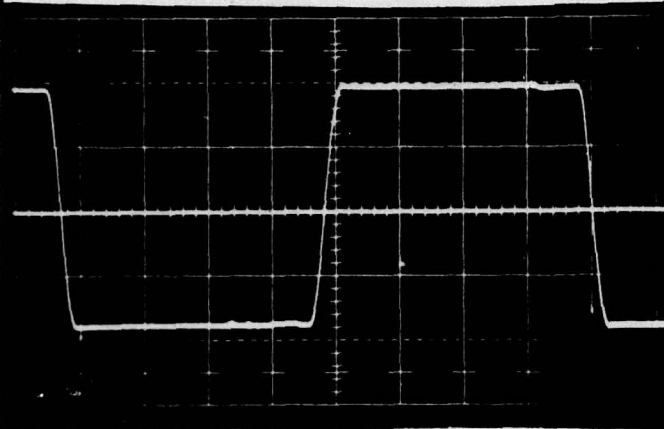
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POWER CENTER COMMUTATION CAPACITOR VOLTAGE



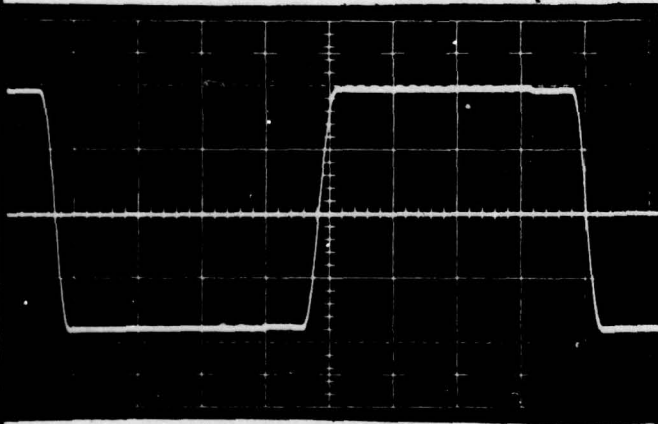
400 HZ THREE PHASE

COMMUTATION CAPACITOR VOLTAGE

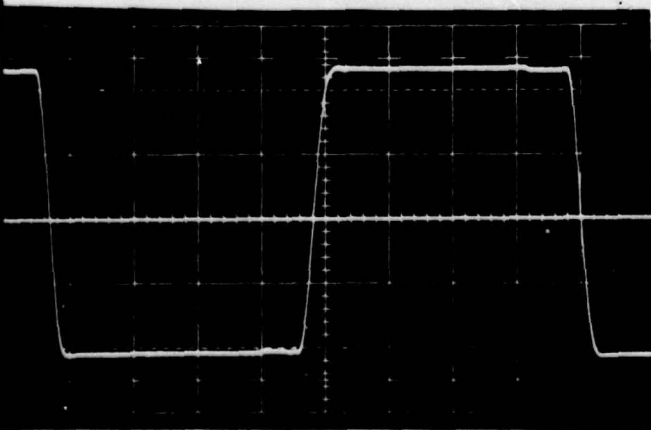
NO LOAD

↓ 50V / DIV.

↔ 100 μSEC / DIV.



16KW, PF=1.0



16KW, PF=0.8

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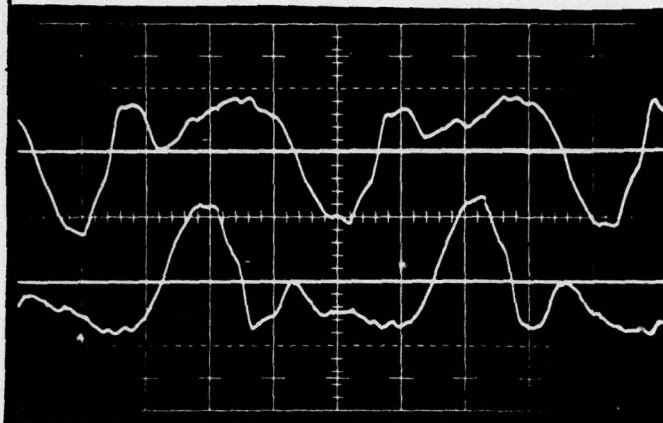
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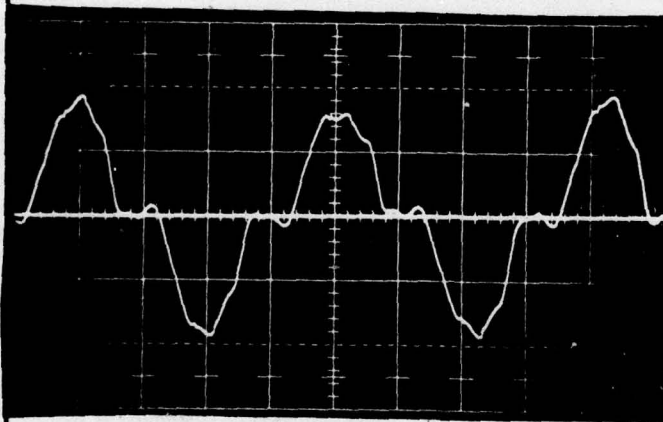
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FREQUENCY CONVERTER INPUT CURRENTS

400HZ THREE PHASE
NO LOAD

↓ 50A / DIV.

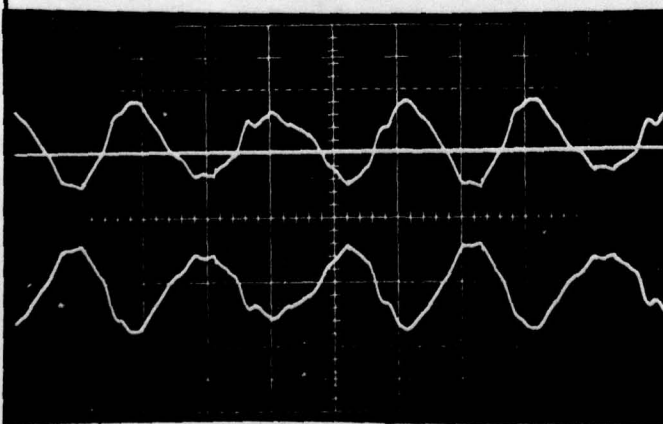
↔ 200 μSEC / DIV.



NEUTRAL CURRENT

↓ 50A / DIV.

↔ 200 μSEC / DIV.

+ INPUT CURRENTS
WITH NEUTRAL
NOT CONNECTED.

↓ 50A / DIV.

↔ 200 μSEC / DIV.

DISTRIBUTION:

TITLE

PREPARED

CORY

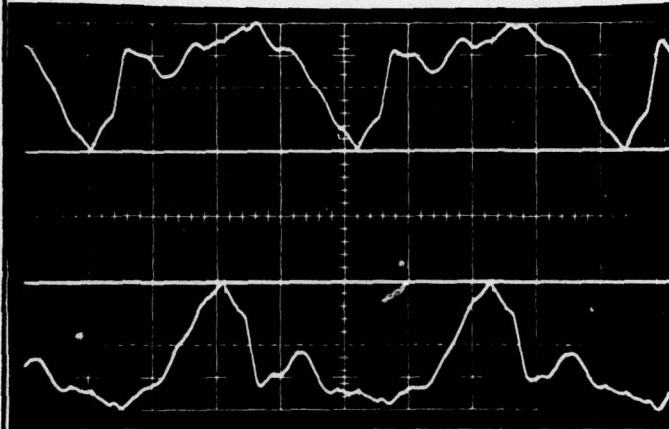
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FREQUENCY CONVERTER INPUT CURRENTS



400 HZ THREE PHASE

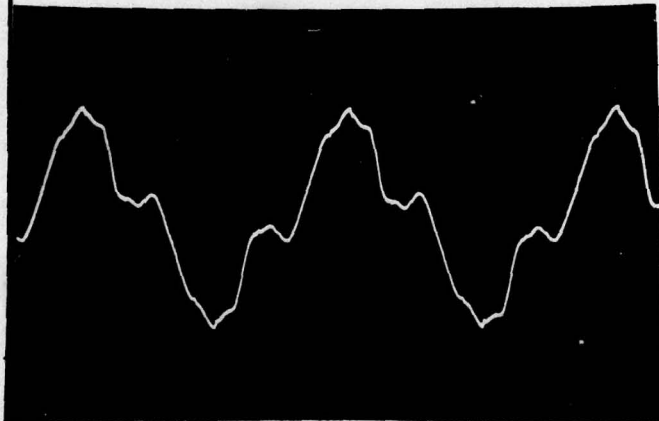
+

16 kW, PF=1.0

-0

↓ 50 A/DIV.

↔ 200 μSEC/DIV.

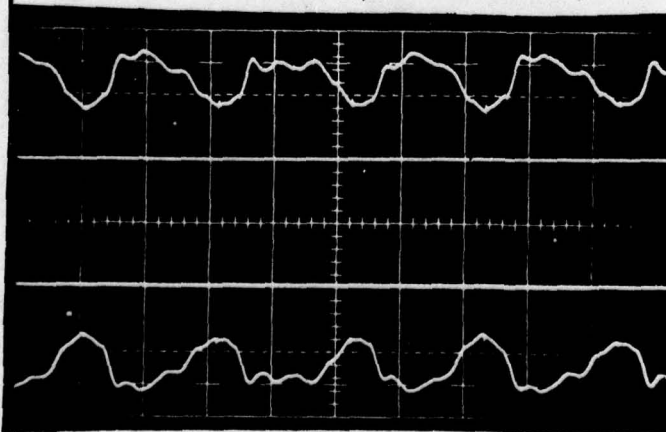


+

-0

NEUTRAL CURRENT

-



+

-0

-0

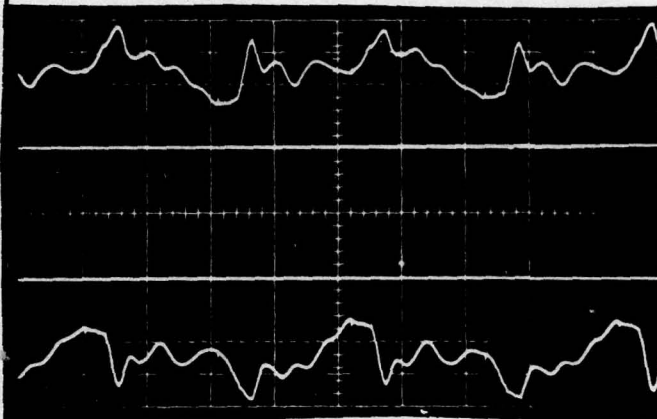
-

± INPUT CURRENTS
WITH NEUTRAL
NOT CONNECTED.

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FREQUENCY CONVERTED INPUT CURRENTS

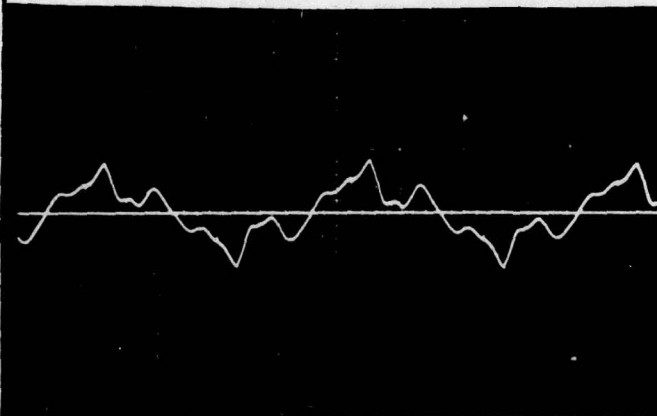


400 HZ THREE PHASE

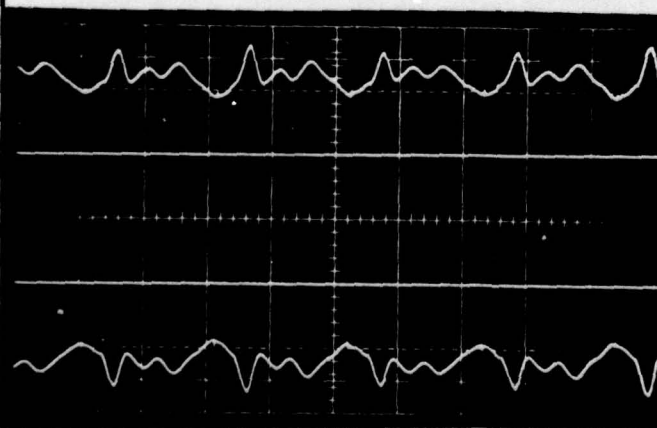
16 KW, PF = 0.8

↓ 50 A/DIV.

↔ 200 μ SEC/DIV.



NEUTRAL CURRENT



± INPUT CURRENTS
WITH NEUTRAL
NOT CONNECTED

DISTRIBUTION:

TITLE

PREPARED

CORRY

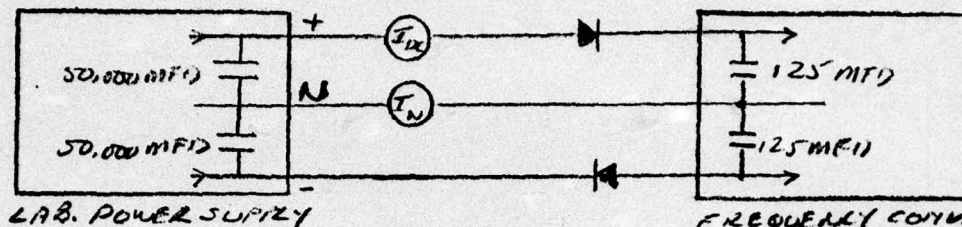
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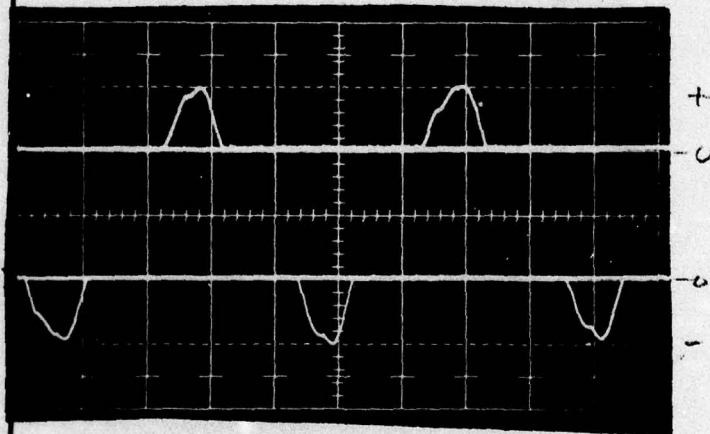
APPROVED

FREQUENCY CONVERTER INPUT CURRENTS



INVESTIGATION OF THE EFFECT DIODES IN SERIES WITH
THE \pm VOLTAGE LINES HAVE ON INPUT CURRENT WAVESHAPES.

(SYSTEM WORKS WITH NEUTRAL DISCONNECTED BUT THD
INCREASES ABOUT 0.5%)

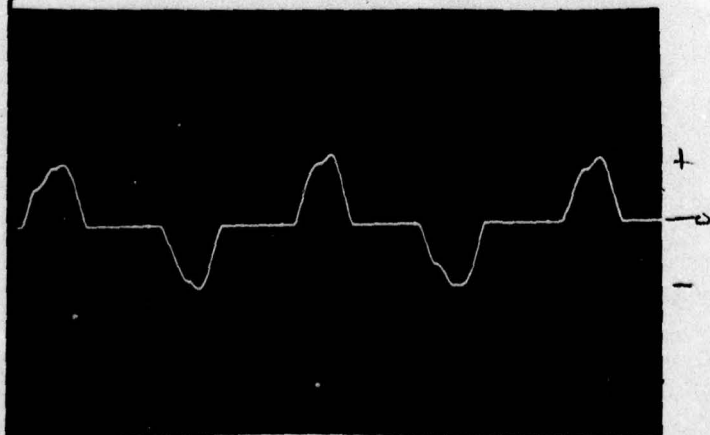


400 HZ THREE PHASE

NO LOAD

50A/DIV.

200μSEC/DIV.



NEUTRAL CURRENT

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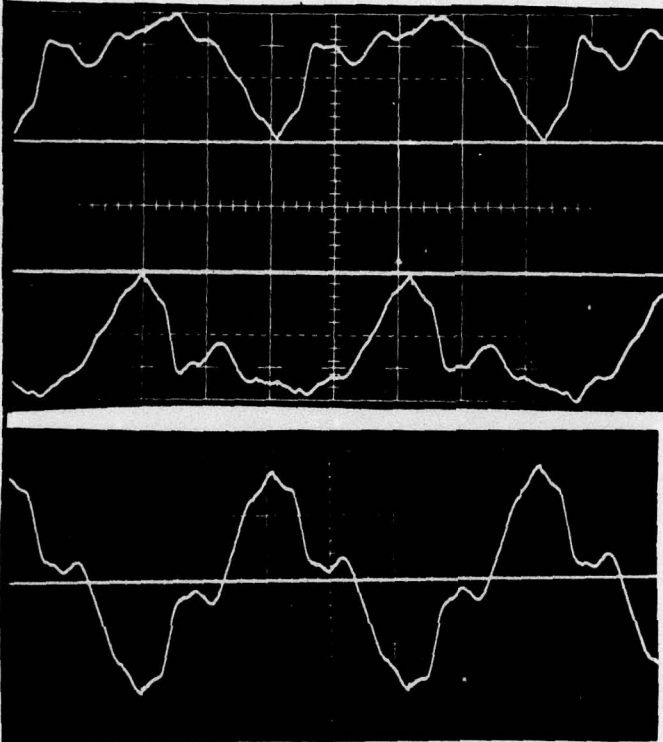
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FREQUENCY CONVERTER INPUT CURRENTS



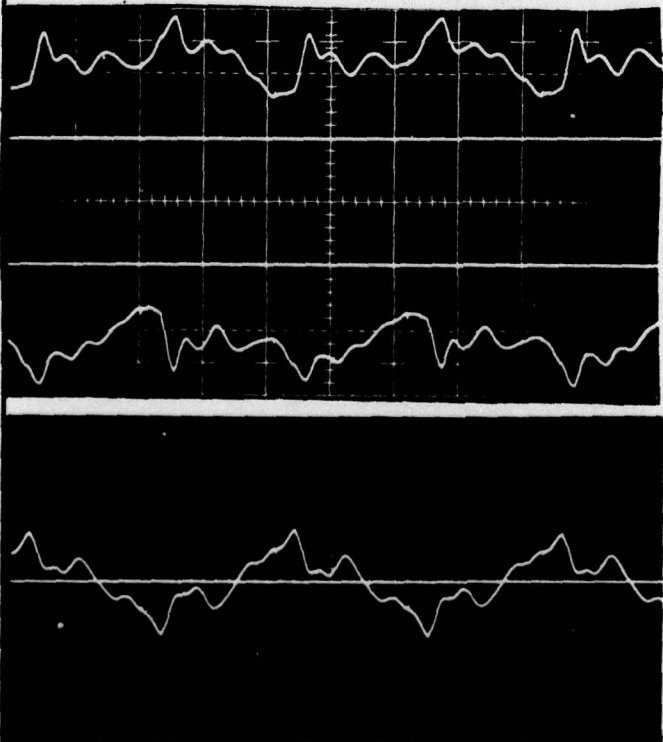
400 HZ THREE PHASE
(DIODES IN SERIES WITH
± VOLTAGE LINES)

16 KW, PF = 1.0

↕ 50A/DIV.

← 200 μSEC/DIV.

NEUTRAL CURRENT



16 KW, PF = 0.8

NEUTRAL CURRENT

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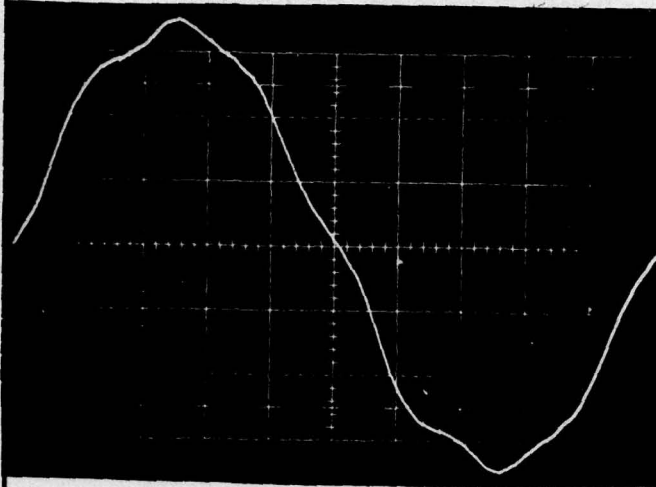
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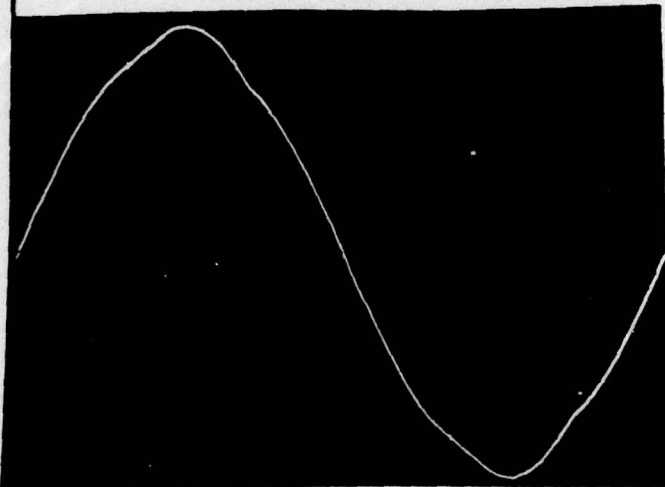
OUTPUT VOLTAGES FOR CIRCUIT ON PAGE 94

400HZ THREE PHASE
L-T-N VOLTAGES

NO LOAD

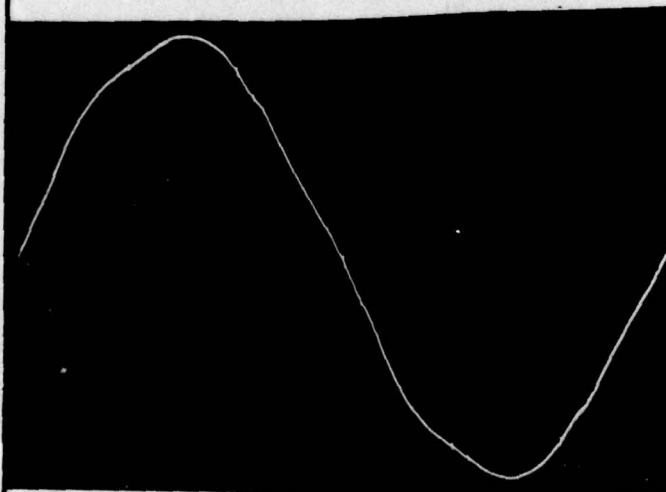
THD = 4.97%

↑ 50V/DIV.



16KW, PF = 1.0

THD = 2.44%



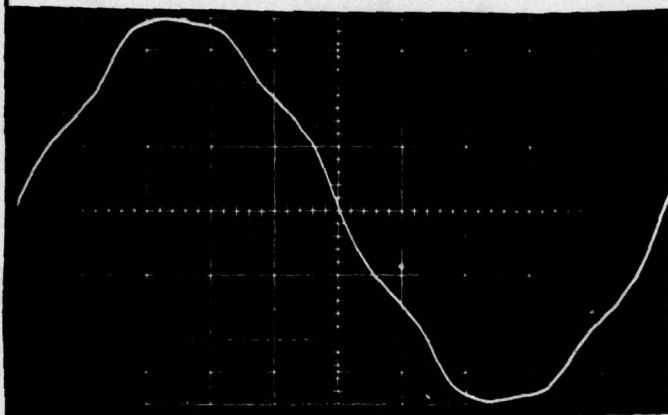
16KW, PF = 0.8

THD = 2.83%

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OUTPUT VOLTAGES FOR CIRCUIT ON PAGE 95

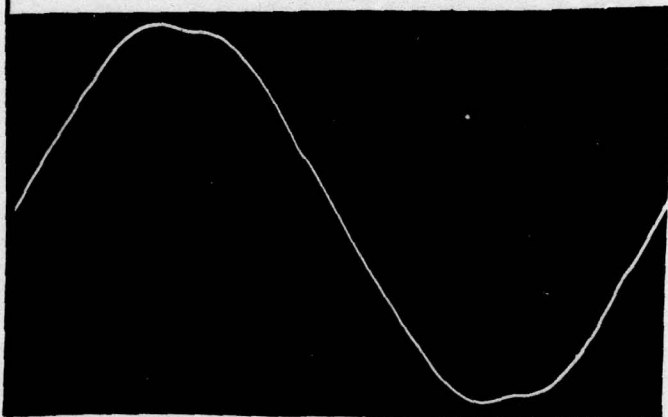


400 HZ THREE PHASE
L-T-L VOLTAGES

NO LOAD

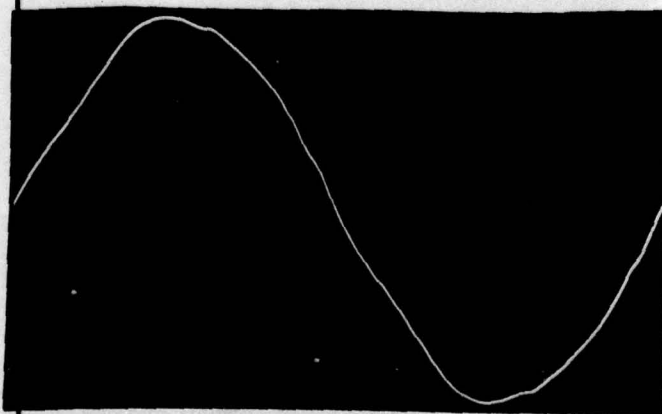
THD = 4.95%

↑ 100V/DIV.



16 KW, PF = 1.0

THD = 2.42%

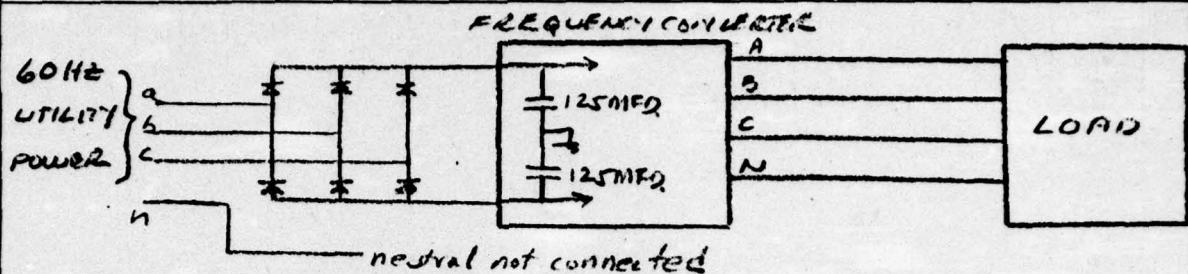


16 KW, PF = 0.8

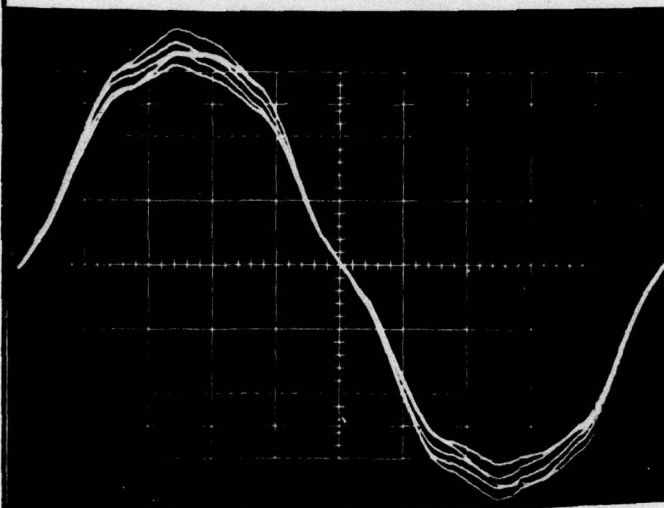
THD = 2.81%

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APPLYING 60Hz 3 ϕ POWER DIRECTLY TO FREQUENCY CHANGER INPUT. INVESTIGATION OF THE EFFECTS OF DC POWER SUPPLY RIPPLE ON FREQUENCY CONVERTER OUTPUT VOLTAGES.

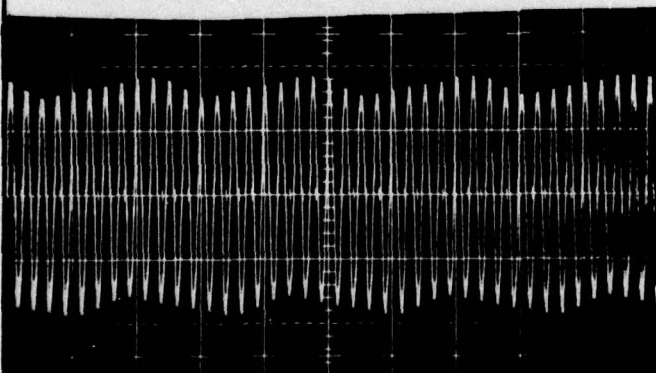


400Hz THREE PHASE
L-T-N VOLTAGES

NO LOAD
THD = 7%

↓ 50V/DIV

(FREQUENCY CONVERTER -
NO TRANSISTORS - 60mF L-T-L
IN OUTPUT)



SAME AS ABOVE
BUT ↓ 100V/DIV
AND ↔ 10ms/DIV.

(NOTE: RIPPLE FREQUENCY
≈ 40Hz AND MAGNI-
TUDINE ≈ 35VOLTS.)

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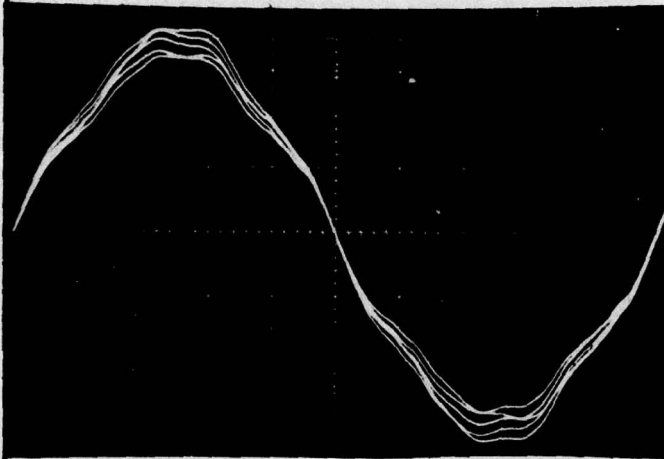
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OUTPUT VOLTAGES FOR CIRCUIT ON PAGE 98

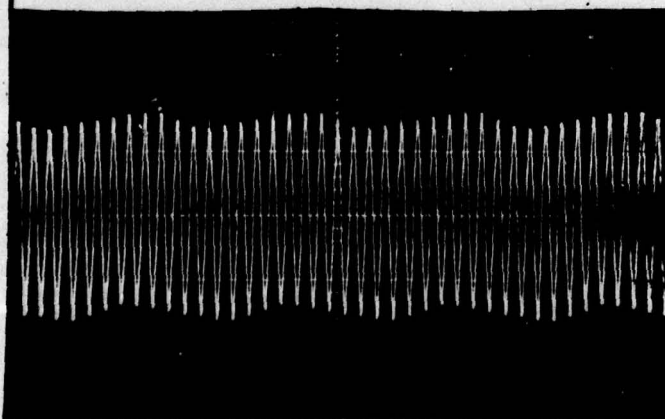


400 HZ THREE PHASE
L-T-L VOLTAGES

NO LOAD

THD = 7%

↕ 100V / DIV.



SAME AS ABOVE
BUT ↕ 200V / DIV.
↔ 10MS / DIV.

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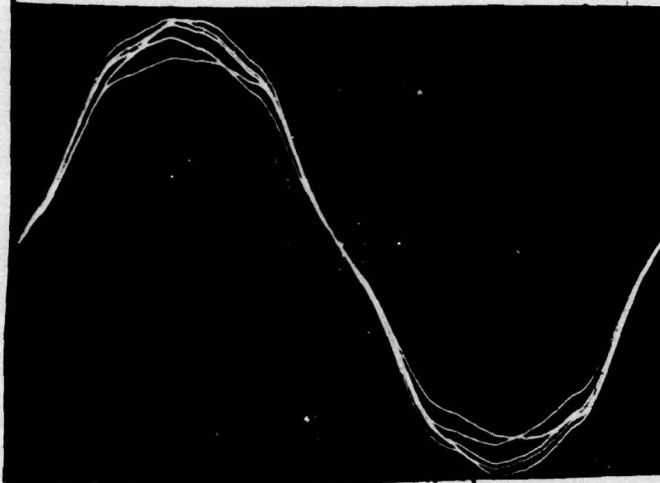
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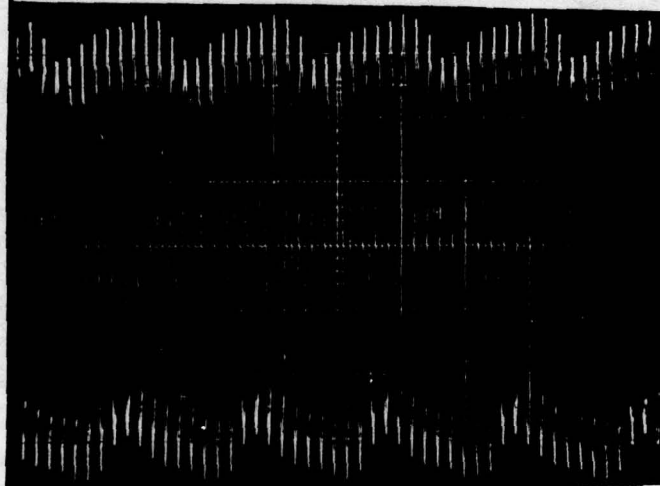
OUTPUT VOLTAGES FOR CIRCUIT ON PAGE 99

400HZ THREE PHASE
L-T-N VOLTAGES

11KW, PF = 1.0

THD = 7.3%

↑ 50V / DIV.

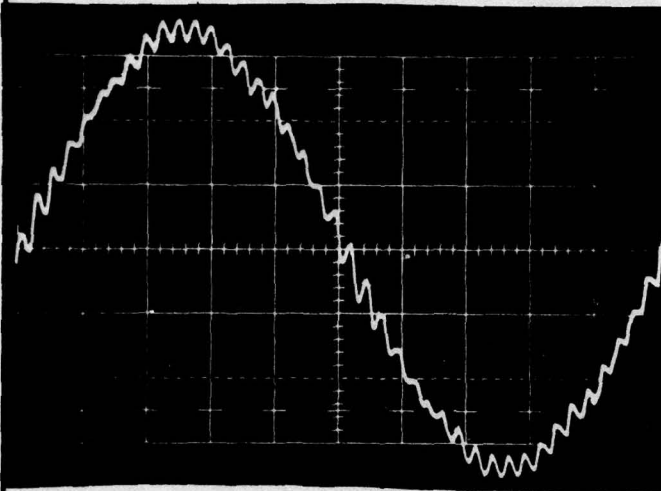
SAME AS ABOVE
← UNCALIBRATED

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(NOTE: CONNECTING INPUT REG. NEUTRAL INCREASE STEP TRANS-
FORMER NOISE LEVEL, BUT REDUCES LOW FREQ. AMPLITUDE
MODULATION LEVEL. NEUTRAL CURRENT HIGH.)

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FREQUENCY CONVERTER OUTPUT VOLTAGES

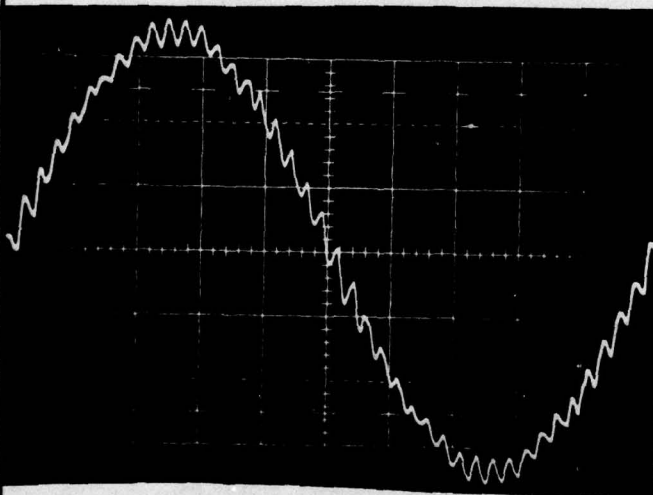


60HZ THREE PHASE
(60 MFD L-T-L)
L-T-N VOLTAGES

NO LOAD

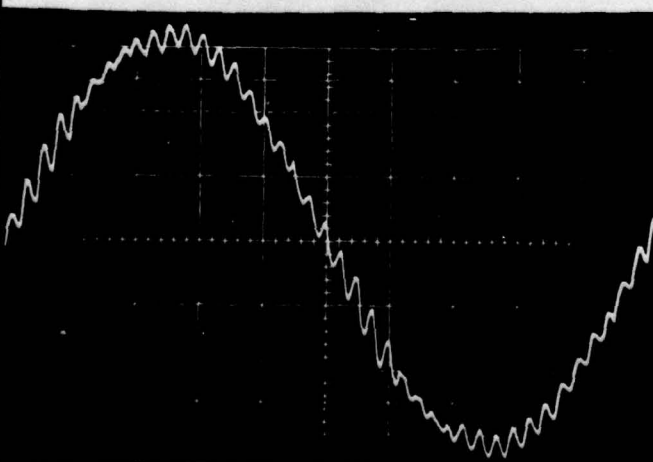
THD = 5%

50V/DIV.



16KW, PF=1.0

THD = 5.2%



16KW, PF=0.8

THD = 5.38%

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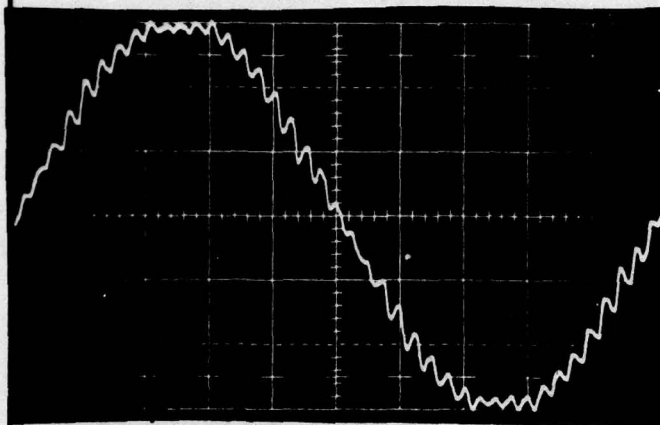
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FREQUENCY CONVERTER OUTPUT VOLTAGES

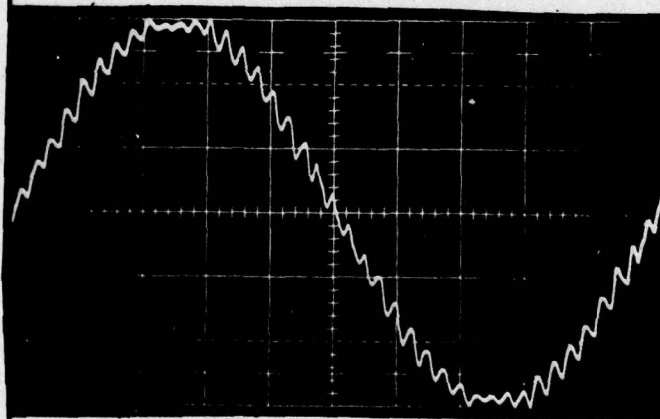


60 HZ THREE PHASE
(60 MFD L-T-L)
L-T-L VOLTAGES

NO LOAD

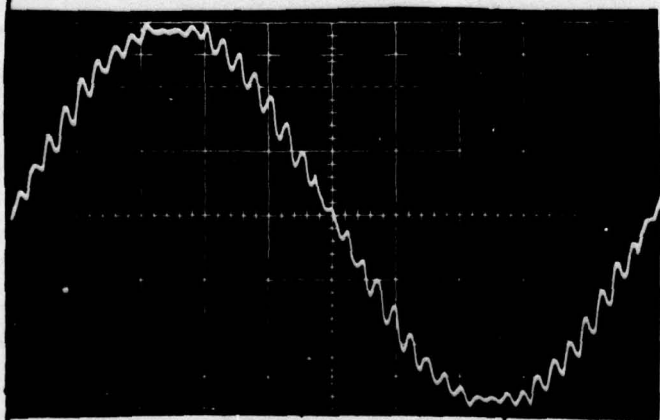
THD = 4.8%

100V/DIV.



16KW, PF = 1.0

THD = 5.0%



16KW, PF = 0.8

THD = 5.18%

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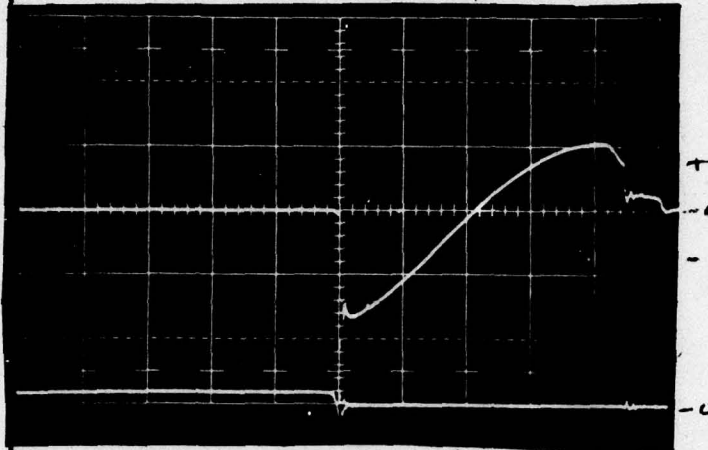
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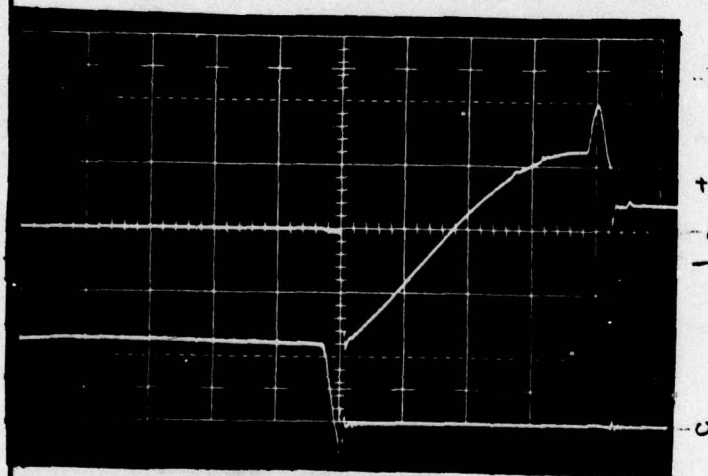
POWER CENTER THYRISTOR REVERSE COMMUTATION VOLTAGE AND ANODE CURRENT



60 HZ THREE PHASE
NO LOAD
THYRISTOR ANODE VOLTAGE

↑ 50V/DIV.
← 10 μsec/DIV.

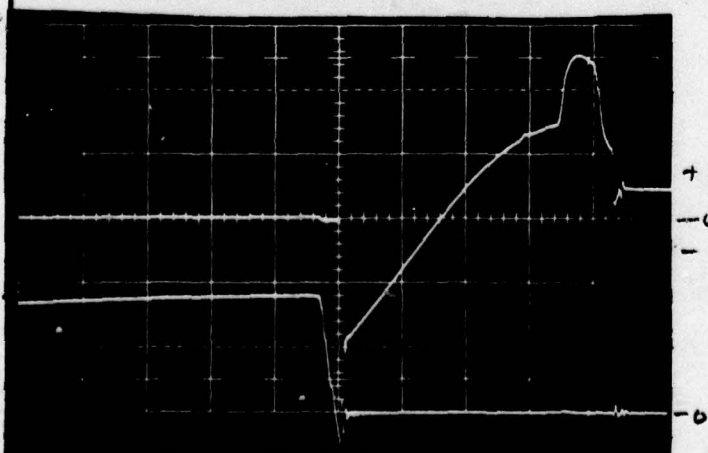
ANODE CURRENT
↑ 50 A/DIV.



16 KW, PF=1.0

THYRISTOR ANODE VOLTAGE

ANODE CURRENT



16 KW, PF=0.8

THYRISTOR ANODE VOLTAGE

ANODE CURRENT

DISTRIBUTION:

(COMMUTATION) BOOST VOLTAGE = ±25VDC. 60 HZ 2-T-L

DP 345 REV. 12-66

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POWER CENTER COMMUTATION CAPACITOR VOLTAGE

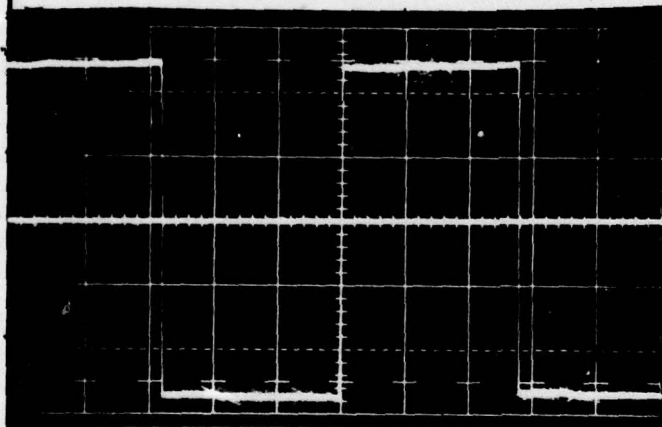
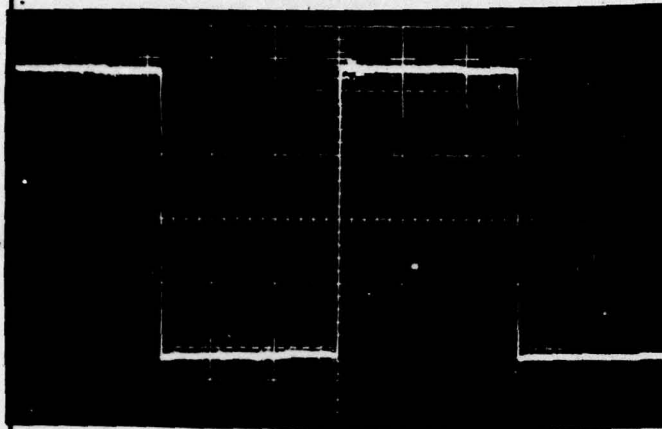
60 HZ THREE PHASE

COMMUTATION CAPACITOR VOLTAGE

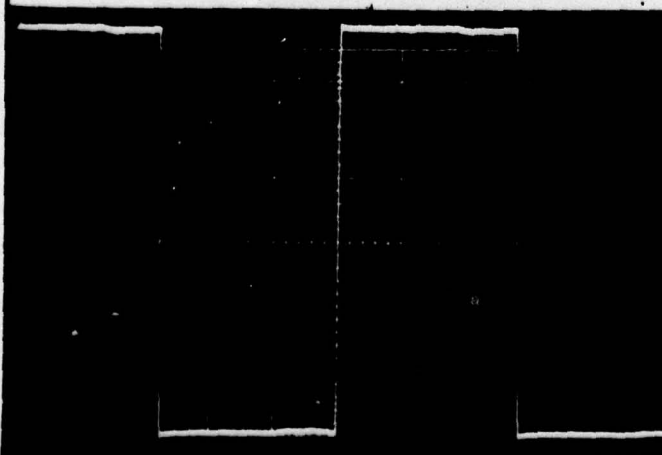
NO LOAD

↑ 50V/DIV.

← 1 MS/DIV.



16KW, PF=1.0



16KW, PF=0.8

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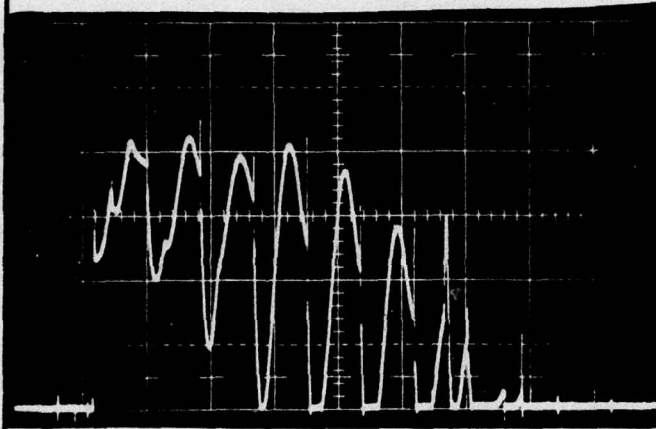
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STEP COMMUTATION TRANSISTOR CURRENTS



60 HZ THREE PHASE

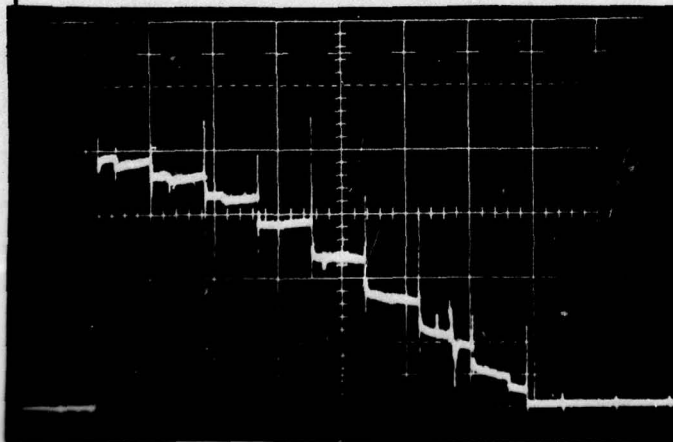
COMMUTATION TRANSISTOR
CURRENTSLOAD = 16KW, PF = 0.8

WITH 60 MFD L-T-L

IN OUTPUT OF

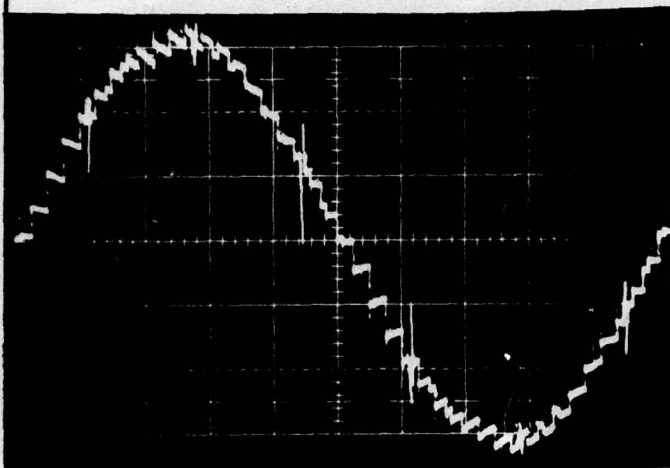
FREQUENCY CONVERTER

↓ 20A/DIV. ↔ 500μSEC/DIV.

60 MFD L-T-L CAPACITORS
REMOVED.

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OUTPUT VOLTAGES WITH 60 MFD. L-T-L CAPACITORS REMOVED

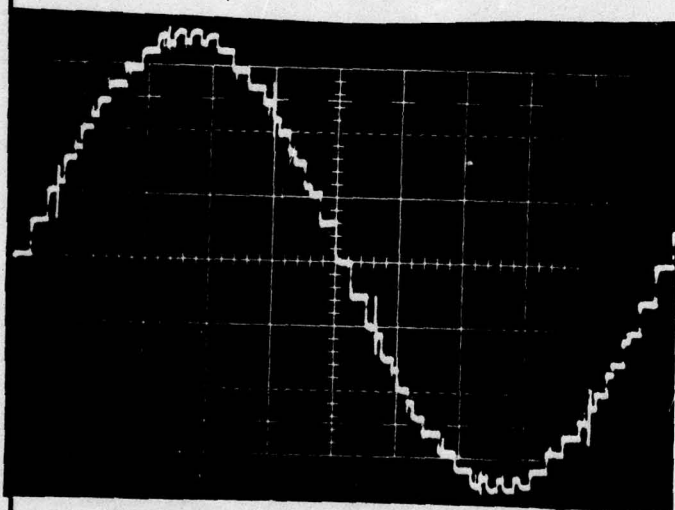


60 HZ THREE PHASE
L-T-N VOLTAGES

NO LOAD

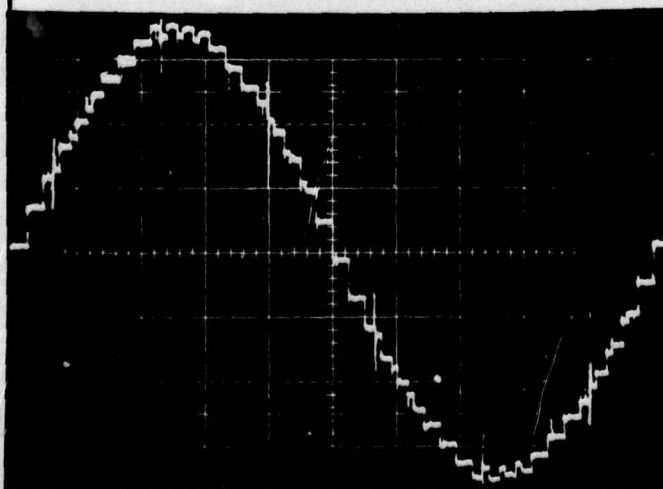
THD = 4.9%

50V/DIV.



16 KW, PF = 1.0

THD = 3.8%



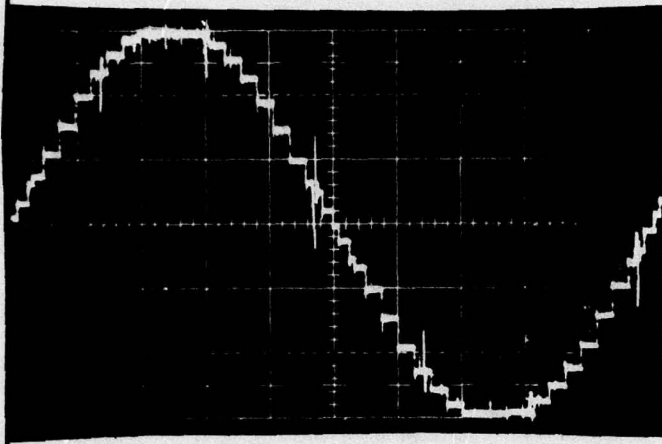
16 KW, PF = 0.8

THD = 4.2%

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OUTPUT VOLTAGES WITH 60 MFD L-T-L CAPACITORS REMOVED

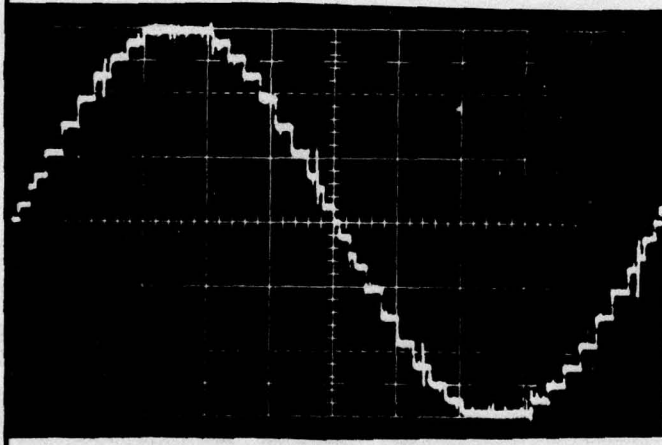


60 HZ THREE PHASE
L-T-L VOLTAGES

NO LOAD

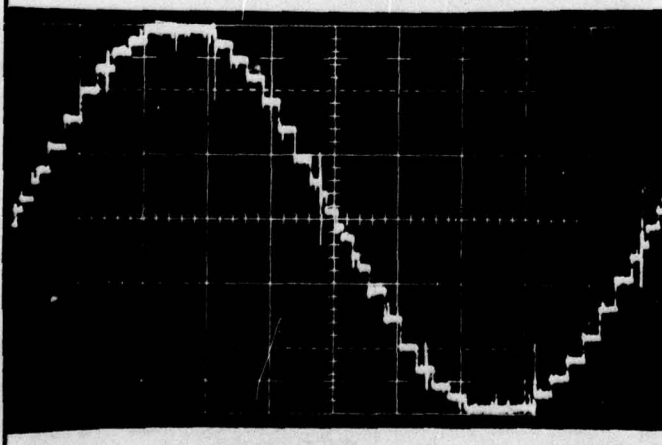
THD = 4.9%

100V/DIV.



16KW, PF=1.0

THD = 3.8%



16KW, PF=0.8

THD = 4.2%

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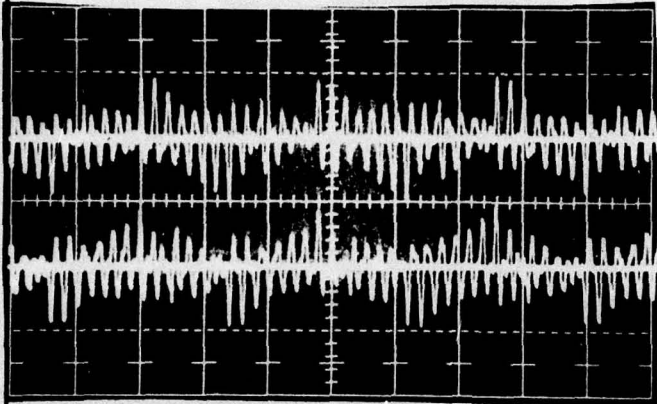
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FREQUENCY CONVERTER INPUT CURRENTS (60 MFD. L-T-L IN OUTPUT)

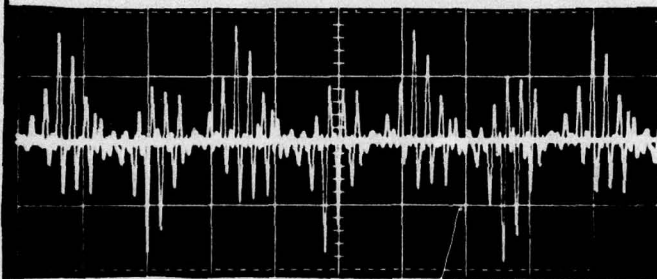


60HZ THREE PHASE

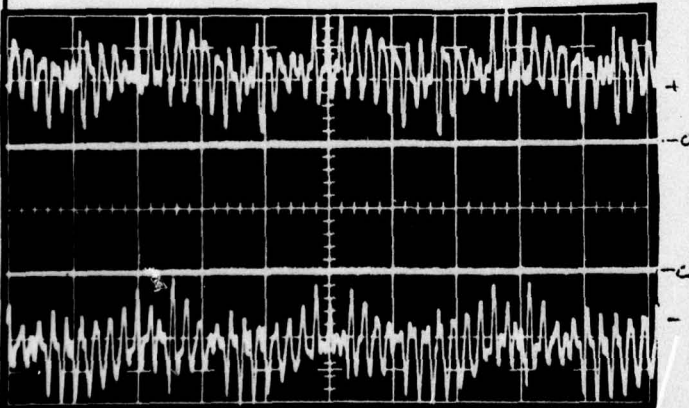
NO LOAD

↓ 50A / DIV.

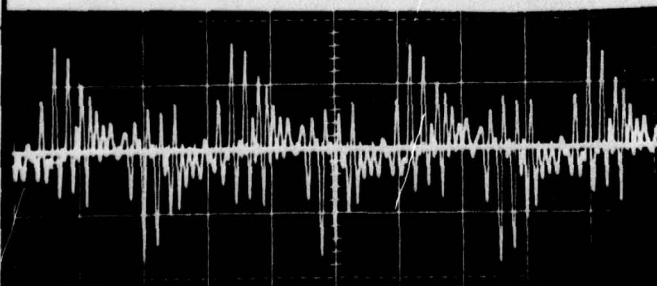
↔ 2ms / DIV.



NEUTRAL CURRENT



16KW, PF=1.0



NEUTRAL CURRENT

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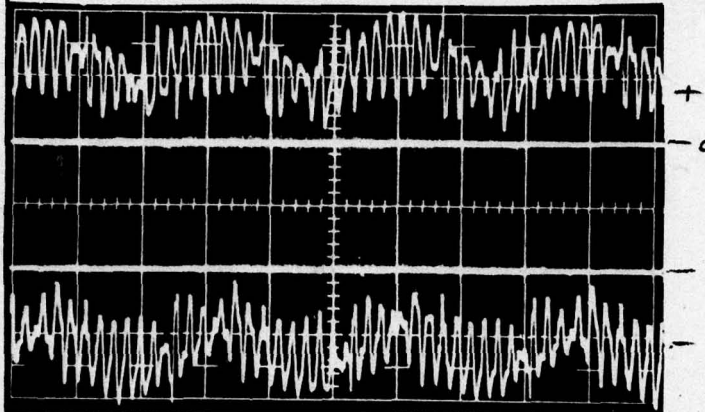
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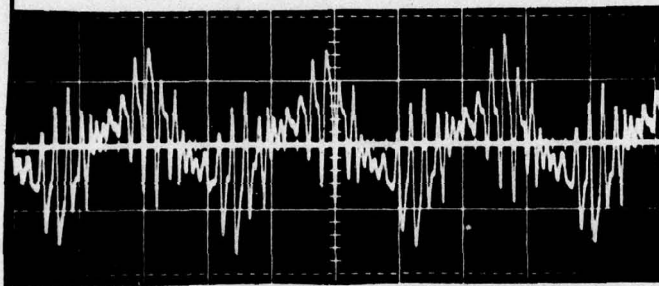
FREQUENCY CONVERTER INPUT CURRENTS



16KW, PF=0.8

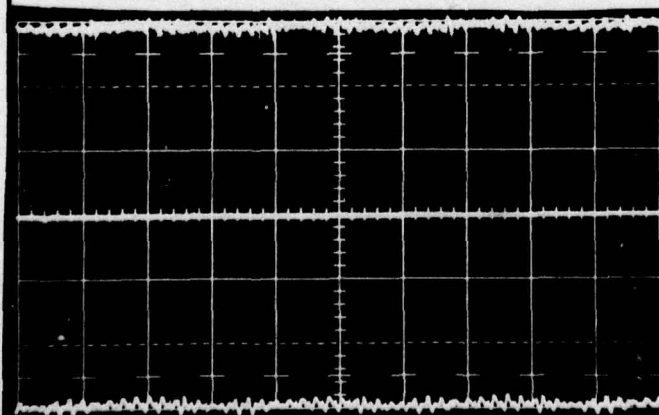
↓ 50A/DIV.

← 2ms/DIV.



0 NEUTRAL CURRENT

FREQUENCY CONVERTER INPUT VOLTAGES



± INPUT VOLTAGES

16KW, PF=0.8

↓ 50V/DIV.

← 2ms/DIV.

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INHERENT VOLTAGE DROOP

FREQUENCY CONVERTER OPERATED FROM LABORATORY
POWER SUPPLY. THREE PHASE OUTPUTS.

INPUT VOLTAGE Vdc	INPUT CURRENT A dc	LOAD KW, 0.8 PF	OUTPUT VOLTAGE Vrms	FREQ. HZ
281.1	6.0	—	120.0	400
↓	14.0	2.2	119.4	↓
	21.5	4.4	118.7	
	29.0	6.6	117.8	
	43.0	11.0	116.4	
↓	58.5	16.0	113.2	↓
286.8	1.0	—	120	60
↓	8.8	2.2	119.3	↓
	16.5	4.4	118.6	
	24.1	6.6	117.9	
	39.0	11.0	117.0	
↓	56.7	16.0	115.7	↓

400 HZ VOLTAGE DROOP

$$\frac{120 - 113.2}{113.2} \times 100 = \underline{\underline{6\%}}$$

60 HZ VOLTAGE DROOP

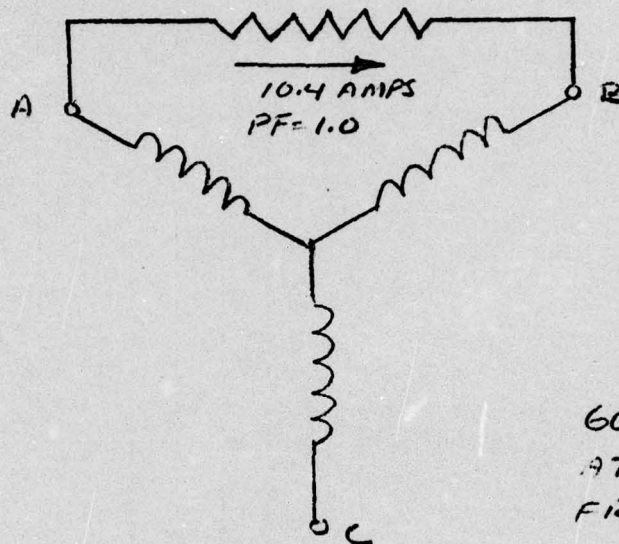
$$\frac{120 - 115.7}{115.7} \times 100 = \underline{\underline{3.7\%}}$$

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VOLTAGE UNBALANCE WITH UNBALANCED LOAD

FREQUENCY CONVERTER OPERATED FROM
LABORATORY POWER SUPPLY.



60 MFD L-T-L
AT OUTPUT OF
FREQUENCY
CONVERTER

	400 HZ V _{RMS}	60 HZ V _{RMS}
V _{AB}	208.29	208.10
V _{BC}	209.6	209.66
V _{CA}	211.20	210.26
V _{AN}	121.18	120.60
V _{BN}	120.30	120.69
V _{CN}	121.8	121.60

400 HZ UNBALANCE

$$\frac{211.20 - 208.29}{208} \times 100 = \underline{1.4\%}$$

60 HZ UNBALANCE

$$\frac{210.26 - 208.1}{208} \times 100 = \underline{1.04\%}$$

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EFFICIENCY - FREQUENCY CONVERTER ENERGIZED
BY LABORATORY POWER SUPPLY

FREQ HZ	V _{IN} V _{AC}	I _{IN} A _{DC}	INPUT POWER WATTS	V _O V _{RMS}	I _P V _{RMS}	OUTPUT POWER WATTS	P.F.	LOSSES WATTS	EFF. % ^{II}
400	280.5	6.0	1683	119.8	—	—	—	1683	—
400	290	63.2	18328	120	45.0	16200	1.0	2128	88.4
400	291	60.0	17460	116.8	56.0	15768	0.8	1692	90.3
60	288.1	1.0	288	120.5	—	—	—	288	—
60	299	57.5	17143	120.6	45.0	16268	1.0	925	94.6
60	297.4	60	17844	119.4	56.8	16133	0.8	1712	90.4

* DOES NOT INCLUDE RECTIFIER OR OTHER FIXED LOSSES.

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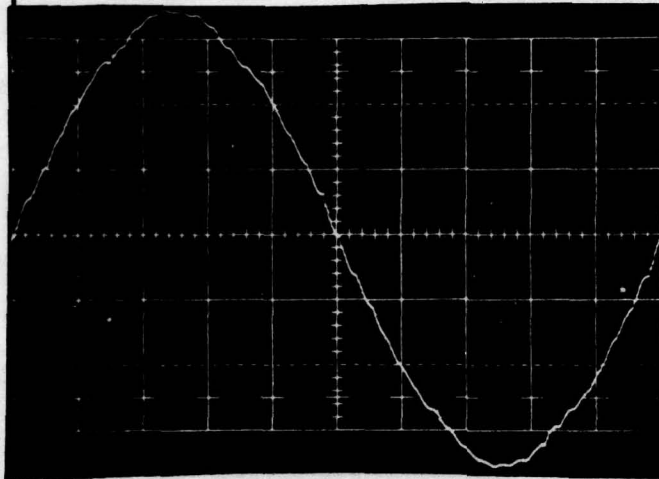
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FREQUENCY CONVERTER OUTPUT VOLTAGES

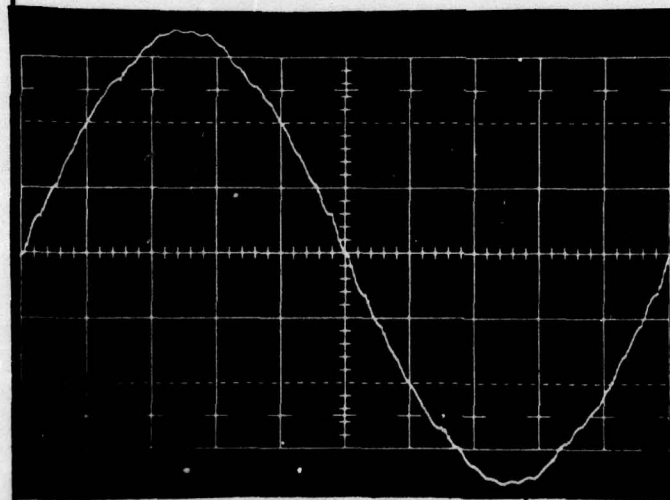


60 HZ THREE PHASE
(NO TRANSISTORS)
(485MFD L-T-L)

NO LOAD

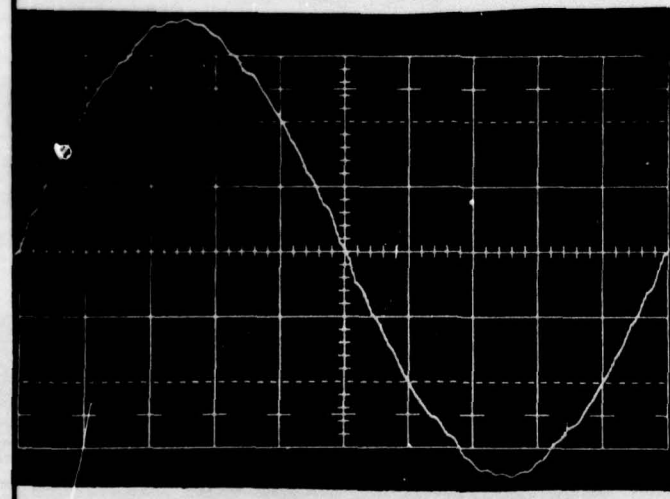
THD = 2.0%

50V/DIV



11KW, PF=1.0

THD=1.85%



11KW, PF=0.8

THD=1.78%

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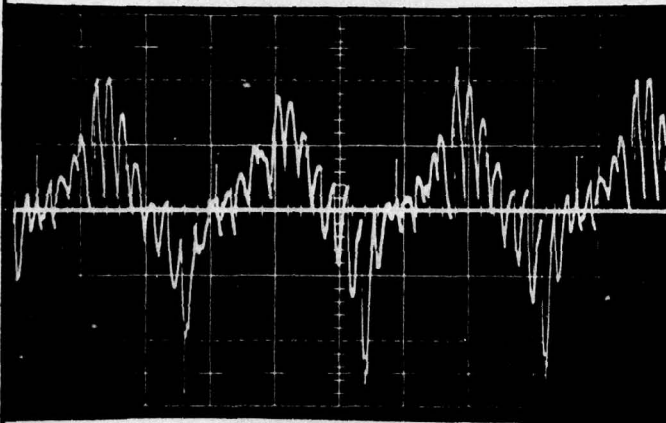
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FREQUENCY CONVERTER INPUT CURRENTS

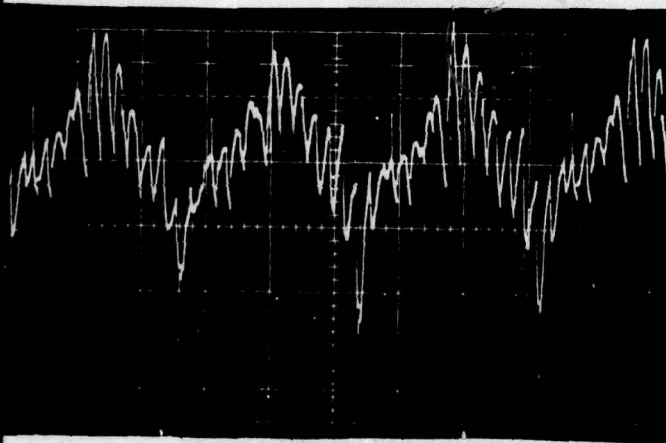


60 HZ THREE PHASE
(NO TRANSISTORS)
(485 MFD L-T-L)
(THREE WIRE INPUT)

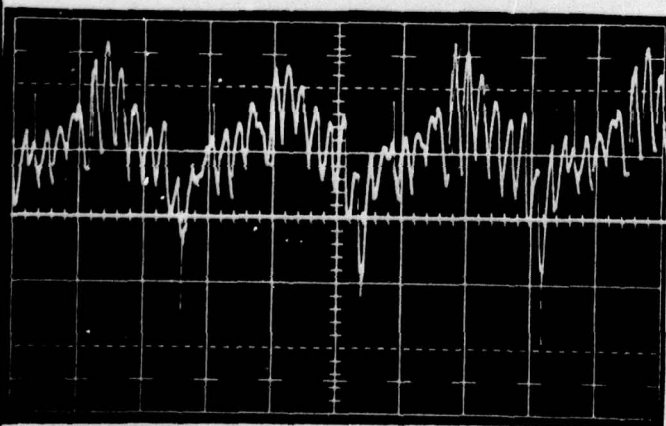
DC LINE INPUT CURRENTS

NO LOAD

↓ 40 A/DIV. ↔ 2 MS/DIV.



11 KW, PF = 1.0



11 KW, PF = 0.8

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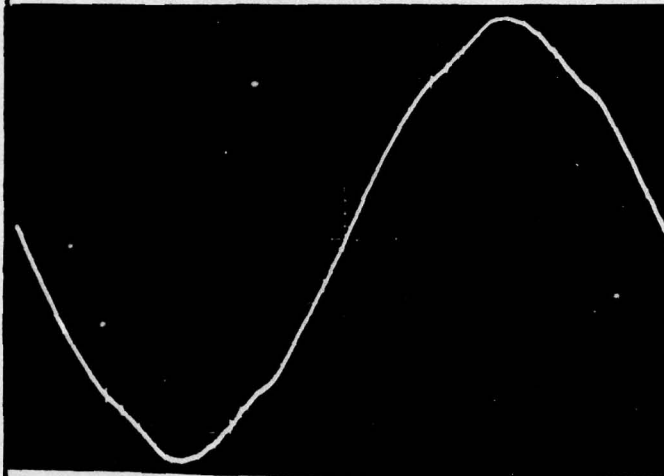
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FREQUENCY CONVERTER OUTPUT VOLTAGES

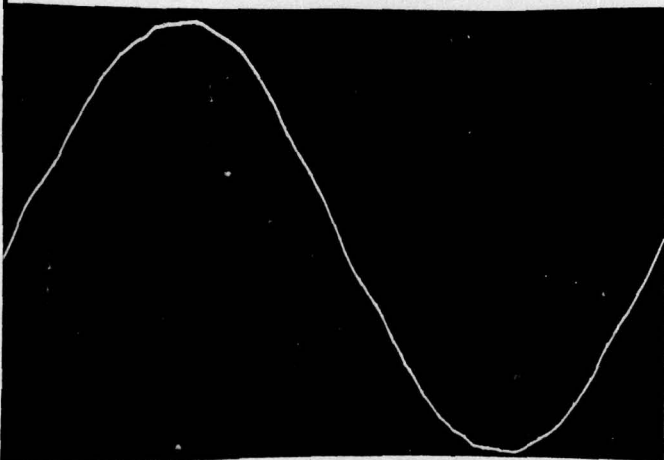


400 HZ SINGLE PHASE
TWO WIRE OUTPUT

NO LOAD

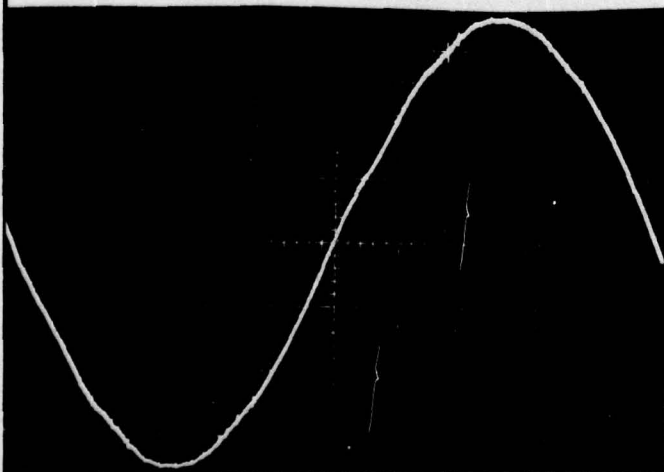
THD = 3.5%

50V/DIV



11 KW, PF = 1.0

THD = 2%



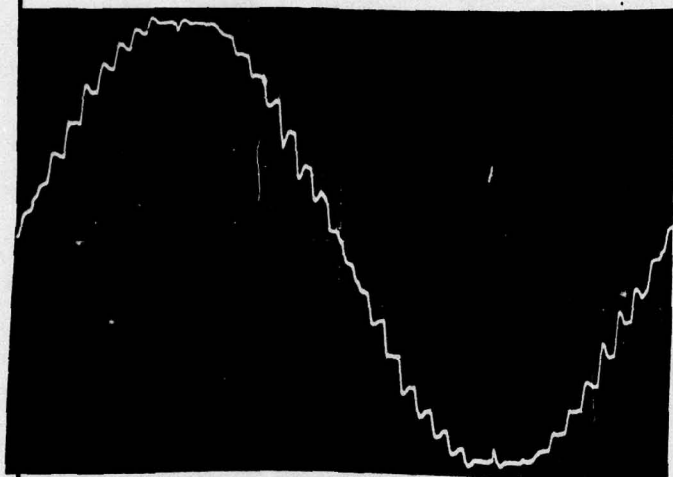
11 KW, PF = 0.8

THD = 2.1%

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FREQUENCY CONVERTER OUTPUT VOLTAGES

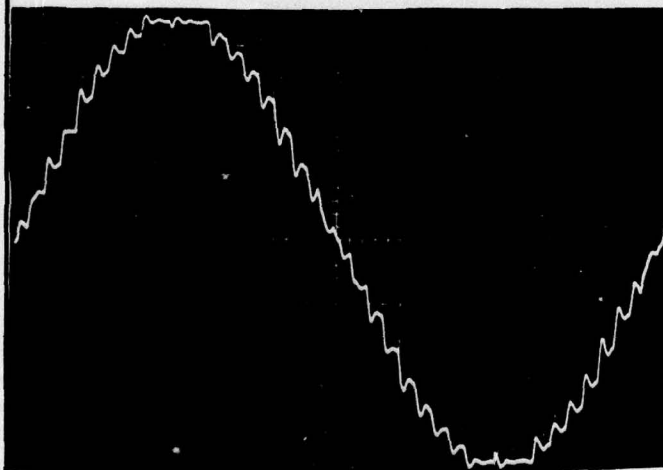


60HZ SINGLE PHASE
TWO WIRE OUTPUT
(WITH TRANSISTORS)
(125MFD L-T-N; 20MFD
PHASE C)

NO LOAD

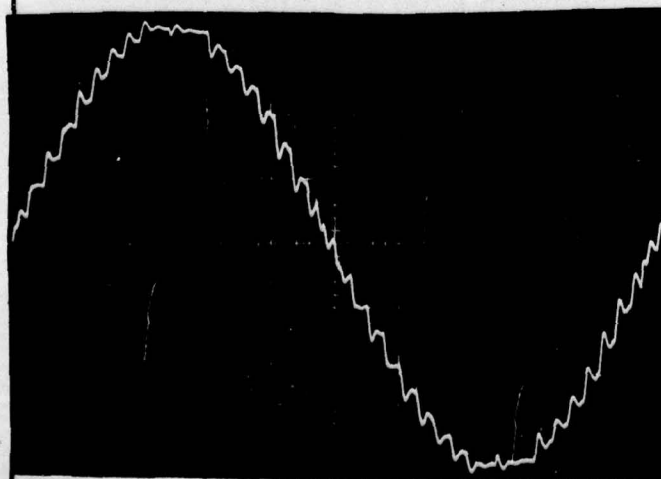
THD = 4.3%

50V/DIV.



11KW, PF=1.0

THD = 4.6%



11KW, PF=0.8

THD = 4.3%

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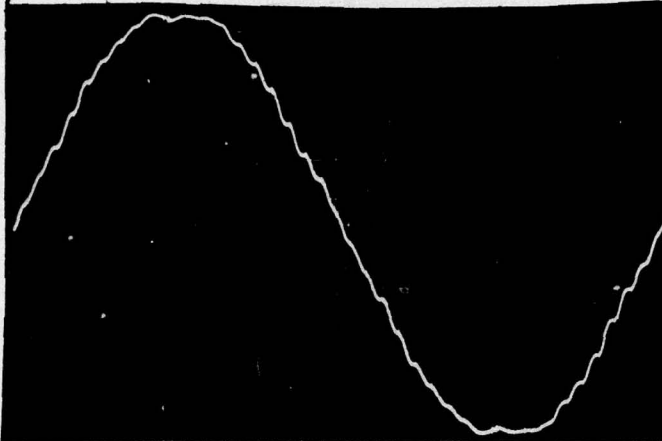
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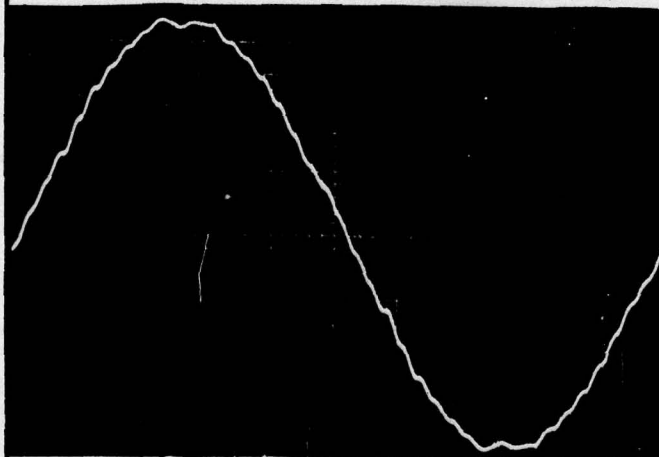
FREQUENCY CONVERTER OUTPUT VOLTAGES & TRANSISTOR CURRENTS



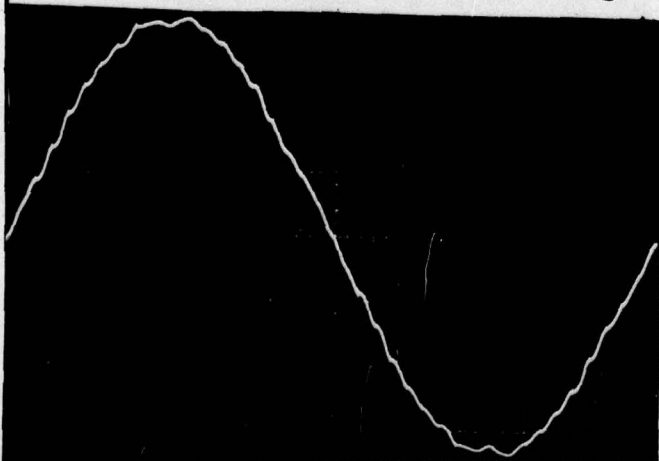
60 HZ SINGLE PHASE
TWO WIRE OUTPUT

(700 MFD L-T-N; 0 MFD
PHASE C; 700 MFD A-B)

NO LOAD THD = 2.5% 50V/DIV.

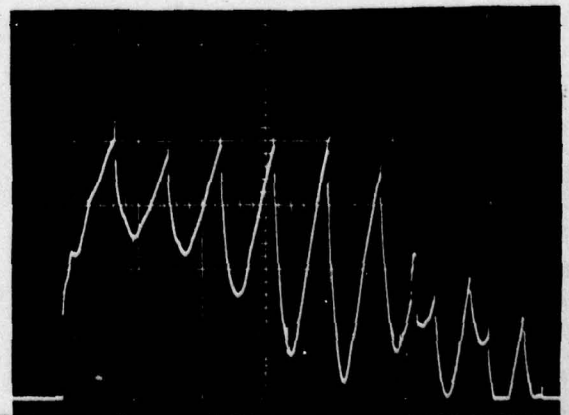
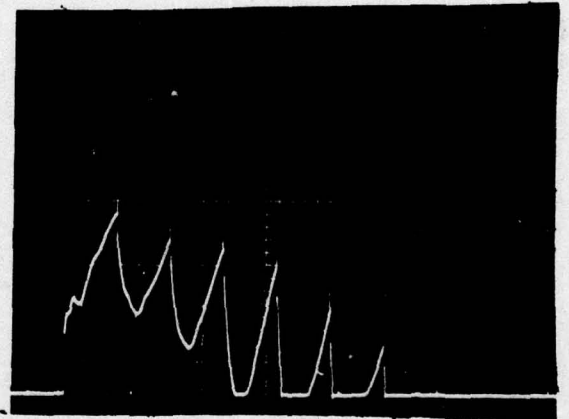


16 KW, PF = 1.0 THD = 2.3%



16 KW, PF = 1.0 THD = 2.42%

STEP VOLTAGE COMMUTATION TRANSISTOR CURRENT



25A/DIV. 500 μSEC/DIV.

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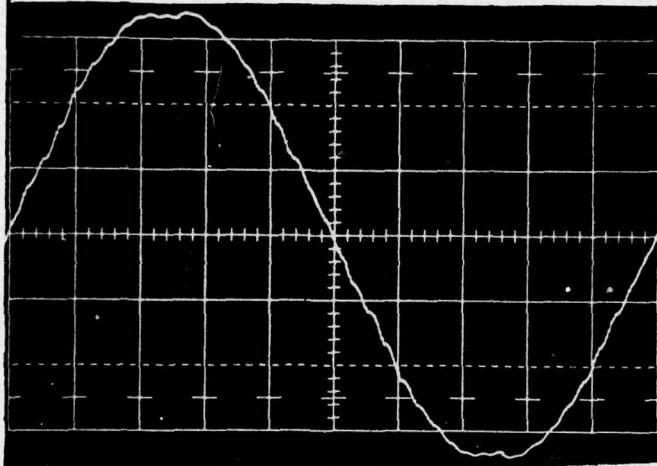
DATE

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APPROVED

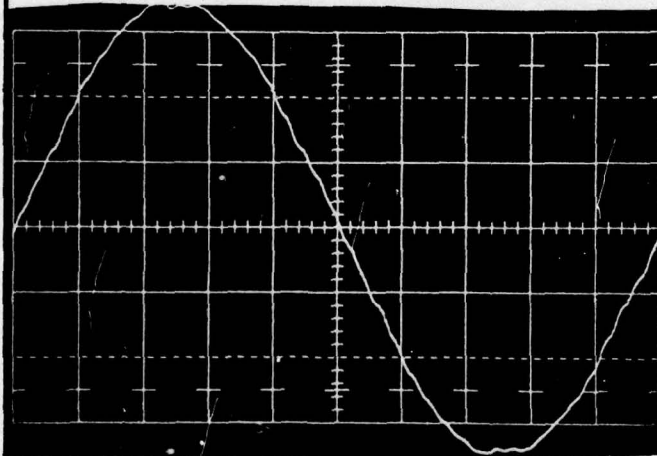
FREQUENCY CONVERTER OUTPUT VOLTAGES



60 HZ SINGLE PHASE
TWO WIRE OUTPUT
(NO TRANSISTORS)
(485 MFD. L-T-L)

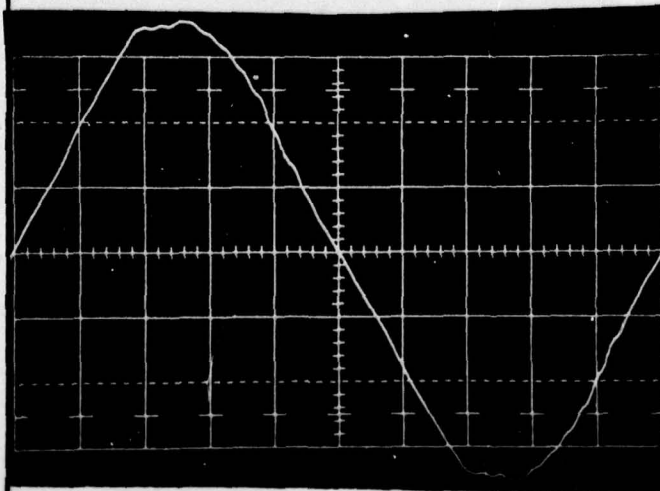
NO LOAD

THD = 2%



11 KW, PF = 1.0

THD = 1.8%



11 KW, PF = 0.8

THD = 5.2%

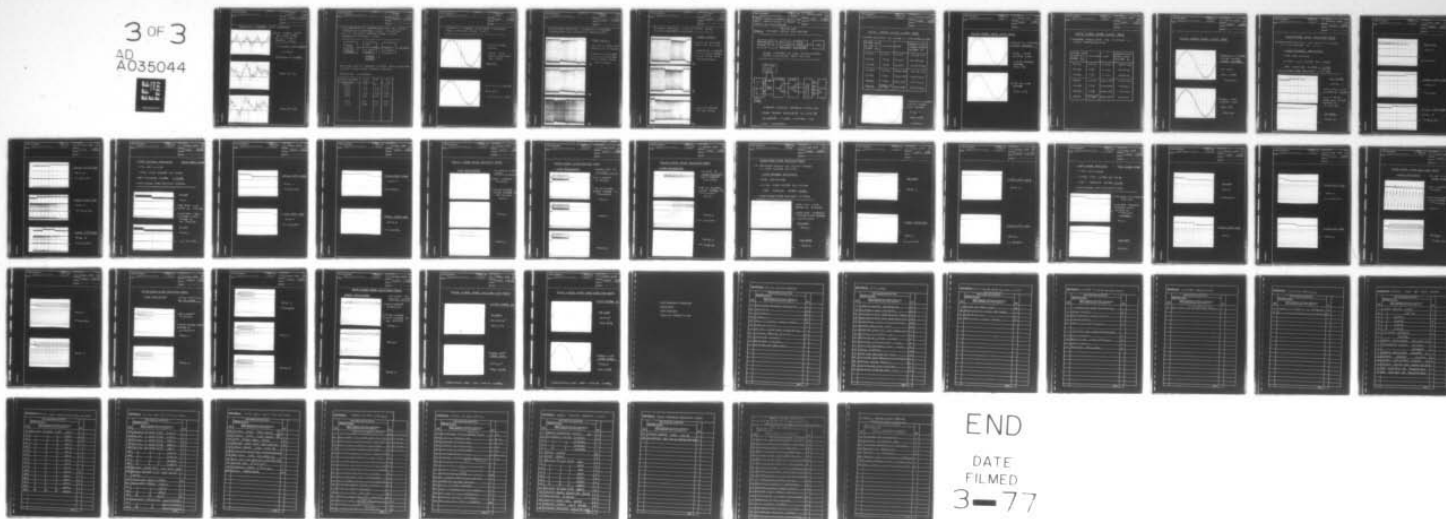
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GENERAL MOTORS CORP GOLETA CALIF DELCO ELECTRONICS DIV F/6 9/5
FREQUENCY CONVERTER PORTABLE, ALTERNATING CURRENT MULTIFREQUENC--ETC(U)
MAY 74 T CORRY, BARRETT DAAK02-72-C-0210
R74-40-VOL-2 NL

UNCLASSIFIED

3 OF 3
AD
A035044



TITLE

PREPARED

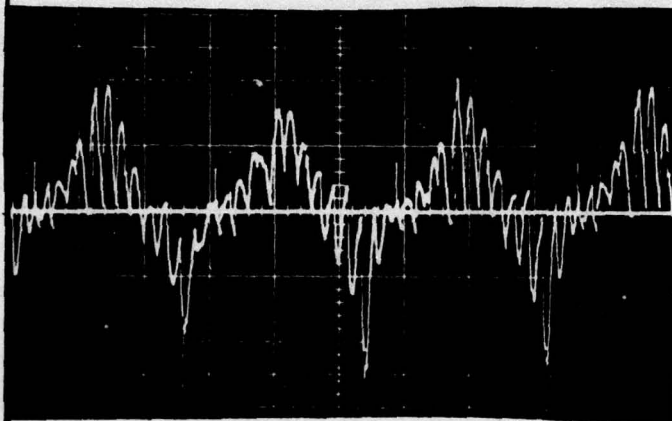
CORRY 1/29/74

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FREQUENCY CONVERTER INPUT CURRENTS

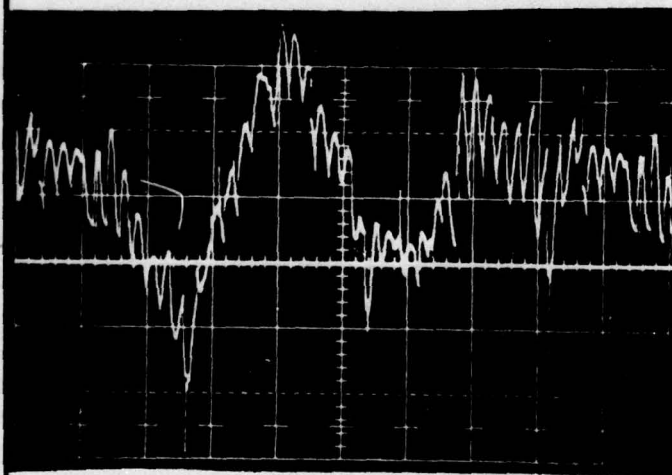


60 HZ SINGLE PHASE
+ TWO WIRE OUTPUT
(NO TRANSISTORS)
(485 MFD, L-T-L)

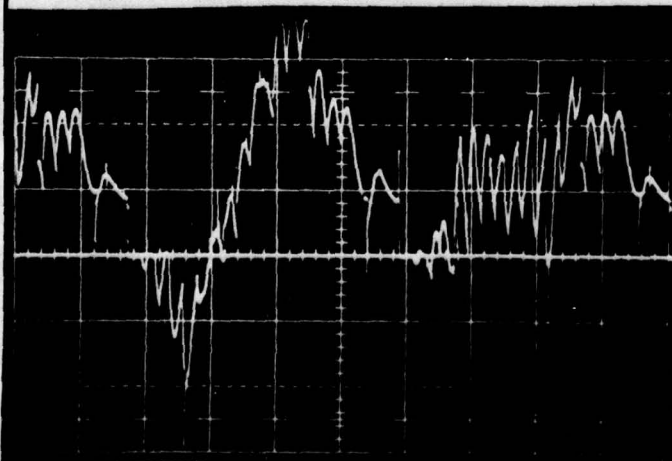
+ DC VOLTAGE INPUT CURRENTS

NO LOAD

↓ 40A/DIV. ← 2ms/DIV.



11KW, PF=1.0

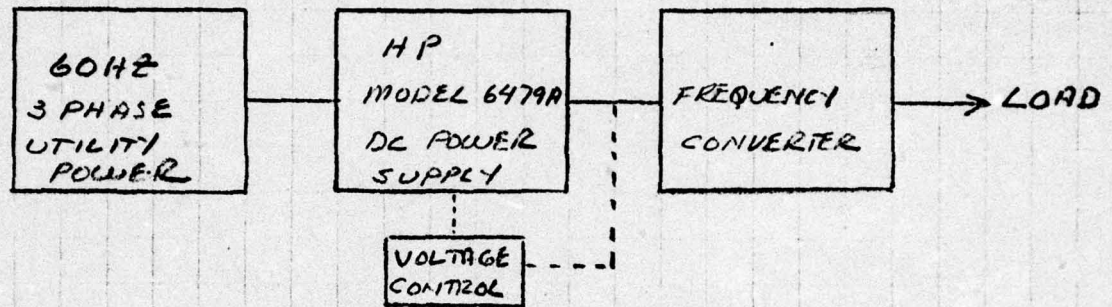


11KW, PF=0.8

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MEASUREMENTS OF PERFORMANCE OF THE MERDC
FREQUENCY CONVERTER WHEN ENERGIZED
BY A HEWLETT PACKARD MODEL 6479A
REGULATED DC POWER SUPPLY



TWO WIRE INPUT TO FREQUENCY CONVERTER, 400 HZ, THREE PHASE
OUTPUT. (POWER FACTOR CORRECTED CIRCUIT)

FREQUENCY CONVERTER:

OUTPUT VOLTAGE VOLTS RMS	LOAD KW	PF	THD %
125.0	—	—	2.7
124.0	2.2	0.8	2.32
123.3	4.4	0.8	2.07
122.5	6.6	0.8	1.86
120.9	8.8	0.8	1.67
122.7	6.6	1.0	2.35
119.3	8.8	1.0	2.3

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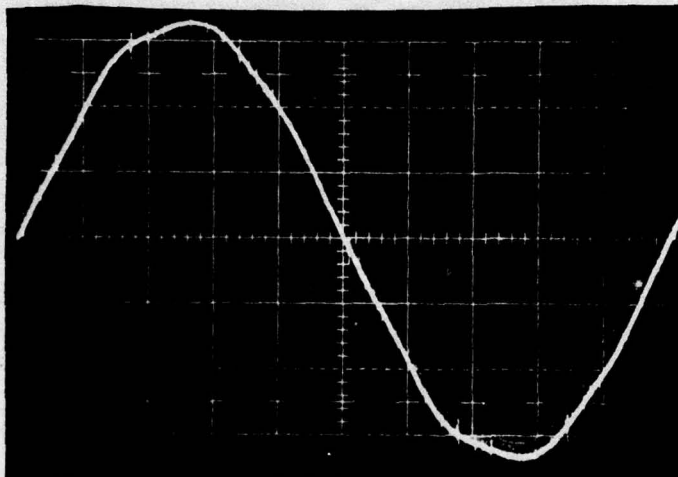
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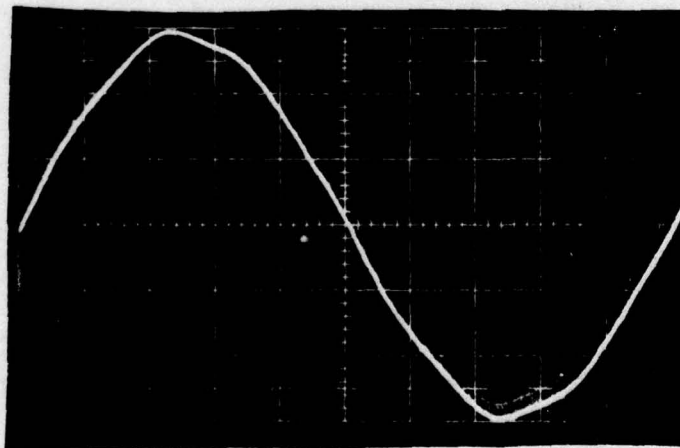
FREQUENCY CONVERTER LOAD TESTS OPERATING
FROM HP 6479A POWER SUPPLY



LINE-TO-NEUTRAL
VOLTAGE

8.8 KW 0.8 PF
400HZ, THREE PHASE
THD = 1.67%

150V/DIV.



LINE-TO-LINE VOLTAGE

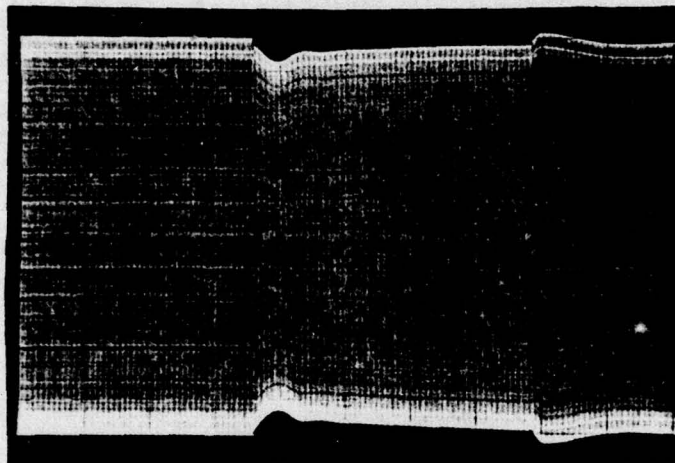
100V/DIV.

SAME LOAD AS ABOVE

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TRANSIENT RESPONSE - FREQUENCY CONVERTER
ENERGIZED BY HP 6479A POWER SUPPLY



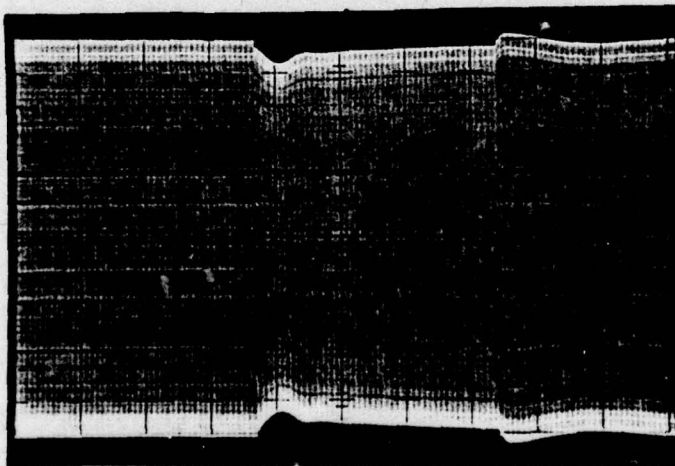
THREE TRIALS

- NO LOAD TO 8.8KW 0.8PF
- 8.8KW 0.8PF TO NO LOAD

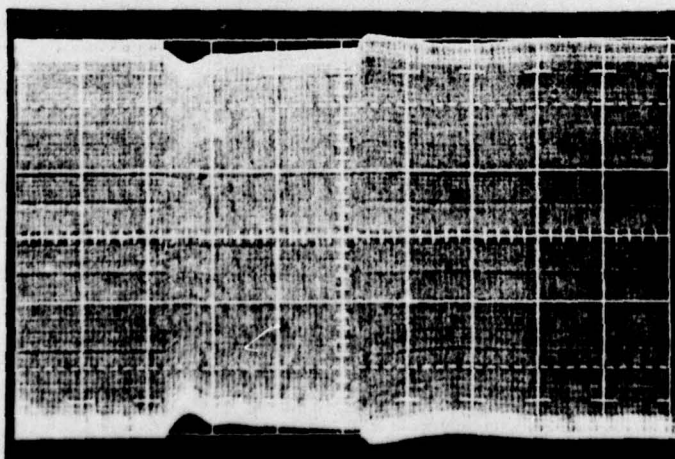
FREQUENCY CONVERTER
L-T-N OUTPUT VOLTAGE
400 HZ, THREE PHASE

↔ 0.2 SEC/DIV.

①



②



③

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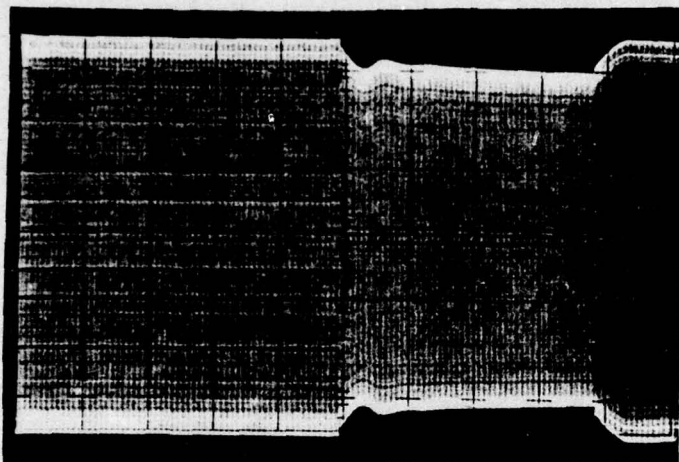
3/21/74

CHECKED

APPROVED

TRANSIENT RESPONSE - WITH HP 6479A POWER
SUPPLY CURRENT LIMITING

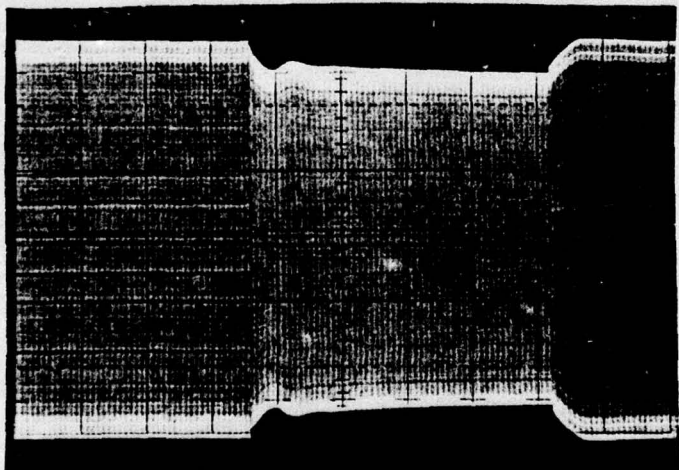
THREE TRIALS



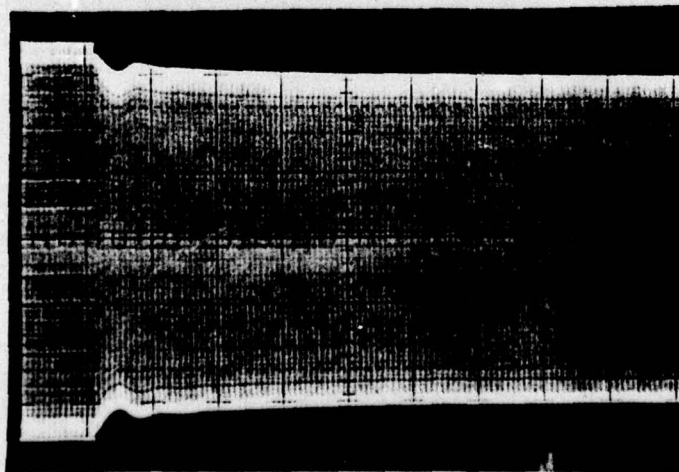
- NO LOAD TO 11KW 0.8PF
- 11KW 0.8PF TO NO LOAD

FREQUENCY CONVERTER
L-T-N OUTPUT VOLTAGE
400HZ, THREE PHASE
↔ 0.2 SEC/DIV.

①



②



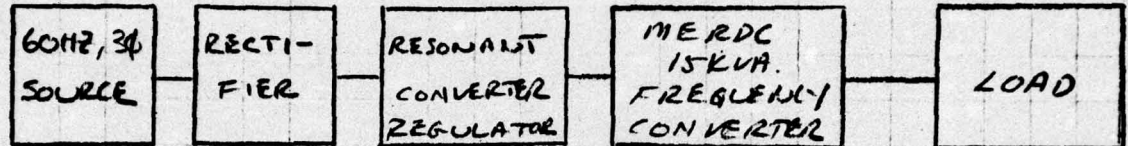
LOAD NOT REMOVED
FOR THIS TRIAL

③

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	TITLE 15KVA POWER CONDITIONER DESIGN DATA TESTS ITEM NO. 0005 CONTRACT NO. DAAK02-72-C-0210 REPORT		PREPARED CORY	DATE 5/6/74
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		APPROVED		

ITEM NO. 0005
TASK 3 PERFORM DESIGN DATA TESTING



BLOCK DIAGRAM OF THE EXPERIMENTAL POWER CONDITIONER TEST SET-UP

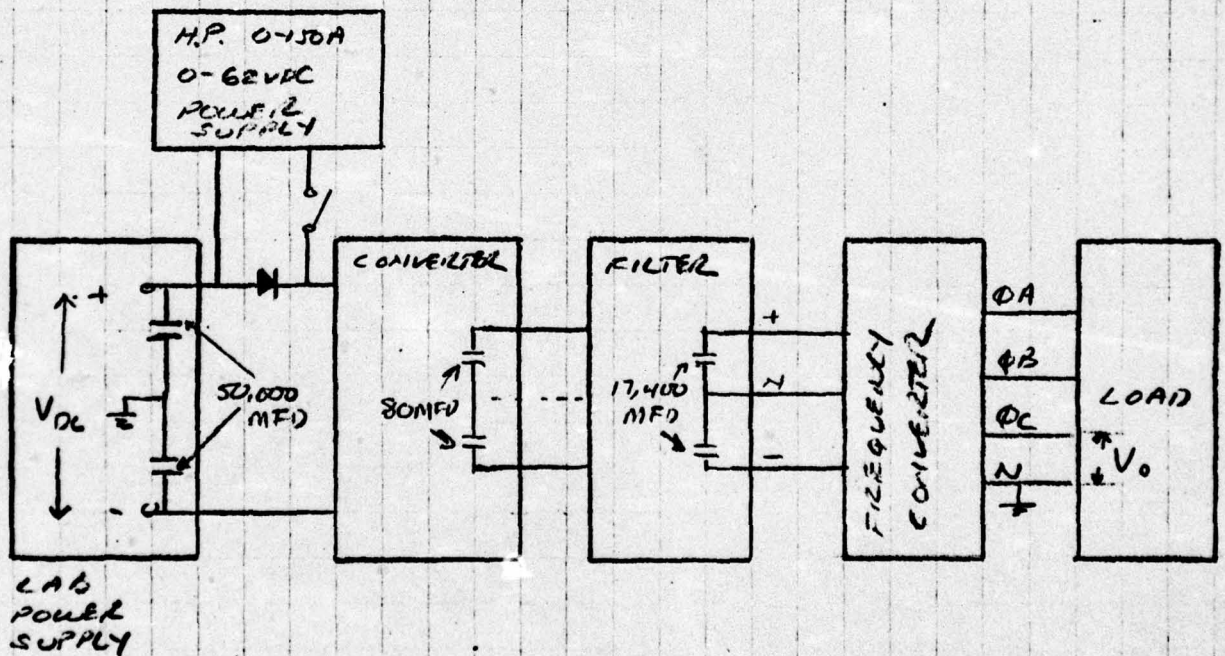


DIAGRAM SHOWING METHOD OF APPLYING POWER SOURCE TRANSIENTS TO INPUT OF CONVERTER. FILTER CAPACITORS ARE ALSO IDENTIFIED

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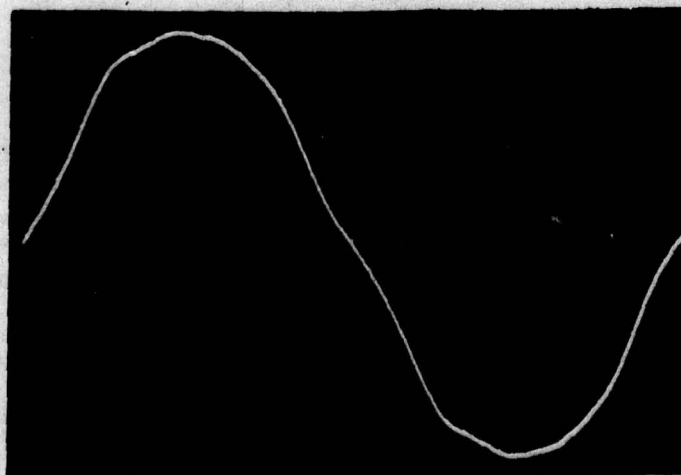
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400 Hz, THREE PHASE OUTPUT TESTS

1) VOLTAGE REGULATION FOR CHANGES IN INPUT VOLTAGE & LOAD

VOLTAGE INPUT TO REG. CON- VERTER V _{DC}	CONDITION	LOAD	FREQUENCY CON- VERTER OUTPUT VOLTAGE V _o
340 V _{DC}	NORMAL	NO LOAD	120.66 V _{rms}
374 V _{DC}	+10%	NO LOAD	120.69 V _{rms}
289 V _{DC}	-15%	NO LOAD	120.61 V _{rms}
340 V _{DC}	NORMAL	13.2KW, 0.8PF	120.08 V _{rms}
374 V _{DC}	+10%	13.2KW, 0.8PF	120.09 V _{rms}
289 V _{DC}	-15%	13.2KW, 0.8PF	120.07 V _{rms}
268 V _{DC}	LOWER LIMIT OF REG.	13.2KW, 0.8PF	120.06 V _{rms}



FREQUENCY CONVERTER
LINE-TO-NEUTRAL
OUTPUT VOLTAGE

NO LOAD

THD = 3.95%

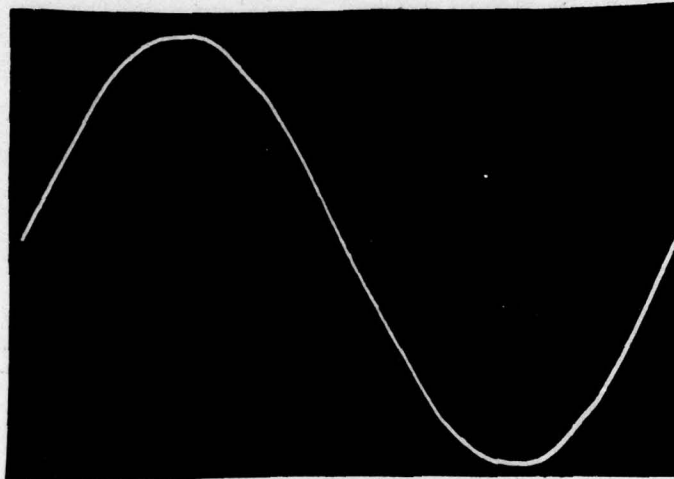
120.66 V_{rms}

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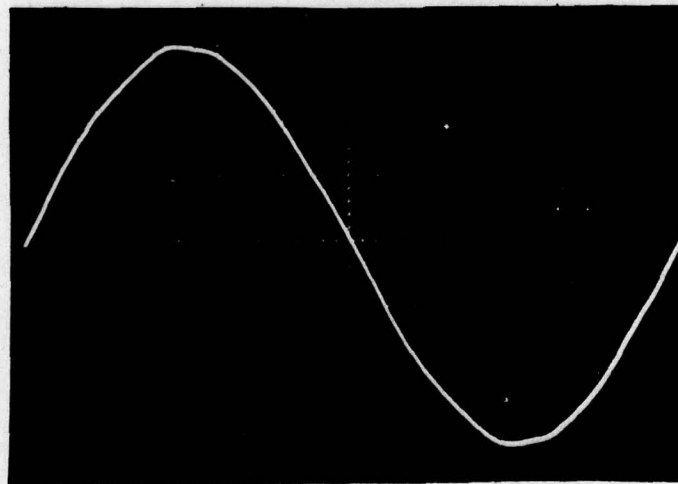
400 HZ, THREE PHASE OUTPUT TESTS



FREQUENCY CONVERTER
OUTPUT VOLTAGES

13.2KW , 0.8 PF
16.5KVA LOAD

LINE-TO-NEUTRAL
VOLTAGE
THD= 1.1%



LINE-TO-LINE
VOLTAGE

THD= 1.1%

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60HZ, THREE PHASE OUTPUT TESTS

1) VOLTAGE REGULATION FOR CHANGES IN
INPUT VOLTAGE & LOAD.

VOLTAGE INPUT TO REG. CON- VERTER V_{DC}	CONDITION	LOAD	FREQUENCY CON- VERTER OUTPUT VOLTAGE V_o
340Vdc	NORMAL	NO LOAD	120.4 Vrms
374Vdc	+10%	NO LOAD	120.5 Vrms
289Vdc	-15%	NO LOAD	120.3 Vrms
340Vdc	NORMAL	13.2KW, 0.8PF	120.2 Vrms
374Vdc	+10%	13.2KW, 0.8PF	118.96 Vrms
289Vdc	-15%	13.2KW, 0.8PF	120.1 Vrms
260Vdc	LOWER LIMIT OF REG.	13.2KW, 0.8PF	120.0 Vrms

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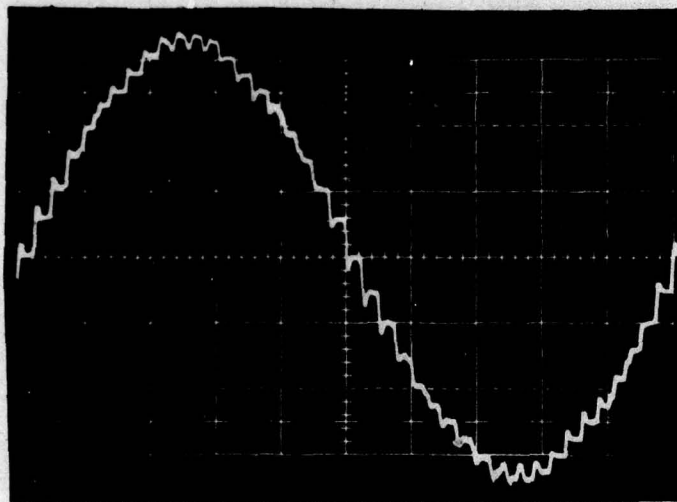
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60 HZ, THREE PHASE OUTPUT TESTS

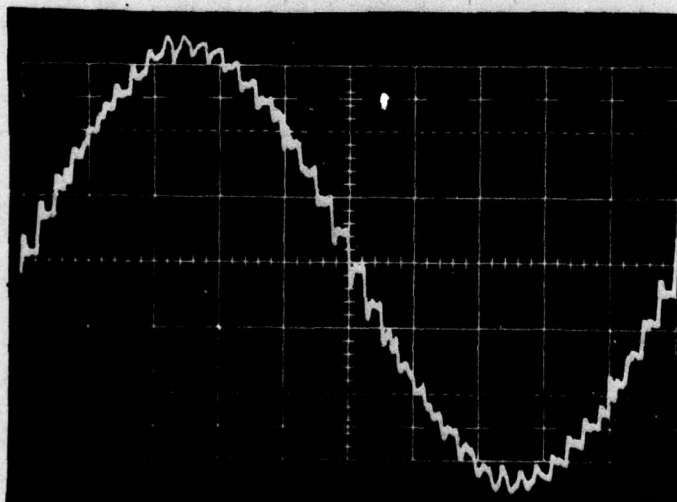


FREQUENCY CONVERTED
LINE-TO-NEUTRAL
OUTPUT VOLTAGES

NO LOAD

THD = 4.54%

120.4 Vrms



13.2 KW, 0.8 PF
16.5 KVA LOAD

THD = 5%

120.2 Vrms

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400HZ, THREE PHASE TRANSIENT TESTS

2) TRANSIENT RESPONSE FOR ABRUPT CHANGES
IN INPUT VOLTAGE OR LOAD.

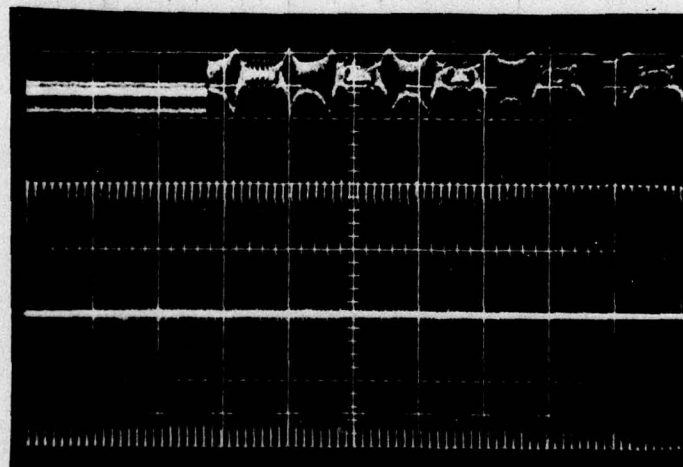
INPUT VOLTAGE TRANSIENTS

+10% STEP CHANGE

INITIAL INPUT VOLTAGE $V_{DC} = 340V_{DC}$

STEP INCREASE VOLTAGE = 34V_{DC}

INPUT VOLTAGE AFTER TRANSIENT = 374V_{DC}

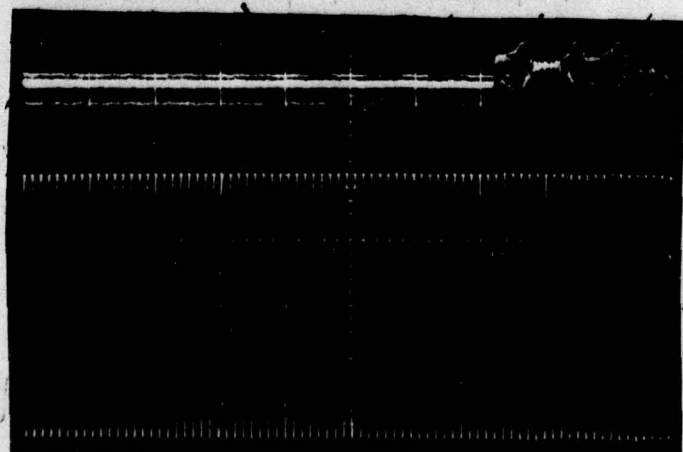


NO LOAD

TRIAL 1

UPPER TRACE - INPUT
VOLTAGE V_{DC} $\downarrow 100V/DIV$

LOWER TRACE -
FREQ. CONV. OUTPUT
VOLTAGE V_O
 $\leftrightarrow 20MS/DIV.$



NO LOAD

TRIAL 2

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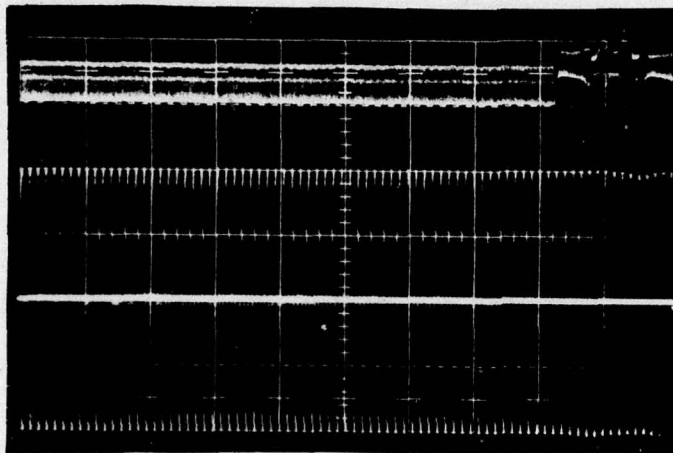
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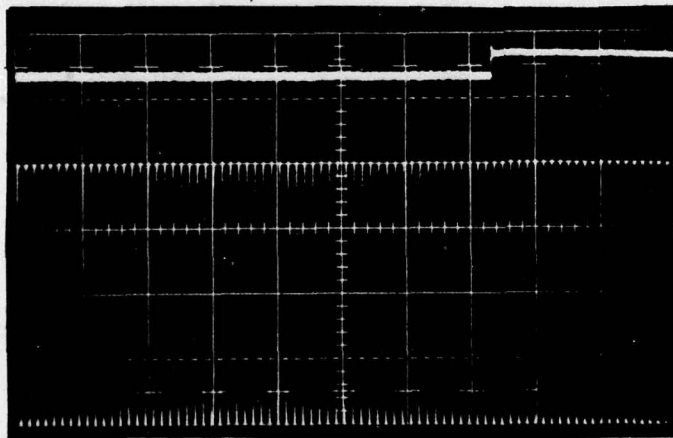
APPROVED



2 KW LOAD

TRIAL 3

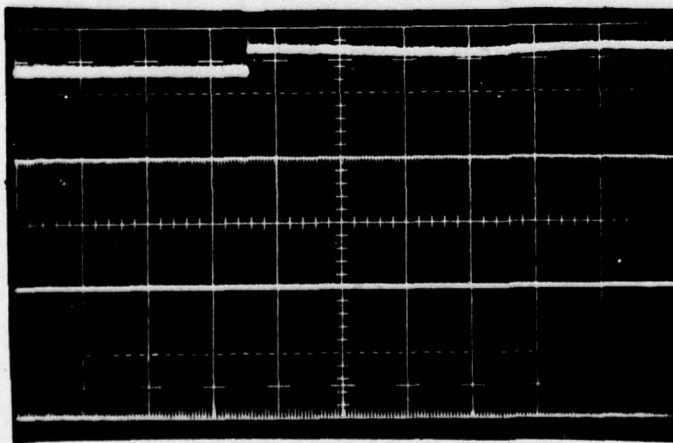
↔ 20 ms / DIV.



13.2 KW, 0.8 PF LOAD

TRIAL 4

↔ 20 ms / DIV.



13.2 KW, 0.8 PF LOAD

TRIAL 5

↔ 50 ms / DIV.

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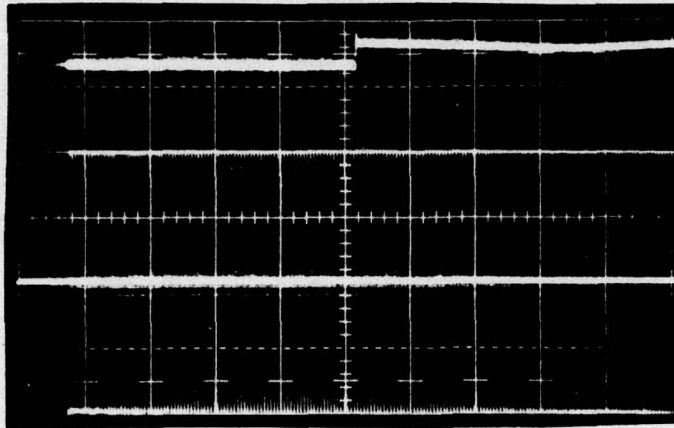
PAGE JOB NO. PAGE
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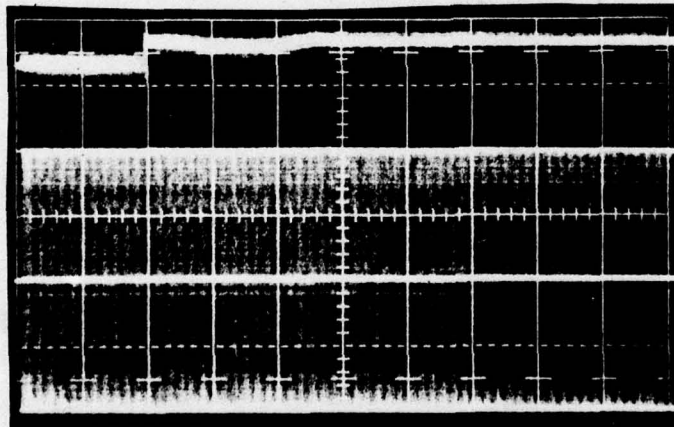
APPROVED



13.2 KW, 0.8 PF LOAD

TRIAL 6

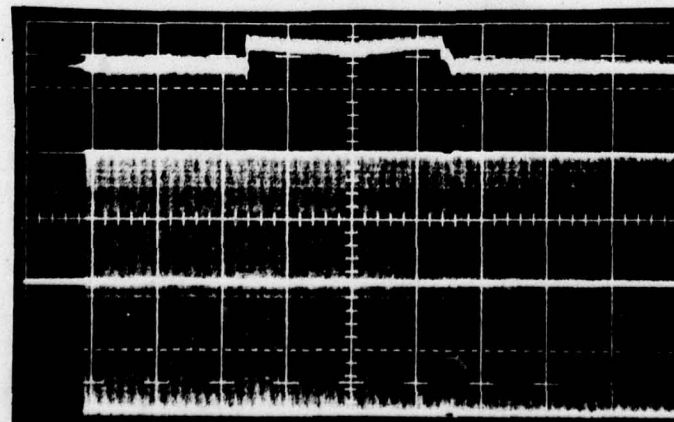
← 50MS / DIV



13.2 KW, 0.8 PF LOAD

TRIAL 7

← 100MS / DIV.



13.2 KW, 0.8 PF LOAD

TRIAL 8

← 100MS / DIV.

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INPUT VOLTAGE TRANSIENTS

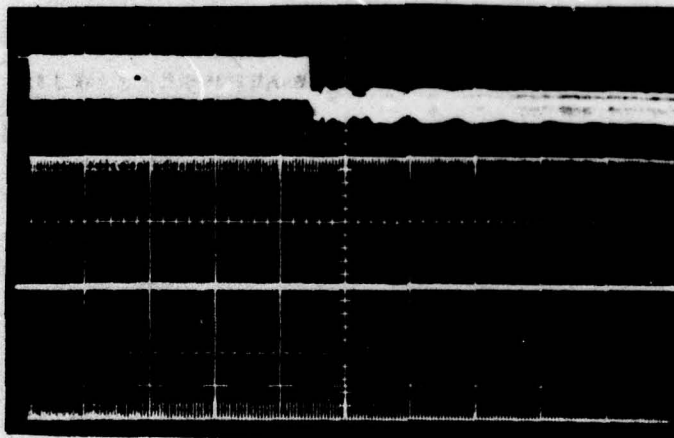
400HZ, THREE PHASE

-15% STEP CHANGE

INITIAL INPUT VOLTAGE $V_{DC} = 340 \text{ Vdc}$

STEP DECREASE VOLTAGE = -57 Vdc

INPUT VOLTAGE AFTER TRANSIENT = 289 Vdc

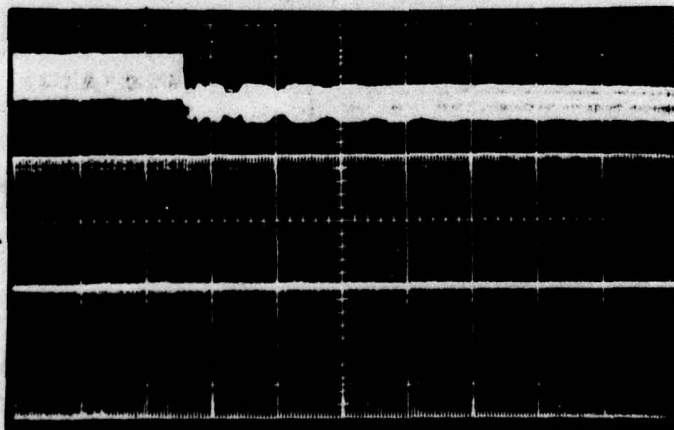


NO LOAD

TRIAL 1

UPPER TRACE - INPUT
VOLTAGE V_{DC} $\downarrow 100 \text{ V/DIV}$

LOWER TRACE - FREQ.
CONVERTER OUTPUT
VOLTAGE V_o
 $\leftrightarrow 50 \text{ MS/DIV.}$



NO LOAD

TRIAL 2

$\leftrightarrow 50 \text{ MS/DIV.}$

DELCO ELECTRONICS

GENERAL MOTORS CORPORATION

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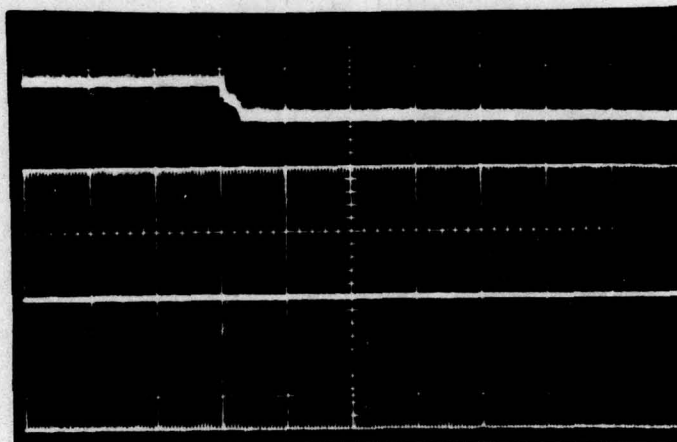
PREPARED

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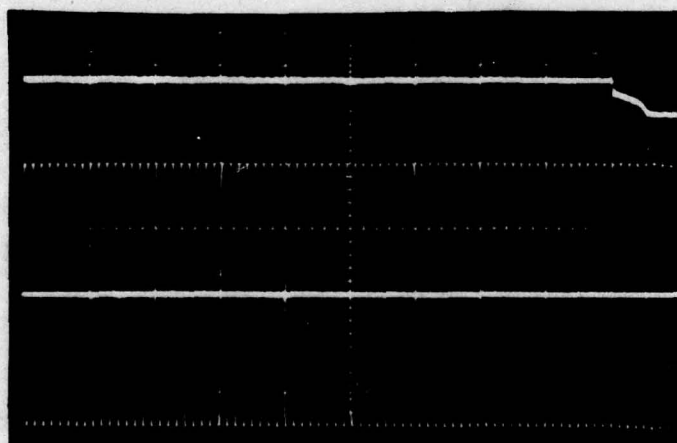
APPROVED



13.2 KW, 0.8 PF LOAD

TRIAL 3

↔ 50 ms/DIV



13.2 KW, 0.8 PF LOAD

TRIAL 4

↔ 20 ms/DIV.

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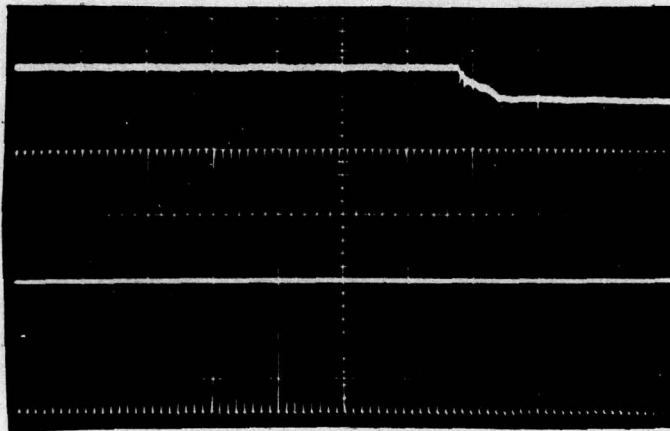
CORRY

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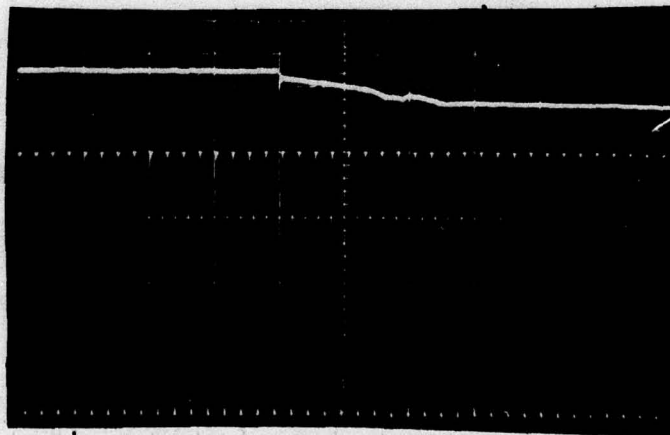
APPROVED



13.2KW, 0.8PF LOAD

TRIAL 5

↔ 20MS/DIV



13.2KW, 0.8PF LOAD

TRIAL 6

↔ 10MS/DIV

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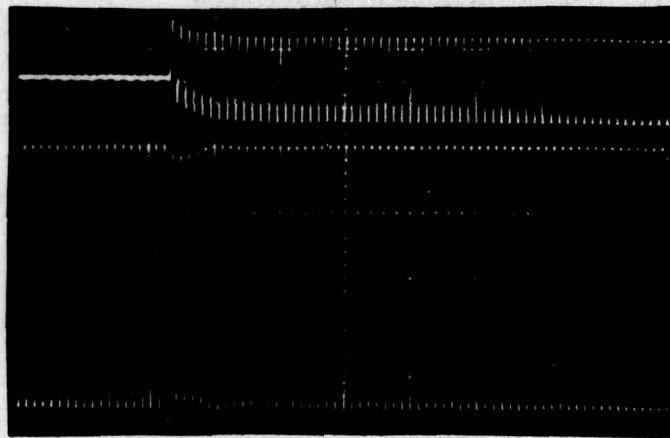
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400 HZ, THREE PHASE TRANSIENT TESTS

LOAD TRANSIENTS

NO LOAD TO 13.2 KW

0.8 PF



LOAD CURRENT

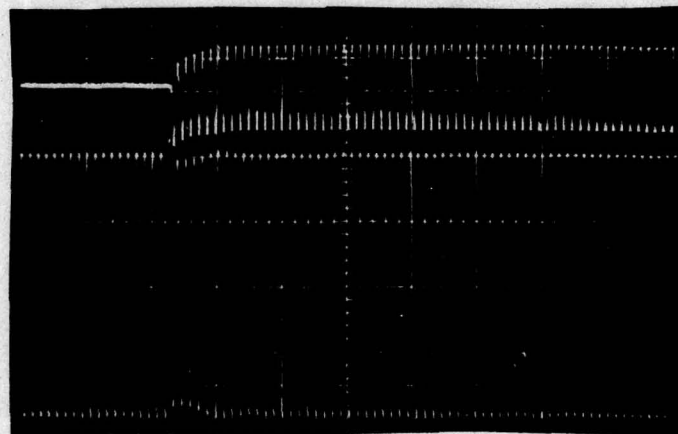
↓ 100A/DIV.

LINE-TO-NEUTRAL

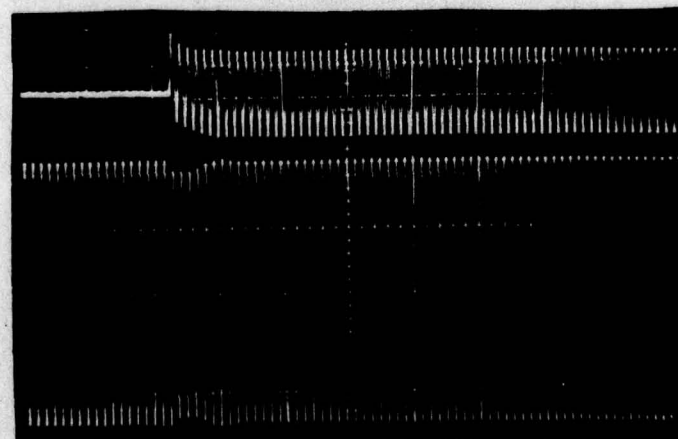
OUTPUT VOLTAGE

↔ 20MS/DIV

TRIAL 1



TRIAL 2



TRIAL 3

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CORRY 5/6/74

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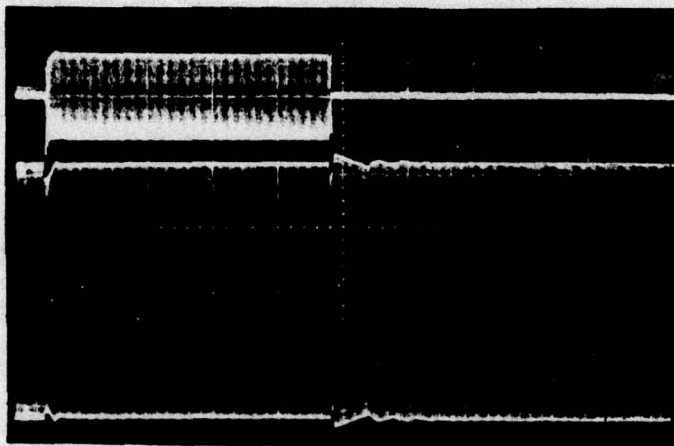
CHECKED

APPROVED

400 HZ, THREE PHASE TRANSIENT TESTS

LOAD TRANSIENTS

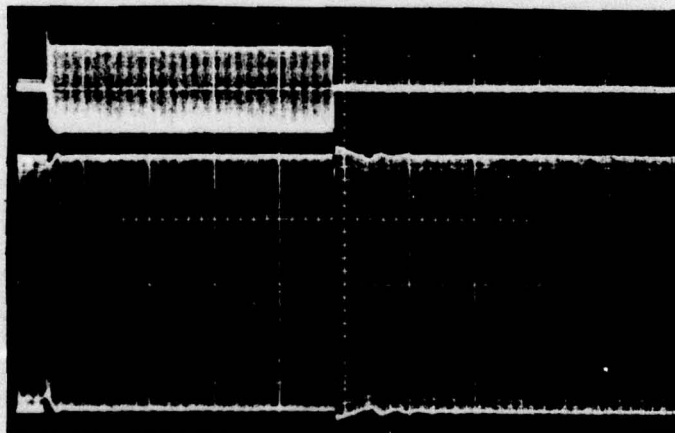
13.2 KW, 0.8 PF TO
NO LOAD



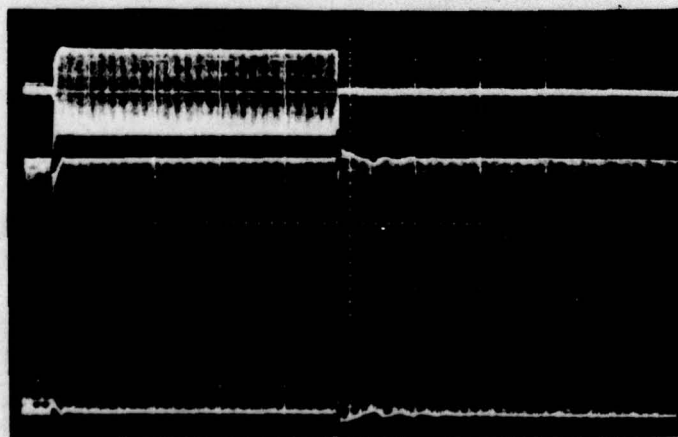
LOAD CURRENT
↓ 100A/DIV.

LINE-TO-NEUTRAL
OUTPUT VOLTAGE V_o
← 20ms/DIV.

TRIAL 1



TRIAL 2



TRIAL 3

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TITLE

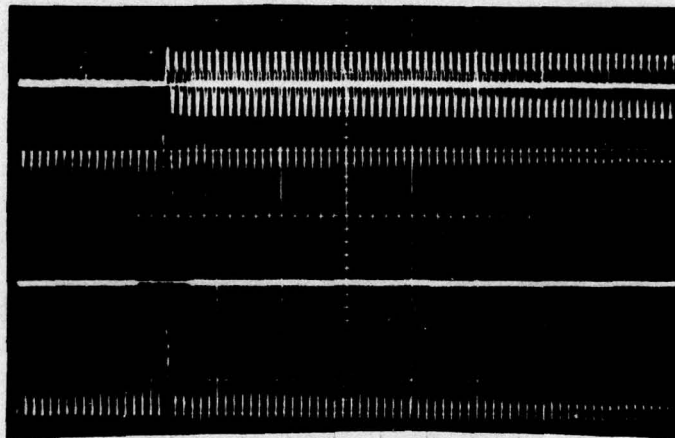
PREPARED

CORRY 5/6/79

DATE

CHECKED

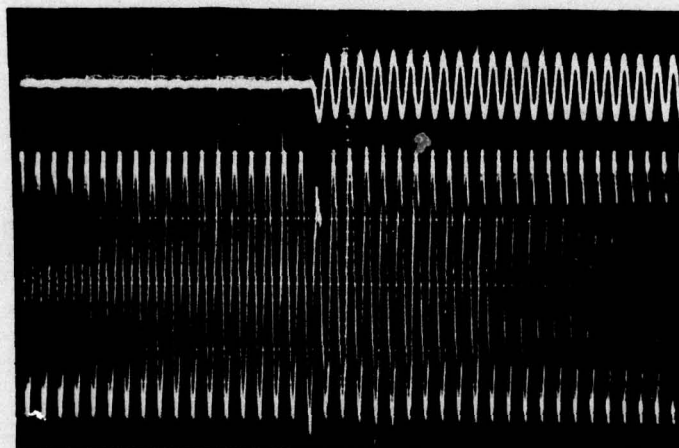
APPROVED

400 HZ, THREE PHASE TRANSIENT TESTSLOAD TRANSIENTS

NO LOAD TO
TWO P. U. 0.4 PF
LOAD CURRENT
↑ 200 A / DIV.

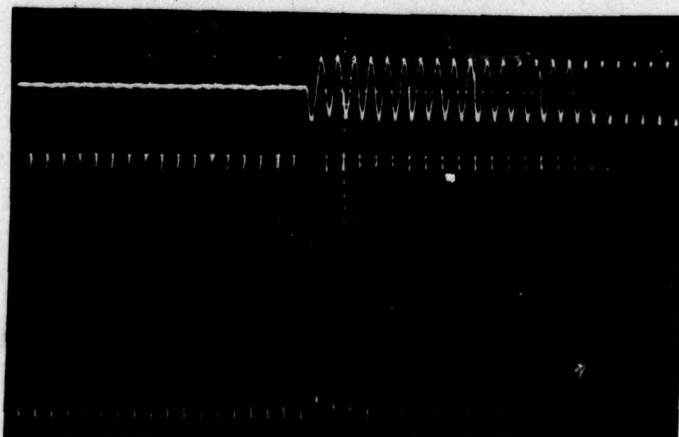
LINE-TO-NEUTRAL
OUTPUT VOLTAGE V_o
↔ 20 MS / DIV.

TRIAL 1



TRIAL 2

↔ 10 MS / DIV.



TRIAL 3

↔ 10 MS / DIV.

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TITLE

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60HZ, THREE PHASE TRANSIENT TESTS

2) TRANSIENT RESPONSE FOR ABRUPT CHANGES
IN INPUT VOLTAGE OR LOAD.

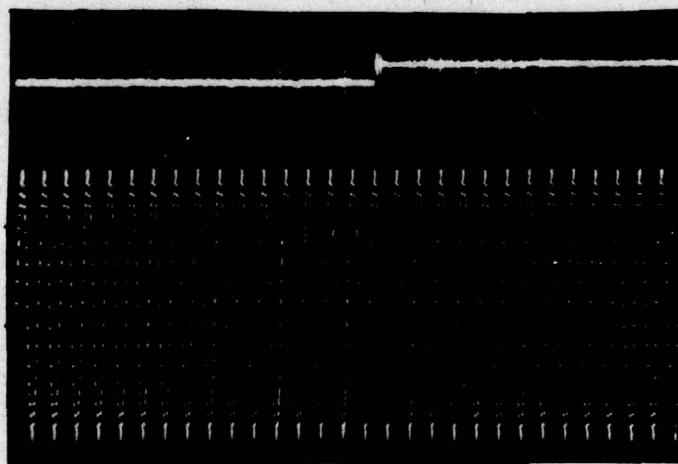
INPUT VOLTAGE TRANSIENTS

+10% STEP CHANGE

INITIAL INPUT VOLTAGE $V_{DC} = 340 \text{ Vdc}$

STEP INCREASE VOLTAGE = 34 Vdc

INPUT VOLTAGE AFTER TRANSIENT = 374 Vdc

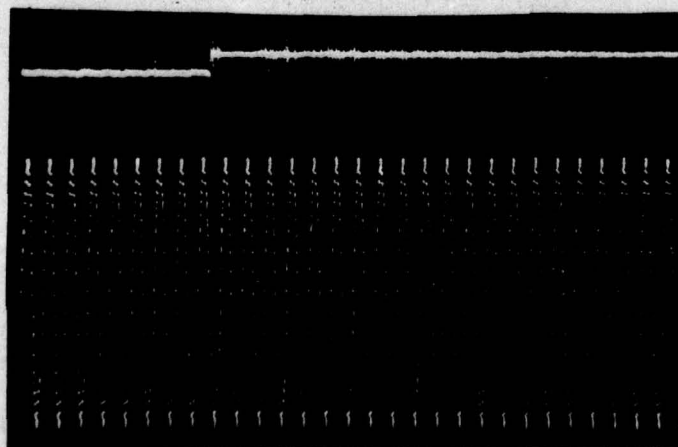


UPPER TRACE - INPUT
VOLTAGE V_{DC} $\downarrow 100 \text{ V/DIV.}$

LOWER TRACE - FREQUENCY
CONVERTER OUTPUT VOLTAGE
 $\leftarrow 50 \text{ ms/DIV.}$

NO LOAD

TRIAL 1



NO LOAD

TRIAL 2

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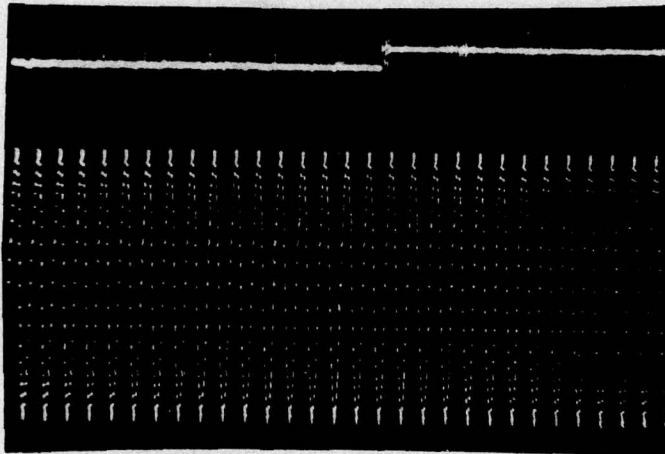
PREPARED

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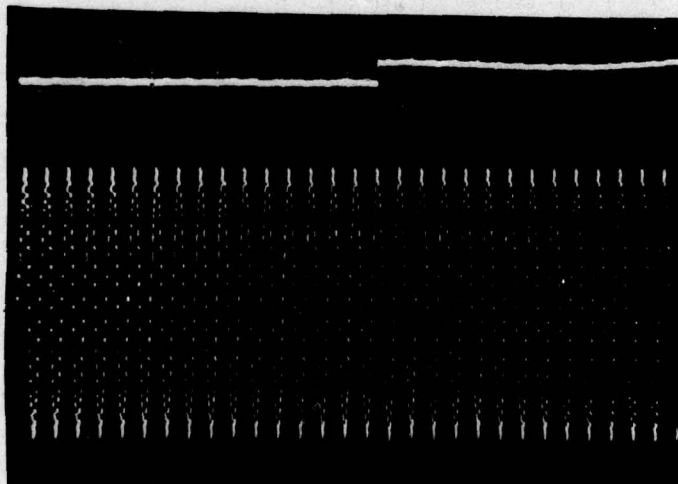
CHECKED

APPROVED



NO LOAD

TRIAL 3



13.2KW, 0.8 PF LOAD

TRIAL 1

← 50 ms / DIV.

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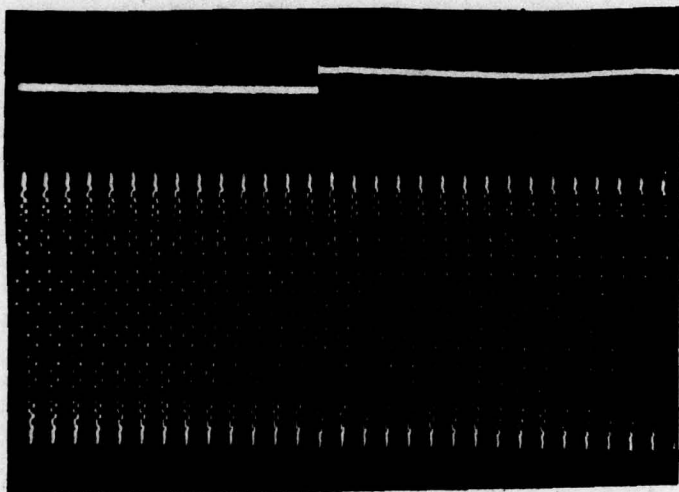
TITLE

PREPARED

DATE

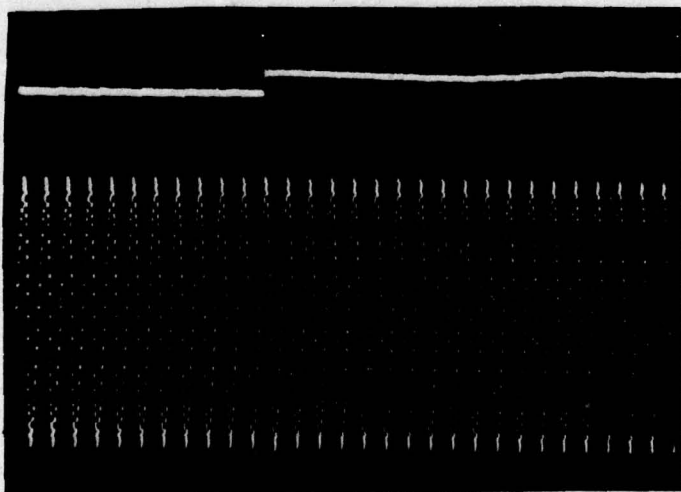
CORRY 5/6/79
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APPROVED



13.2 KW, 0.8 PF LOAD

TRIAL 2



13.2 KW, 0.8 PF LOAD

TRIAL 3

↔ 50MS/DIV.

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		CHECKED		
		APPROVED		

INPUT VOLTAGE TRANSIENTS

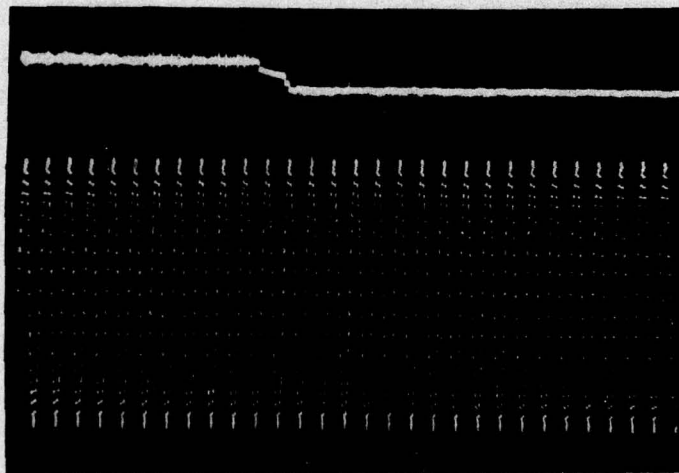
60HZ, THREE PHASE

-15% STEP CHANGE

INITIAL INPUT VOLTAGE $V_{in} = 340 \text{ VAC}$

STEP DECREASE VOLTAGE = -51 VAC

INPUT VOLTAGE AFTER TRANSIENT = 289 VAC



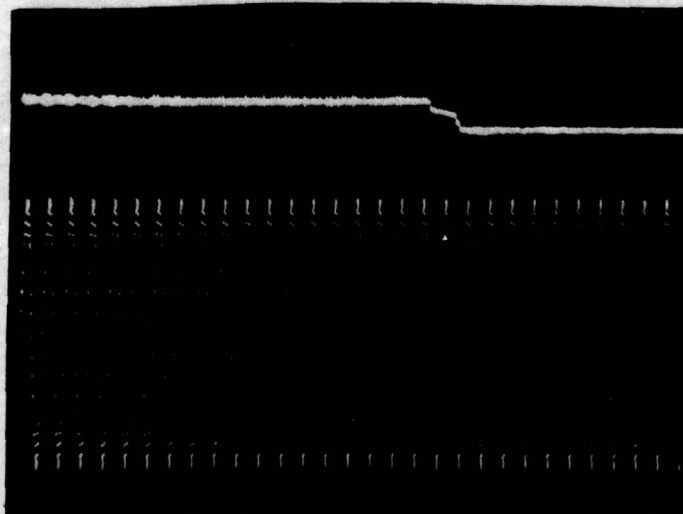
UPPER TRACE - INPUT VOLTAGE V_{in}
↓ 100 V / DIV.

LOWER TRACE - FREQUENCY
CONVERTER OUTPUT

VOLTAGE V_o
↔ 50 MS / DIV.

NO LOAD

TRIAL 1



NO LOAD

TRIAL 2

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TITLE

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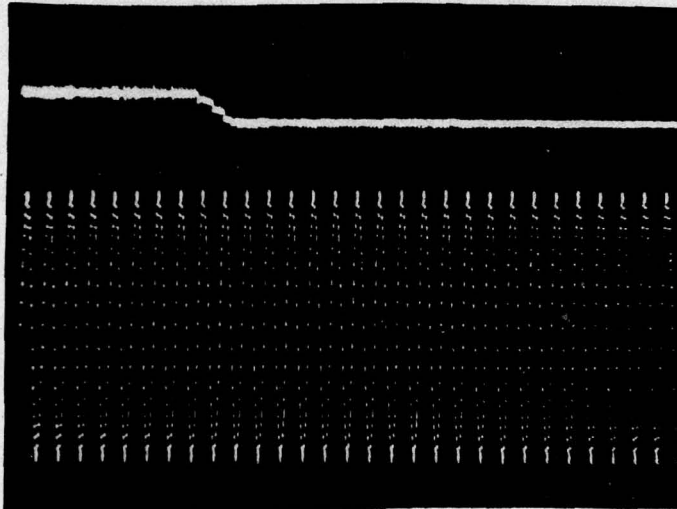
CORRY

DATE

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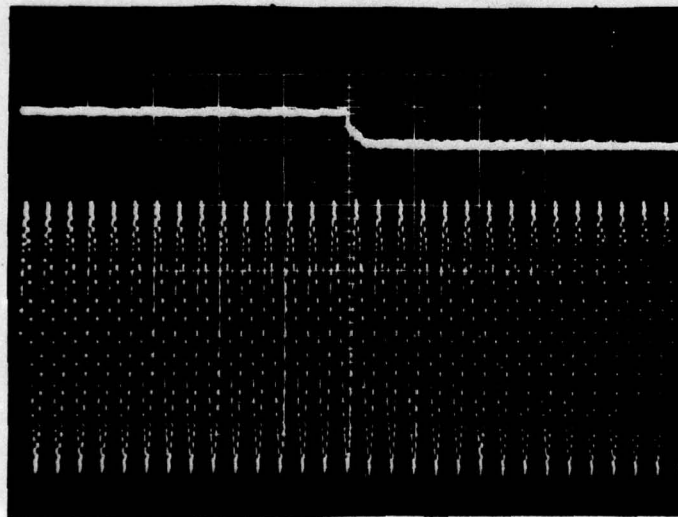
APPROVED



NO LOAD

TRIAL 3

← 50ms/DIV.



13.2KW, 0.8PF LOAD

TRIAL 1

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TITLE

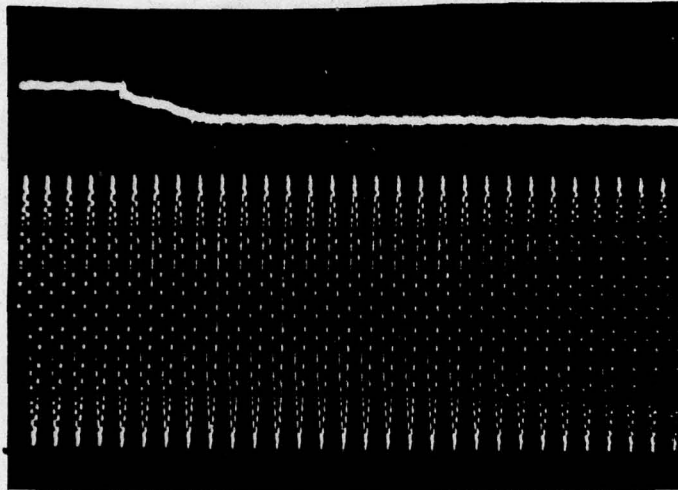
PREPARED

CORRY 5/6/74

DATE

CHECKED

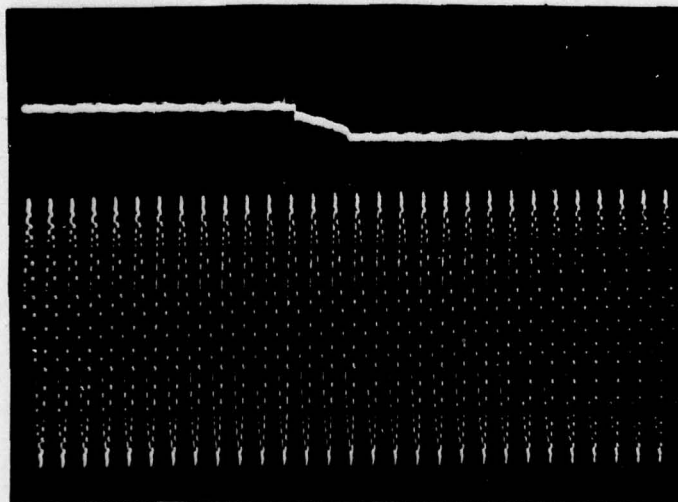
APPROVED



13.2KW, 0.8PF LOAD

TRIAL 2

← 50 MS / DIV.



13.2KW, 0.8PF LOAD

TRIAL 3

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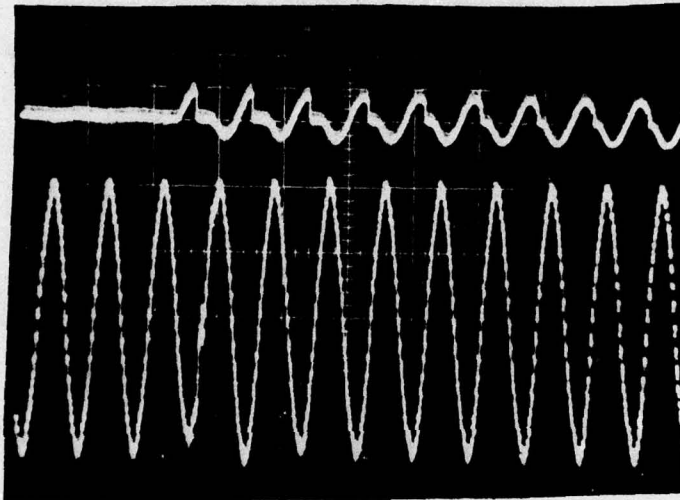
CHECKED

APPROVED

60 HZ, THREE PHASE TRANSIENT TESTS

LOAD TRANSIENTS

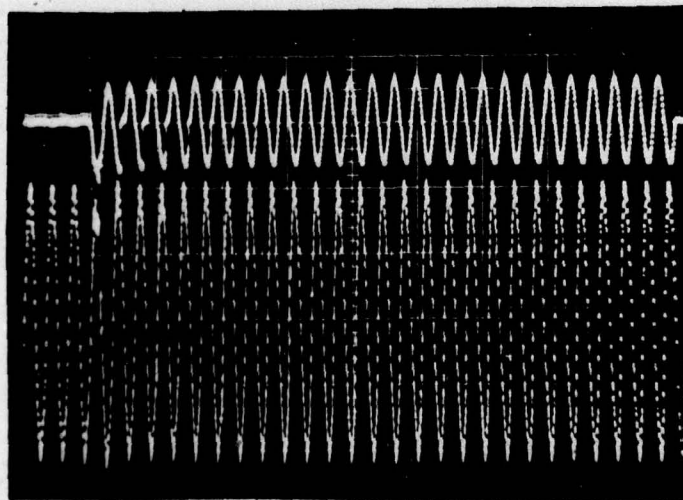
NO LOAD TO 13.2 KW
0.8 PF LOAD



LOAD CURRENT
↓ 100A/DIV.

LINE-TO-NEUTRAL
OUTPUT VOLTAGE V_0
← 20 MS/DIV.

TRIAL 1

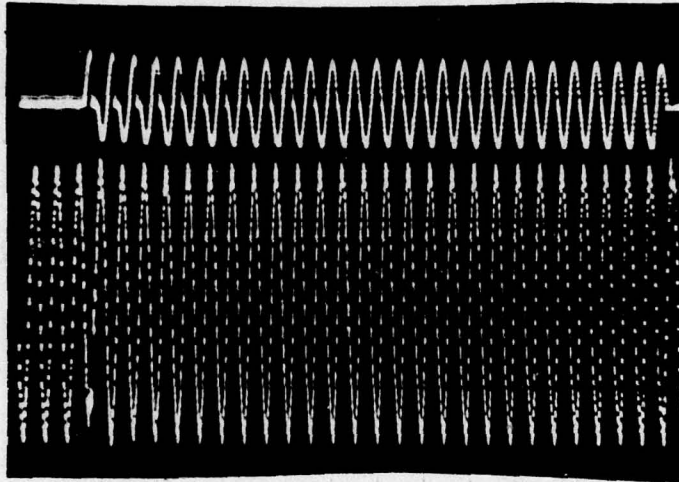


TRIAL 2

← 50 MS/DIV.

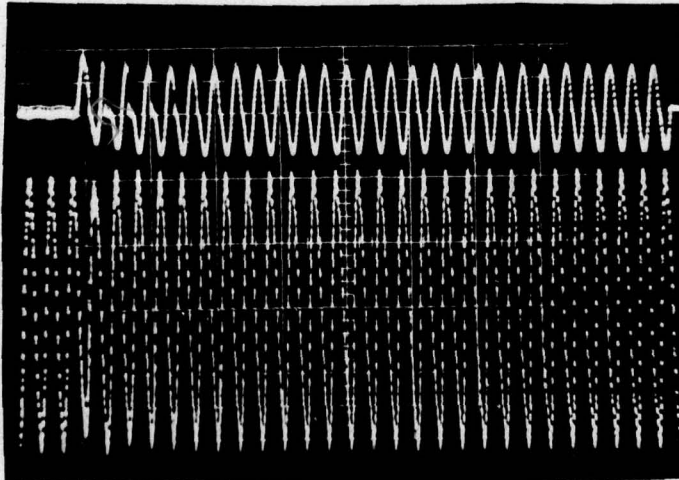
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TITLE			PREPARED	DATE		
			CORRY 5/6/74			
			CHECKED			
			APPROVED			



TRIAL 3

→ 50 ms / DIV.



TRIAL 4

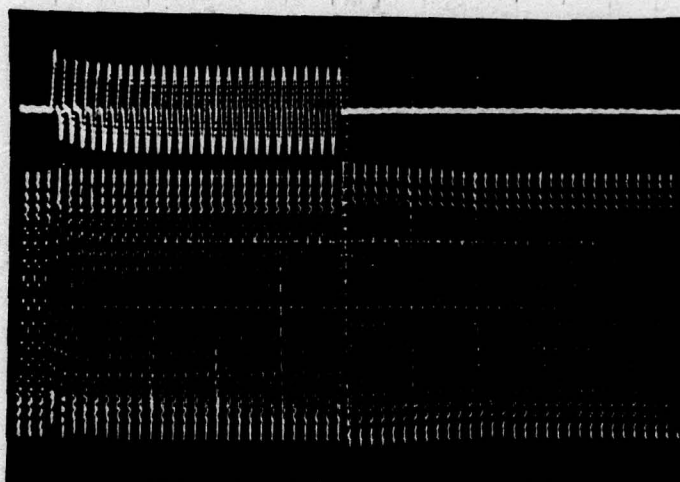
DISTRIBUTION:

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	CORRY		5/6/7	
	CHECKED			
		APPROVED		

60 HZ, THREE PHASE TRANSIENT TESTS

LOAD TRANSIENTS

13.2 KW, 0.8 PF LOAD
TO NO LOAD

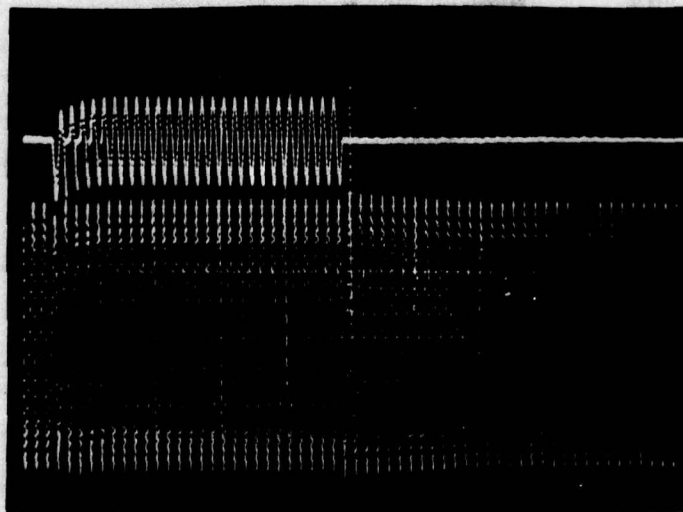


LOAD CURRENT
↑ 100A / DIV.

LINE-TO-NEUTRAL OUTPUT
V₀

↔ 50MS / DIV.

TRIAL 1



TRIAL 2

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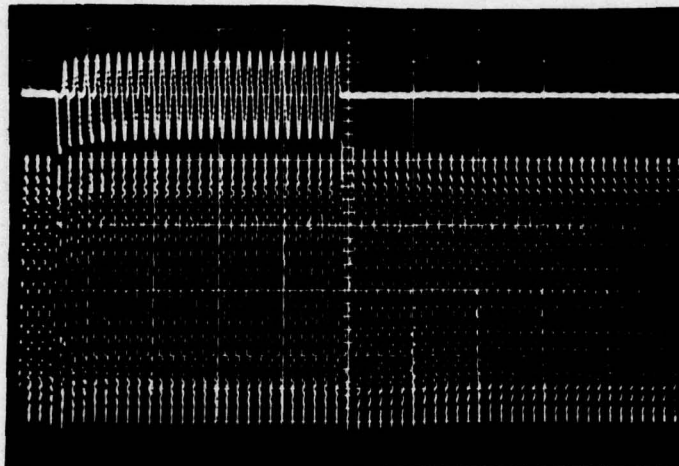
PREPARED

DATE

CORRY 5/6/74

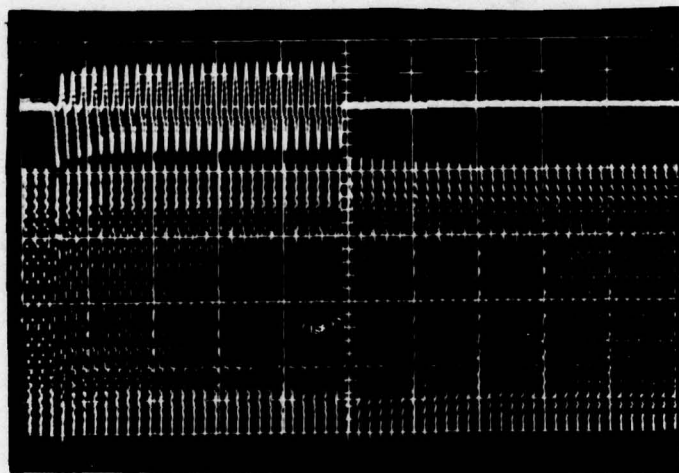
CHECKED

APPROVED

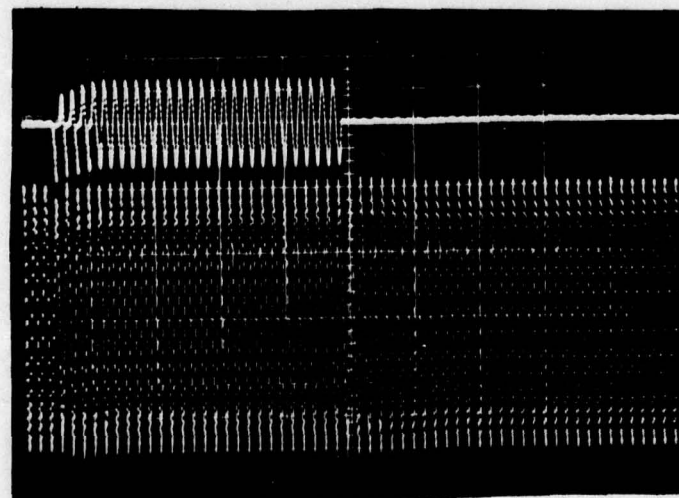


TRIAL 3

← 50 ms/DIV



TRIAL 4



TRIAL 5

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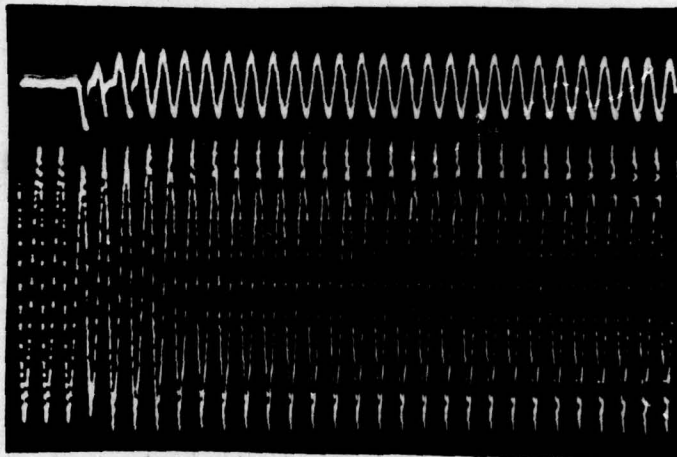
CHECKED

APPROVED

60 HZ, THREE PHASE TRANSIENT TESTS

LOAD TRANSIENTS

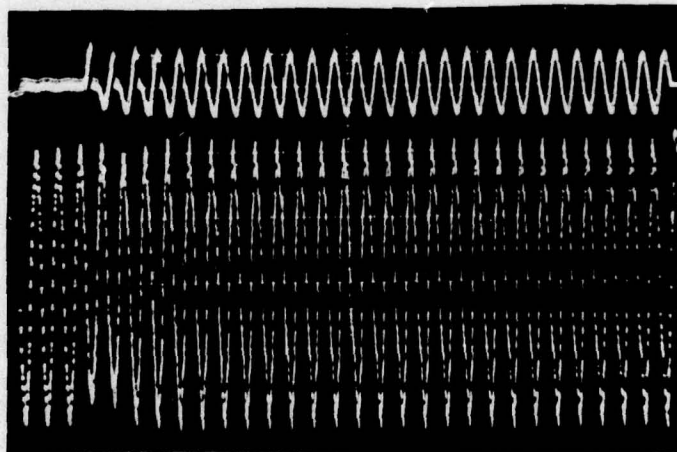
NO LOAD TO
TWO P.U., 0.4 PF.



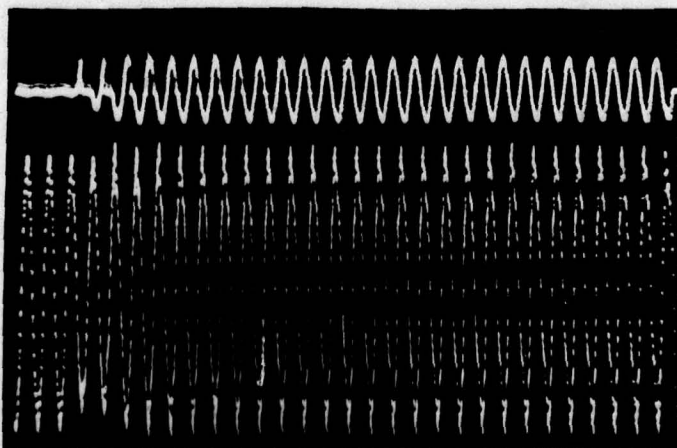
LOAD CURRENT
↑ 200 A / DIV.

LINE-TO-NEUTRAL
OUTPUT VOLTAGE V_o
↔ 20 MS / DIV.

TRIAL 1



TRIAL 2



TRIAL 3

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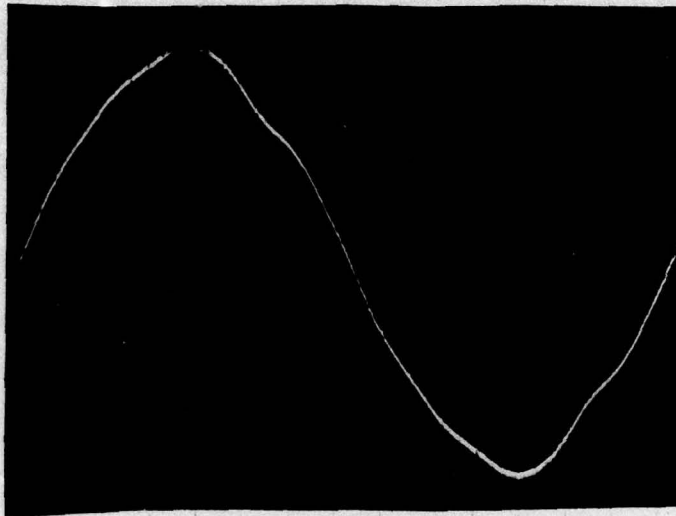
PREPARED

CORY 5/8/74

DATE

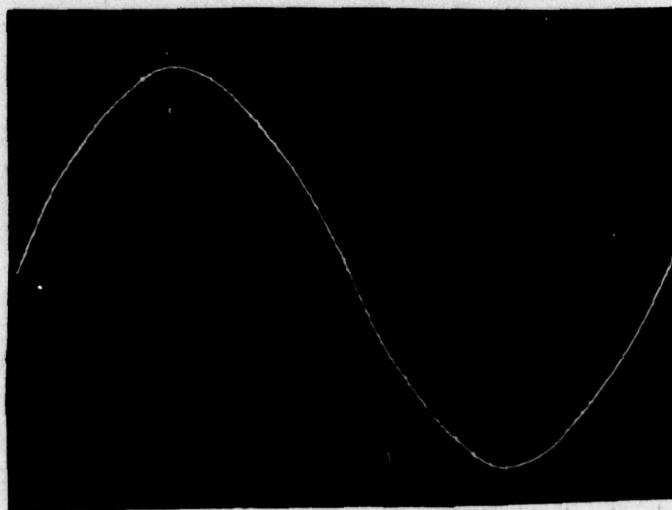
CHECKED

APPROVED

400 HZ, SINGLE PHASE, TWO WIRE LOAD TESTSOUTPUT VOLTAGE V_o NO LOAD

120.02 Vrms *

THD = 3.4%

8.8 kW, 0.8 PF
11 kVA LOAD

120 Vrms *

THD = 2.65%

(REGULATION LOOP OPEN - MANUAL CONTROL)

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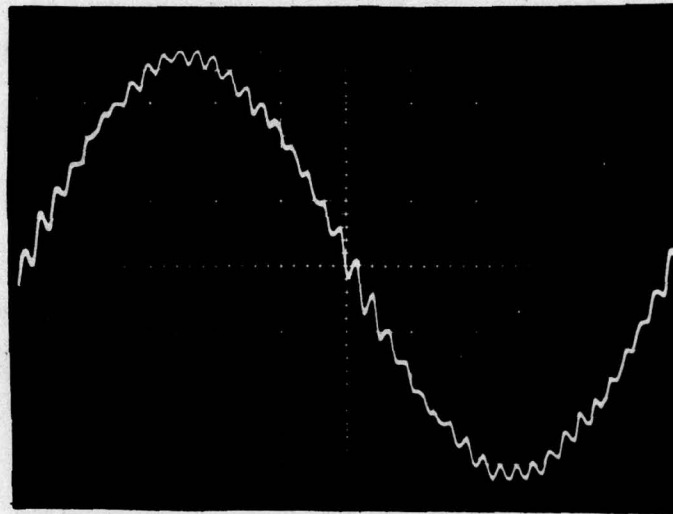
PREPARED CORRY 5/8/7

CHECKED

APPROVED

60HZ, SINGLE PHASE, TWO WIRE LOAD TESTS

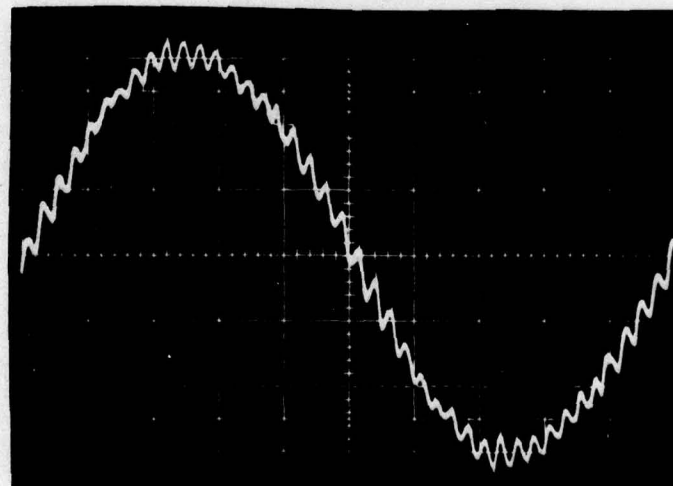
OUTPUT VOLTAGE V_o



NO LOAD

120 Vrms*

THD = 4.7%



8.8KW, 0.8 PF
11KVA LOAD

120 Vrms*

THD = 5.6%

(REGULATION LOOP OPEN - MANUAL CONTROL)

DISTRIBUTION:

10 KW FREQUENCY CONVERTER

PARTS LISTS

CDRL ITEM A002

Contract No. DAAK02-72-C-0210

MATERIAL MEMORY TIMING CIRCUIT

[illegible]

MATERIAL R.F. DRIVERS

ITEM	PART NUMBER AND DESCRIPTION	QTY
	DESCRIBE IN DETAIL	
	PART NO., VENDOR CODE, SPECIFICATION, DIMENSION, UNIT, TRADE OR BRAND NAME, COLOR, TYPE OF MATERIAL, ETC.	
1	CIRCUIT BOARD RSK 20296-501	6
2	SN 5402N QUAD NOR GATE	18
3	SN 5413N DUAL NAND SCHMITT TRIGGER	6
4	MH 4002A QUAD CORE DRIVER TRANSISTORS	18
5	F625-92-06 CORE, INDIANA GENERAL	36
6	2N 5333 TRANSISTOR PNP	12
7	RESISTOR, 50HM $\pm 3\%$ SW. DALE NH-5	12
8	RESISTOR, 390HM $\pm 5\%$ 1W.	12
9	ZENER DIODE, UZ740 40VOLT	6
10	CAPACITOR, MYLAR 0.015MFD 100VDC	6
11	CAPACITOR, TANTALUM, 100MFD 10VDC	6
12	DIODE, 1N4448	72
13	HEAT SINK TX 0506-B 1ERC	12
14	CONNECTOR, ELCO P/N 00-6007-044-980-002	6
15	T-STRUT VECTOR TS169N	6
16	RETAINER KIT, VECTOR BR 19H	4
17	CASE GUIDE VECTOR BR 19-6-1 3.5"	5
TOTAL		

[illegible]

TOTAL

MATERIAL THYRISTOR R.F. DRIVE ISOLATION CIRCUIT

[illegible]

[illegible]

TOTAL

[illegible]

MATERIAL- MERDC 10 KW ALT. FIELD CONTROL

ITEM	PART NUMBER AND DESCRIPTION		QTY
	DESCRIBE IN DETAIL		
	PART NO., VENDOR CODE, SPECIFICATION, DIMENSION, UNIT, TRADE OR BRAND NAME, COLOR, TYPE OF MATERIAL, ETC.		
1	DIODE - ZENER	1N748	1
2	"	UZ760	1
3		1N3913	1
4		1N4448	9
5		1N4946	4
6	V	1N5418	1
7	TRANSISTOR	2N2219	2
8	"	2N3421	1
9	POWER DARLINGTON	DTS-4065' DELCO	1
10	INTEGRATED CIRCUIT	SN7414N	1
11	"	" SN7402N	1
12	VOLTAGE REGULATOR	LM309K NS	1
13	TIMMER	NE555V SIGNETICS	2
14	VOLTAGE COMPARATOR	LM211H NS	2
15	TRIMPOT -	BOURNS MODEL 3250P-1-202 (2.0K)	1
16	POT. 250- Ω $\frac{1}{2}$ W IRC	RY6LAYSA251A	1
17	POT. 5.0K $\frac{1}{2}$ W IRC	RY6LAYSA502A	1

MATERIAL: MERDC 10KW ALTERNATOR FIELD CONTROL

[illegible]

MATERIAL - ME2DC 10KW ALT. FIELD CONTROL

ITEM	PART NUMBER AND DESCRIPTION			QTY
	DESCRIBE IN DETAIL			
	PART NO., VENDOR CODE, SPECIFICATION, DIMENSION, UNIT, TRADE OR BRAND NAME, COLOR, TYPE OF MATERIAL, ETC.			
34	RESISTOR 1/2 Watt $\pm 5\%$ 7.5K- Ω			1
35	RESISTOR 1 Watt $\pm 5\%$ 2.0K- Ω			1
36	RESISTOR 1 Watt $\pm 5\%$ 3.9K- Ω			2
37	RESISTOR 1 Watt $\pm 5\%$ 56K- Ω			4
38	RESISTOR 1/4 Watt $\pm 1\%$ 536- Ω			1
39			3.01K- Ω	2
40			3.32K- Ω	1
41			5.90K- Ω	1
42	↓	↓	6.04K- Ω	1
43	RESISTOR 5Watt $\pm 3\%$ DALE NH-5 200 Ω			1
44	RESISTOR 25Watt $\pm 3\%$ DALE NH-25 50- Ω)			1
45	CAPACITOR .01 μ f CERAMIC			3
46	CAPACITOR - Mylar .047 μ f			1
47			.22 μ f	1
48			.33 μ f	1
49	↓	↓	1.0 μ f	3
50	CAPACITOR - Tantalum 10 μ f @ 35VDC			1
51	↓	-	100 μ f @ 10VDC	2
52	↓	-	330 μ f @ 6VDC	4
	TOTAL			

MATERIAL - MERDC 10KW ALT. FIELD CONTROL

[illegible]

MATERIAL POWER SWITCH ASSEMBLY

ITEM	PART NUMBER AND DESCRIPTION	QTY	
	DESCRIBE IN DETAIL		
	PART NO., VENDOR CODE, SPECIFICATION, DIMENSION, UNIT, TRADE OR BRAND NAME, COLOR, TYPE OF MATERIAL, ETC.		
1	INTERNATIONAL RECTIFIER 82-2022 THYRISTOR NATIONAL NL-F156E-HC15	22	SCR1 THRU SCR22
2	DIODE INTERNATIONAL RECT. P/N 82-0060	5	D1 THRU D5
3	TRANSISTOR WESTINGHOUSE 1741-1460	4	Q1 THRU Q4
4	TRANSISTOR WESTINGHOUSE 1756-1460	4	Q5 THRU Q10
5	250V 2 DIODE DAICO DP220-KOR	4	D1 THRU D4
6	RESISTOR 0.1 OHM 25W $\pm 2\%$ DALE NH-25	4	
7	RESISTOR 10 OHM 5W $\pm 2\%$ DALE NH-5	4	
8	CAPACITOR 0.1 MFD 50V 50% COR 9A016104-D	10	
9	RESISTOR 20 OHM 25W $\pm 1\%$ DALE NH-25	10	
10	CAPACITOR 20 MFD CORNELL-DUPILIER SCR5-105	1	
11	CAPACITOR 20 MFD SPREAFUE 223P12	3	
12	CAPACITOR 12 MFD 6.3V 28F1104FC	2	
13	CAPACITOR 50 MFD CORNELL-DUPILIER SCR2050	2	
14	CAPACITOR 60 MFD SPREAFUE 330P31	4	
15	DIODE SEMTECH SCDA24F	1	
16	DIODE SEMTECH SCDA4F	2	
17	RESISTOR 1.0 OHM 25W $\pm 3\%$ DALE NH-25	6	
18	TRANSFORMER XT72035-01 180-120V 50/60HZ SEP AUTO TRANSFORMER	1	T1
19	TRANSFORMER XT72034-01 60-400V 210-210V	1	T2
20	TRANSFORMER XT73001 P.C. COMMUTATION BOOST	1	T3
	TOTAL		

MATERIAL POWER SWITCH ASSEMBLY

ITEM	PART NUMBER AND DESCRIPTION	QTY
	DESCRIBE IN DETAIL	
	PART NO., VENDOR CODE, SPECIFICATION, DIMENSION, UNIT, TRADE OR BRAND NAME, COLOR, TYPE OF MATERIAL, ETC.	
	XT72040	
21	TRANSFORMER T+T-COMMUTATION BOOST	1 T4
22	INDUCTOR 7MICROHENRIES	2 L1, L2
23	INDUCTOR 7MICROHENRIES	2 L3, L4
24	INDUCTOR 5MICROHENRIES	1 L5
25	INDUCTOR 5MICROHENRIES	1 L6
26	INDUCTOR 7MICROHENRIES	3 L7, L8, L9
27	INDUCTOR TRIPLE FILTER XL72022-01	1 L10
28	CIRCUIT BREAKER 65AMP. HEINEMANN P3XAM1516 .	1
29	RESISTOR 250 OHM 3% 25W. DIAL NH-25 TYPE B	2
30	WIRE #12 TEFLON FLEXIBLE MIL-W-16974D TYPE B	100 FT.
31	WIRE #14 TEFLON FLEXIBLE MIL-W-16974D TYPE B	50 FT.
32	FAN ROTRON MARK 4 GRILL SERIES 747	4
33	RECTIFIER SENTECH SC3AS6F	1
34	DIODE SENTECH SCDA24F	1
35	ALTERNATOR OUTPUT INDUCTION XL72026	1
36	TERMINAL SEASTROM 5903-4-16	2
37	TERMINAL SEASTROM 5903-6-F	1
38	TERMINAL AMP CAT.NO. 320574	500
	TOTAL	

MATERIAL MERDC - TRANSISTOR PROTECTION CIRCUIT

ITEM	PART NUMBER AND DESCRIPTION			QTY
	DESCRIBE IN DETAIL			
	PART NO., VENDOR CODE, SPECIFICATION, DIMENSION, UNIT, TRADE OR BRAND NAME, COLOR, TYPE OF MATERIAL, ETC.			
1	VOLTAGE COMPARATOR LM311D NS			4
2	INTEGRATED CIRCUIT SN7400N			2
3			SN7404N	1
4			SN74132N	1
5	↓	↓	SN74279N	1
6	DIODE 1N4448			16
7	DIODE SBR1F			2
8	RESISTOR 1/4 Watt ±5% 360-Ω			4
9			470-Ω	4
10			1K-Ω	4
11			1.8K-Ω	4
12			2.2K-Ω	4
13			8.2K-Ω	4
14	↓	↓	10.0K-Ω	1
15	RESISTOR 1/2 Watt ±5% 200-Ω			2
16	TRIMPOT- BOURNS 3250P-1-103 (10K-Ω)			1
17	TRANSFORMER XT72038			2
18	CAPACITOR- SILVER MICA 1000PF			4
19	CAPACITOR- CERAMIC .01μf 100VDC			5
20	CAPACITOR- TANTALUM 6.8μf @ 35VDC			1
	TOTAL			

MATERIAL MERDC - TRANSISTOR PROTECTION CIRCUIT

[illegible]

POWER SWITCH ASSEMBLY
MATERIAL CONTRACT NO. DA462-72-C-0010
MODIFICATION P0003 (SINGLE PHASE INVESTIGATION)

ITEM	PART NUMBER AND DESCRIPTION		QTY
	DESCRIBE IN DETAIL		
	PART NO., VENDOR CODE, SPECIFICATION, DIMENSION, UNIT, TRADE OR BRAND NAME, COLOR, TYPE OF MATERIAL, ETC.		
1	INTERNATIONAL RECTIFIER 82-2022 THYRISTOR OR NATIONAL AL-FLAKE-HS15		22
2	DIODE INTERNATIONAL RECTIFIER 82-0060		2
3	TRANSISTOR WESTGEMME 1781-1460		4
4	TRANSISTOR WESTGEMME 1752-1460		4
5	ZENER DIODE T-ALCO DP2 30-20R		4
6	RESISTOR 0.1 OHM $\pm 3\%$ 25W DALE NH-25		4
7	RESISTOR 10 OHM $\pm 3\%$ 5W DALE NH-5		4
8	CAPACITOR 0.1 MFD WET COO 940161042		10
9	RESISTOR 20 OHM $\pm 1\%$ 25W DALE NH-25		10
10	CAPACITOR 20 MFD CORNELL-CORPILIER SC25405		1
11	CAPACITOR 60 MFD SPRAGUE 232P13		3
12	CAPACITOR 125 MFD E.F. 28F1104 FC		2
13	CAPACITOR 10 MFD SPRAGUE 232P21		4
14	CAPACITOR 20 MFD SPRAGUE 232P12		1
15	CAPACITOR 50 MFD CORNELL-CORPILIER SC22022		2
16	RECTIFIER SEMTECH SC3056F		1
17	DIODE SEMTECH SC304F		2
18	RESISTOR 5 OHM $\pm 3\%$ 25W DALE NH-25		2
19	TRANSFORMER STEP-DOWN XT73026		1
20	TRANSFORMER 60-4V 44 215-215 XT72034-01		1
	TOTAL		

MATERIAL POWER SWITCH ASSEMBLY.

DAK02-72-C-0210 MOD. P.003

[illegible]